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FLIGHT
CENTER**

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**APPENDIX
TO
SPENT STAGE EXPERIMENT
SUPPORT MODULE PROPOSAL**

JUNE 1966

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National Aeronautics and Space Administration



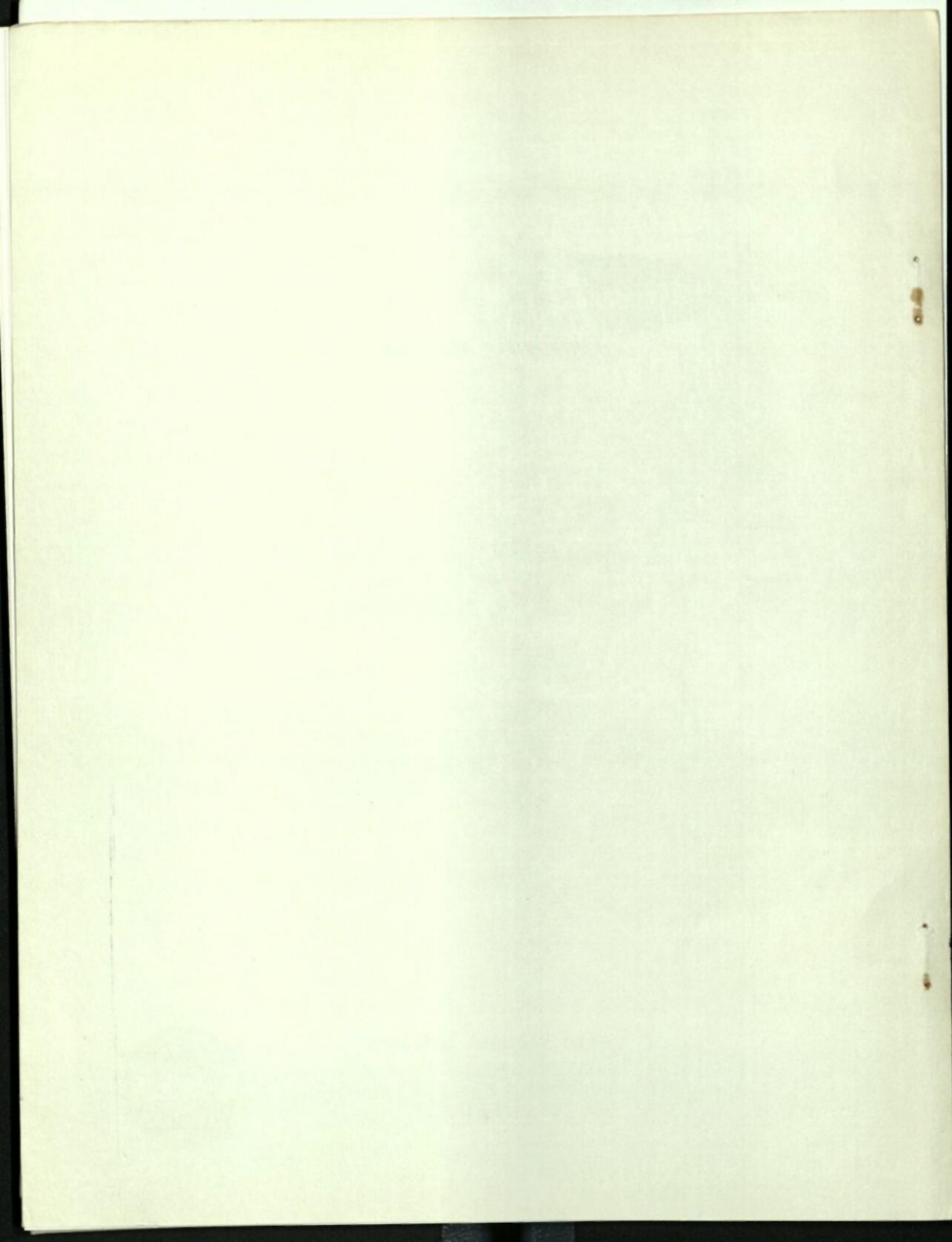
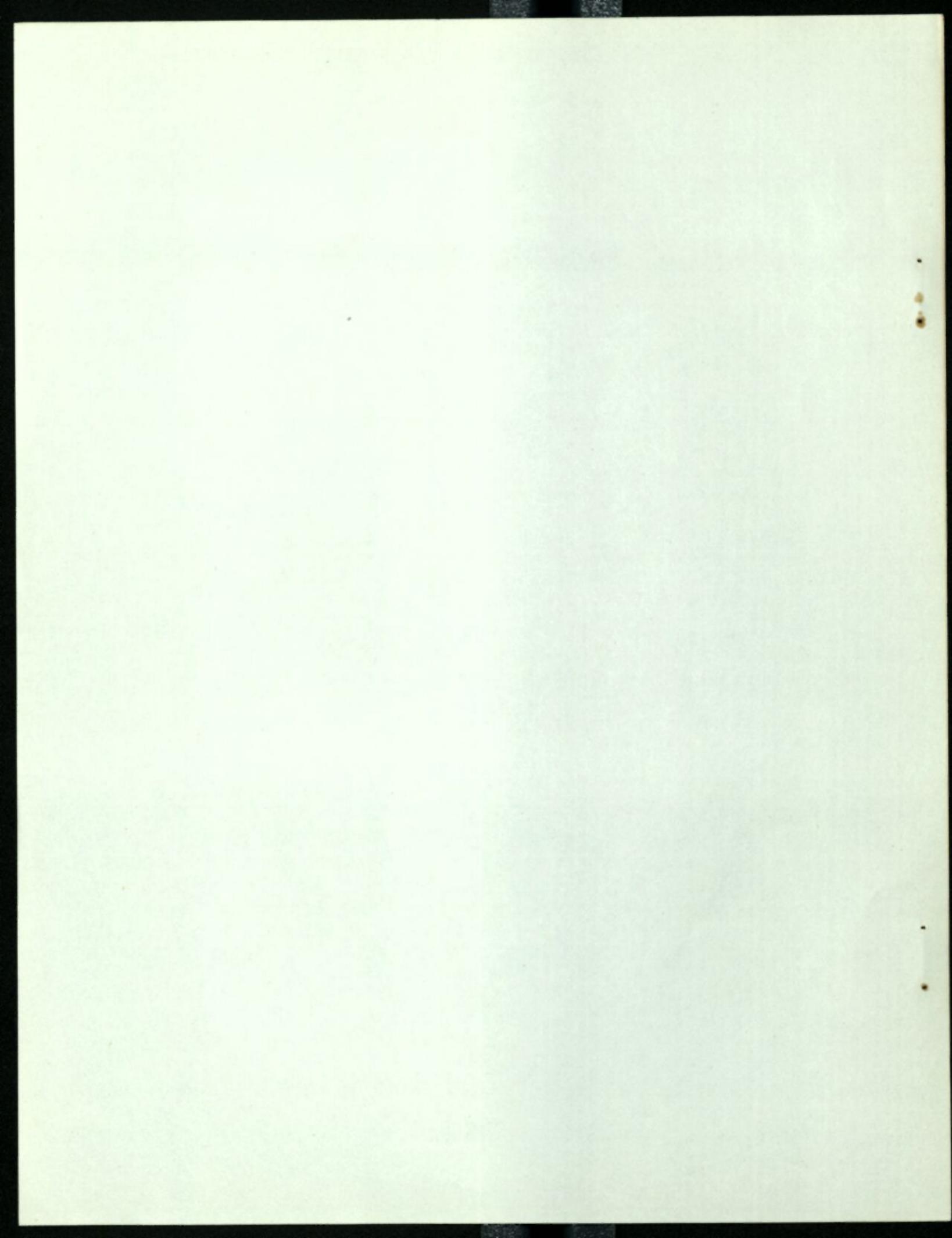


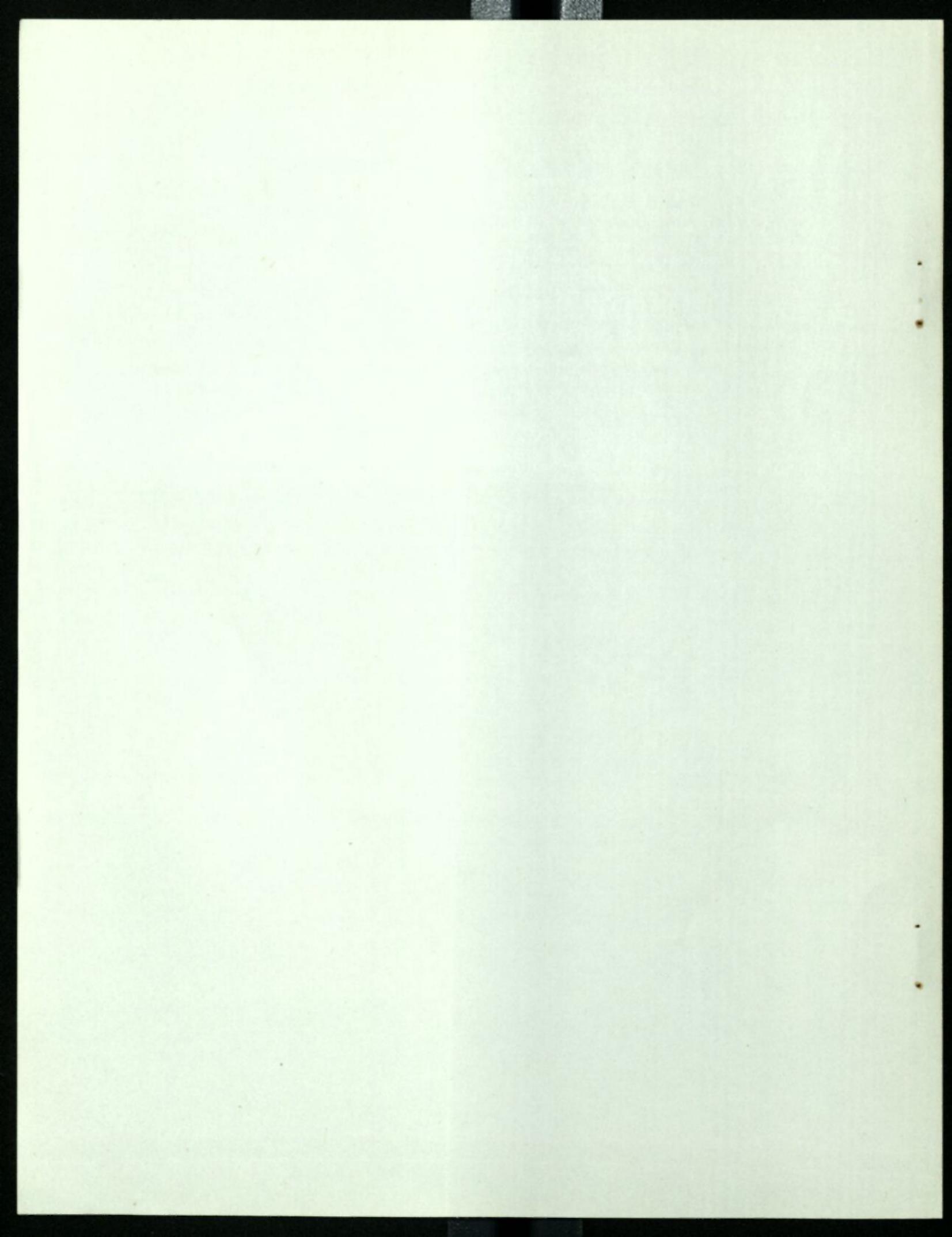
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SECTION 1.0 INTRODUCTION

This Appendix contains supplementary material on selected subjects which complements the MSFC Spent Stage Experiment Support Module (SSESMM) Proposal. Presented are the design ground rules upon which the SSESMM design is based, mission and mission task sequences, structural testing criteria, electrical system schematics, instrumentation equipment list and measurements, maintenance concepts, handling procedures, and crew familiarization requirements.



SECTION 2.0 DESIGN GROUND RULES

2.1 MISSION DESIGN GROUND RULES

2.1.1 General

The Saturn IB Design Ground Rules, revision 2, R-P&VE-VAD-65-101, will apply except where specifically stated otherwise.

a. Mission. - Mission objective of the S-IVB Spent Stage Experiment is to activate the AS-209 S-IVB LH₂ tank into a large pressurized workshop in which astronauts can operate in a shirt-sleeve environment for 4 hours per 16-hour period for 20 days. Minimum change to the Saturn IB launch vehicle and Block II Command Service Module (CSM) and maximum use of developed and qualified subsystems, operational procedures and techniques should be employed whenever possible. A design objective is to retain a readiness and capability on the S-IVB stage and CSM for use on a standard Apollo mission.

(1) Orbit Conditions. - It will be determined if CSM propulsion must be used for orbit circularization to meet the minimum mission duration.

(2) Experiment Definition. - The primary experiment is the passivation and activation of the S-IVB spent stage into a workshop capable of supporting manned activity and the activation of the Spent Stage Experiment Support Module (SSESMM) and associated support systems. A limited number of corollary experiments will be incorporated in the S-IVB Spent Stage Experiment. Experiment equipment will be stowed or installed inside and/or outside the SSESMM during launch into orbit.

(3) Orbital Operation

(a) The transposition and docking maneuver will be accomplished after orbital confirmation and systems checkout.

(b) The planned Apollo docking procedure will be followed which includes fold-out of the spacecraft Lunar Excursion Module (LEM) adapter panels to their normal 45-degree deployment position. It will be determined what the subsequent deployment will be.

(c) The S-IVB stage will stabilize and control its own attitude during the CSM transposing and docking maneuver.

(d) The CSM will provide all stabilization and control required for the spacecraft after the transposing and docking maneuver is completed.

(e) Attitude control of the spacecraft will be provided when required for experiment operation and thermal control of the workshop. It will be determined if operational requirements other than those stated dictate attitude control for the spacecraft for specified periods of operation.

(f) Propulsion capabilities for the CSM for orbital abort will be maintained throughout the entire mission.

(g) After transposing and docking, the CSM will provide all orbital guidance and earth communication.

(h) Service Module (SM) propellant loading will be in accordance with mission requirements.

(i) Preparation for activation of the workshop will be made after the transposing and docking maneuver and normal inflight checkout have been accomplished.

(j) All equipment required for S-IVB LH₂ tank habitation and experiment utilization will be carried external to the S-IVB LH₂ tank at launch and assembled manually in orbit.

(k) LH₂ tank will be vented prior to astronaut egress from the air lock.

(l) The S-IVB LH₂ tank will be made ready for occupancy by astronaut removal and storage of the LH₂ tank dome hatch, followed by attachment of a stowed flexible pressure sealing boot between the aft end of the air lock and the LH₂ tank dome hatch mounting surface.

(m) LH₂ tank passivation functions will be telemetered via the Instrument Unit (IU) for ground monitoring.

(n) The LH₂ interior tank wall will have a protective coating to inhibit burning of insulation if the tank wall is penetrated by a micrometeoroid.

(o) Titanium spheres located within the LH₂ tank will either be removed or protective covers will be installed.

b. Configuration. - The Saturn IB spent stage experiment launch vehicle will consist of an operational Saturn IB launch vehicle and air lock unit. The Saturn IB launch vehicle is composed of the S-IB stage, S-IVB stage, and IU. The first Saturn IB launch vehicle utilized will be AS-209. Modifications to the Saturn and Apollo hardware will be held to a minimum. Modification to AS-209 which could prevent the accomplishment of its primary mission as an Apollo backup will not be permitted. Existing or off-the-shelf hardware will be used to minimize cost, schedule, and development problems.

S-IVB/IU subsystems which represent a potential hazard to the astronaut will be modified to provide a method(s) of passivation.

Add-on type S-IVB subsystem passivation modifications will be installed at Kennedy Space Center (KSC).

Subsystems to be investigated for passivation should include, but not be restricted to, the following: Electrical System, Hydraulic System, Stored Gases, Ordnance System, and Propellant.

c. Interface Requirements. - MSFC will control the following interfaces in addition to the Saturn IB launch vehicle interfaces: Air lock to CSM, Air lock to S-IVB Stage, Air lock to IU, Air lock to SLA, Air lock to the Launch Complex, and Air lock to the Government Furnished Support Equipment.

All interfaces will be controlled in accordance with the Interface Control Documents (ICD's) in the Apollo Intercenter Interface Control Document Log (1A01) and the Saturn Interface Control Document Log (IS01).

2.1.2 Experiments

a. Experiment Integration. - MSFC will integrate experiments and develop interface specifications.

b. Weight. - The maximum weight of corollary experiments and associated equipment will not exceed 1,000 pounds.

2.1.3 Launch Facilities

The Saturn IB Spent Stage Experiment launch vehicle will be capable of being launched from Launch Complexes (LC) 34 and 37B.

2.2 S-IB STAGE DESIGN GROUND RULES

Configuration of the S-IB stage for the Saturn IB Orbital Workshop launch vehicle will be identical to the S-IB stage for the operational Saturn IB launch vehicle.

2.3 S-IVB STAGE DESIGN GROUND RULES

2.3.1 General

a. Configuration. - The S-IVB Orbital Workshop is an operational S-IVB/IB stage, with minor modifications to support the spent stage experiment.

b. Interface Requirements

(1) Interface Tooling. - The air lock flexible bellows adapter interface tooling (master mating gauge) will be manufactured by the S-IVB stage contractor.

2.3.2 Structure (Propellant Containers)

a. The LH₂ tank forward dome access opening will be enlarged to a 43-inch diameter.

b. Provisions will be made for the storage of the LH₂ tank forward access dome hatch.

c. A hand valve will be provided in the LH₂ tank forward dome hatch, or in the near vicinity, for manually venting hydrogen gas which is liberated from the LH₂ tank insulation.

d. The LH₂ tank forward dome will have provisions to mate and make a pressure tight connection with the flexible bellows adapter.

e. One hundred holes will be drilled and tapped at the intersections of the waffle pattern grids in the LH₂ tank for the purpose of mounting equipment and experiments. Work will be accomplished in accordance with MSFC SK10-8270.

f. An atmosphere circulation blower system will be required within the LH₂ tank.

2.3.3 Propulsion System (Propellant Evacuation)

a. Venting of the LH₂ tank will be accomplished by the nonpropulsive vent system.

b. Method (s) to be employed to evacuate residual and flight performance reserve LOX will be determined.

c. Existing controls will be modified to accomplish evacuating and/or venting of propellants.

2.3.4 Environmental Control System

The environmental control system which is located on the air lock support structure will provide atmosphere supply to the workshop.

2.4 SSESMD DESIGN GROUND RULES

2.4.1 General

The SSESMD is defined as an independent air lock unit which interconnects the CSM and the S-IVB LH₂ tank and is mounted at the

LEM attach points in the LEM adapter. The SSESM will include docking capability with the CSM and will provide environmental control system, electrical power, and life support to the S-IVB spent stage for the entire mission.

The air lock and docking structure will not be connected to or transmit loads to the S-IVB stage hydrogen tank forward dome during powered flight of the launch vehicle.

a. Configuration. - The SSESM will include an air lock, docking structure, environmental control system, electrical power system, and support equipment, as defined below. It will also include the support structure for these systems, expendables, and experiment stowage. The air lock will have the capability for independent and integrated operation with the CSM and S-IVB Workshop.

b. Interface Requirements

(1) Interface Tooling. - Manned Spacecraft Center (MSC) and/or the spacecraft contractor will provide the air lock/ space-craft interface tooling. The S-IVB stage contractor will provide the air lock/S-IVB adapter interface tooling.

(2) Field Splice Connecting Hardware. - MSFC will supply the connecting hardware for all air lock unit field splices. The interface hardware will be specified and documented in vehicle assembly documentation by the S-IB stage contractor. The hardware will be delivered to Cape Kennedy in compliance with the vehicle assembly schedule for AS-209.

c. Alignment. - Air lock unit to S-IVB forward bulkhead alignment is not critical as the design of the flexible adapter will allow for minor misalignment. Internal alignment of the air lock unit components will be controlled by an MSFC drawing "to be released." This drawing will govern pertinent design documentation but will not be used for manufacturing, procurement of hardware, inspection of manufactured items or assembly.

d. Reliability. - The reliability goal for the SSESM has not been established.

e. Weights. - The maximum weight of the SSESMM and corollary experiments is 10,996 pounds. The control weight is presently established as 9,000 pounds without the carry-on experiments. These weights are preliminary and will be revised.

2.4.2 Test Requirements

The complete SSESMM test item and subsystem will be functionally tested to verify the capability to meet the structural loads, natural and induced environments expected during mission lifetime. Human factor task tests will be performed to assure man/machine compatibility. Electrical power requirements during ground test operations will be provided from an external source.

2.4.3 Flight Mechanics

a. Natural Environments. - Design of the SSESMM will be based on applicable natural (space) environmental conditions, as given in NASA reports TMX-53273 and NASA TMX-53023.

b. Induced Environments. - Design of the SSESMM will be based on applicable induced environmental conditions, as given in MSFC Report IN-P&VE-S-63-1.

2.4.4 Structure

a. General. - The operational air lock will provide minimum environment perturbation on the CSM, micrometeorite protection as great as CSM, even lighting distribution, local voice communications, and operational sensing equipment to all systems required for the operations of the workshop. The docking structure will make maximum use of existing CSM/LEM design and components. The air lock will be capable of accommodating two suited astronauts, and a locking through cycle will normally be done for two astronauts. The air lock will allow for astronaut suit donning and doffing.

b. Emergency Facilities. - The air lock will provide for emergency occupancy by two astronauts independent of the CSM.

c. Factors of Safety. - The following factors of safety are the minimum values to be applied. They are to be used in addition

to consideration of vibration magnification and shock given to surge phenomena, coupling between stages and propulsion system vibrations. Analytical investigations and test results will be used to validate the actual factors of safety of hydraulic and pneumatic systems. Safety factors different from those specified in the guide will require approval by the procuring agency.

(1) General Structure

Manned Vehicle

Yield factor of safety = 1.10
Ultimate factor of safety = 1.40

(2) Hydraulic or Pneumatic Systems

Flexible hose, tubing, ducts, and fittings less than 1 1/2 inches in diameter.

Proof pressure = 2.00 X limit pressure
Burst pressure = 4.00 X limit pressure

Flexible hose, tubing, ducts, and fittings 1 1/2 inches in diameter and greater.

Proof pressure = 1.50 X limit pressure
Burst pressure = 2.50 X limit pressure

Actuating cylinders, valves, filters, switches.

Proof pressure = 1.50 X limit pressure
Burst pressure = 2.50 X limit pressure

Reservoirs

Proof pressure = 1.50 X limit pressure
Yield pressure = 1.10 X limit pressure
Burst pressure = 2.00 X limit pressure

d. Dimensions. - The cylindrical air lock will be nominally 65 inches in diameter and a minimum of 110 inches long (gross length). The length may be greater than 110 inches if necessary.

e. Access. - The air lock will contain three hatches:

Top hatch (Apollo command module exit) identical to LEM docking hatch.

Side hatch (exit to LEM adapter area).

Bottom hatch (entrance to S-IVB stage hydrogen tank) will be 48 inches in diameter. All equipment for the workshop will pass through the air lock.

f. Docking Structure. - The top of the air lock and support structure will include a docking structure compatible with the Block II Apollo spacecraft and similar to the LEM docking adapter. The docking structure will be capable of carrying all loads induced by the SM propulsion system as a result of orbit change maneuvers in addition to docking loads.

g. Adapter (air lock/S-IVB). - Provisions will be made for a pressure-tight connection to the S-IVB LH₂ forward dome mounting surface after removal of the dome cover which provides a pressure environment for passage from the air lock to the hydrogen tank.

h. Equipment Support and Storage. - The air lock support structure will be capable of supporting all experiment and support equipment as well as the air lock. Equipment to be used inside the S-IVB hydrogen tank during operation in orbit will be stowed on the air lock unit during launch.

i. Umbilicals. - Two pressure suit loop umbilicals will be provided in the air lock. Umbilical length will be sufficient to allow the astronaut to move to the S-IVB common bulkhead.

j. Lightning Protection. - The air lock unit will have the capability to receive and discharge lightning without damage to the vehicle. For additional information see Kennedy Space Center policy memorandum dated November 30, 1964.

k. Electrostatic Compatibility. - It will be determined if a positive shorting system is required to make the air lock/docking mechanism and CSM compatible during docking maneuver.

2.4.5 Propulsion System

There is no propulsion system associated with the air lock unit.

2.4.6 Astrionic Systems

a. Electrical System

(1) Battery power will provide a maximum of electrical power with an average of 750 watts for 4 hours/16-hour cycle for Environmental Control System (ECS), housekeeping, scientific purposes, and lighting requirements.

(2) Provisions will be made for electrical and instrumentation support for activities inside the S-IVB LH₂ tank.

(3) General lighting requirements will be determined and provided for the air lock and the S-IVB LH₂ tank.

(4) Necessary electrical controls and displays of critical S-IVB spent stage parameters will be centralized on panels to be located within the air lock.

b. Instrumentation System

(1) Basic instrumentation will allow monitoring of air lock environmental control system and housekeeping during pad checkout, ascent, and orbit. Basic system does not include visual coverage or data storage.

(2) Telemetry will utilize existing IU antenna system.

(3) System checkout and procedures will be compatible with present system.

(4) Vehicle-to-ground voice communication will be by CSM. Local voice communication will be by spacecraft system.

(5) Lighting requirements for television or film cameras will be defined if the requirement exists.

(6) It will be determined if monitoring of experiments is required.

2.4.7 Environmental Control System (ECS)

Flight qualified Gemini, Saturn, or Apollo hardware components will be used whenever expedient. Refurbished flight components are acceptable.

a. Function. - The environmental control system will provide atmosphere supply to the S-IVB LH₂ tank and the air lock.

b. Display. - ECS displays will be located in the air lock and LH₂ tank.

c. Controls. -

(1) ECS controls for the air lock and LH₂ tank will be located in the air lock.

(2) The pressure in the air lock may be reduced to vacuum from the air lock or LH₂ tank with the aft hatch closed.

(3) Dump valves will be provided at the fore, aft, and side hatches of the air lock.

(4) The air lock and LH₂ tank pressures will have the capability of being equalized from the LH₂ tank.

(5) The air lock will have the capability of being pressurized or unpressurized manually.

d. Atmosphere Requirements. - The ECS will be composed of four 20-cubic-foot spheres of metabolic oxygen for pressurization of the LH₂ tank and air lock and one 3.5-cubic-foot LEM sphere for resupply of the Portable Life Support System (PLSS). The ECS will permit:

(1) Two men to work in the LEM adapter, air lock, and S-IVB hydrogen tank areas for an average of 4 hours per 16-hour period for 20 days.

(2) 1.25 charges of the stage hydrogen tank (approximately 10,000 cubic feet) and for 30 pressurizations of the air lock.

(3) Leakage rate will be approximately 30 pounds per day.

(4) Fifteen hours of extravehicular activity by two men, or a total of 30 manhours.

(5) Temperature: $65 \pm 25^{\circ}\text{F}$ with minimal temperature oscillation.

(6) Pressure: 3.5 to 5.5 psia.

(7) Relative humidity: 30-70 percent.

(8) Carbon dioxide: 0.1 psia.

2.4.8 Human Engineering

The human engineering design principles presented in MSFC-STD-267A will be used. Criteria in this document will be used as guidelines.

2.4.9 GSE

a. MSFC will provide all necessary electrical GSE.

b. Maximum use will be made of existing Saturn IB launch complex facilities and equipment.

c. Checkout will be conducted in accordance with MSFC document SR-QUAL-64-13, Space Vehicle Stage Analysis and Checkout Guidelines, dated May 1, 1964.

d. System checkout equipment and procedures will be compatible with present systems. Systems must also conform to safety regulations of KSC operations.

e. No new umbilical plates or swing arms will be permitted.

f. Necessary controls and displays for critical parameters will be provided in the launch complex.

2.4.10 Weight and Balance

Prior to shipment to KSC, measurements will be made to determine weight and 3-axis center of gravity.

2.4.11 Crew Training Requirements

Flight crew training will be provided for the activation of the SSESM, passivation/activation of the S-IVB LH₂ tank and installation, and operation of the corollary experiments.

2.5 INSTRUMENT UNIT DESIGN GROUND RULES

2.5.1 Configuration

Modification of the IU to support the spent stage experiments will be held to an absolute minimum.

2.6 CREW SYSTEM GROUND RULES

The following crew systems criteria reflect astronaut requirements and limitations which have impact on hardware design and mission planning:

a. The normal location of the crew when not engaged in S-IVB Workshop, extravehicular, or experimental tasks will be in the CM.

b. The crew will be periodically rotated in their tasks during the mission.

c. Two crewmen at a time will perform activities outside the CM.

d. Pressure suits will be worn by the astronauts when entering a pressurized area for the first time.

e. The pressure suit umbilical will not be disconnected in a vacuum on the AS-209 mission.

f. Voice communications shall be maintained at all times between the task performers and the CM.

g. One crew member shall remain within the CM at all times except in an emergency.

h. The astronauts will not require a maneuvering unit for activities within the Spacecraft LEM Adapter (SLA). A Portable Life Support System (PLSS) and tethers will be utilized for SLA activities.

i. The crew will maintain two separate compartments at all times as a safety precaution.

j. A 10-minute portable oxygen supply is provided each space-suited astronaut.

k. The normal eating, sleeping, personal hygiene, and other station-keeping tasks will be performed in the CM.

l. After the initial entry to a pressurized compartment, and the compartment is verified operational, subsequent entries to the pressurized compartment may be conducted in shirt sleeves.

m. The Block II Apollo full pressure suit will be utilized.

n. The water-cooled undergarment will be used for astronaut thermal control when the PLSS is required. Three of these will be stored in the air lock.

o. The suit pressure will nominally be 3.5 psi above ambient when the suit is pressurized.

p. The nominal suit inlet temperature will be 50°F.

q. The nominal suit atmosphere will be 100 percent O₂.

r. A thermal outer garment is required for all activities in vacuum.

s. The optimum size access opening for astronaut transfer while wearing the PLSS and thermal outer garment is 38.5 inches.

t. The two PLSS units normally carried in the LEM will be stored in the air lock. A third PLSS is stowed in the CM. The PLSS will be used for emergency operations or as an alternate mode to the suit umbilical.

u. Due to sizing, hygiene, and drying requirements, and to provide the astronaut with immediate access to a space pressure suit, three additional pressure suits will be provided. Two of the suits will be stored in the air lock.

v. Tethers will be available for all activities outside the air lock.

w. Two pressure suit umbilicals, in addition to those provided in the CM, are located in the air lock. The air lock suit umbilicals will reach all parts of the interior LH₂ tank.

x. A habitable environment is provided in the pressurized air lock with the following nominal atmospheric conditions:

- (1) 100 percent O₂
- (2) 5 psia
- (3) 70° F
- (4) 30-50 percent relative humidity

y. The air lock has sufficient volume to accommodate two men, pressure suited and pressurized, and the storage of their equipment. Each man can don and doff the pressure suit, thermal garment, and PLSS in the air lock.

z. The air lock pressure will nominally be 5 psia O₂ upon reaching orbit.

aa. The air lock will be secured to the LH₂ tank bulkhead opening during orbit by the astronauts.

bb. The air lock and LH₂ tank atmospheric pressures may be equalized at any time from the air lock.

cc. The air lock will provide access to the LH₂ tank as well as the SLA.

dd. The manhole cover bolts will be removed by reactionless tools. Conventional tools will be available as backup.

ee. The LH₂ tank is vented prior to crew egress from the CM.

ff. The LH₂ tank will not be pressurized until attachment to air lock..

gg. The LH₂ tank and air lock are at vacuum when the manhole cover is removed.

hh. The LH₂ tank and air lock atmosphere must be monitored whenever astronauts are present. Capability must be provided to monitor atmosphere both from the CM and locally to provide direct readout and redline alarm. The following must be measured constantly for shirt-sleeve operations:

- (1) CO₂ Partial Pressure
- (2) Total Pressure
- (3) Temperature
- (4) Humidity

ii. Vehicle attitude control may be required for thermal control inside the LH₂ tank.

SECTION 3.0 MISSION SEQUENCE

3.1 GENERAL

This section presents a general and detailed sequence for each event currently defined in the design reference mission. In addition, a typical crew time line summary is presented for the first few mission days.

3.2 GENERAL MISSION SEQUENCE

Presented in Figures 3.2-1 through -6 are the initial releases of the S-IVB spent stage experiment design reference mission general sequence for use in analysis and planning. While this sequence is based upon the latest available conceptual design information, it is expected that subsequent design effort will dictate numerous changes to the sequence and provide more data for expanding the sequence to a more detailed level. These changes and additions will be reflected in subsequent releases as necessary to keep the sequence accurate and current during the course of this program.

This design reference mission sequence covers the period from the initiation of launch vehicle countdown through the completion of the 20-day S-IVB spent stage experiment. Data presented herein are limited primarily to gross level vehicle/experiment peculiar sequence with such information as the launch vehicle normal countdown and flight sequences being referenced.

3.3 DETAILED MISSION SEQUENCE

Each event scheduled for days 1, 2, and 20 is sequenced in detail on Figures 3.3-1 through 3.3-26. This information supplements the summary presented in paragraph 3.2. Additional events for days 3 through 19 will be defined as mission plans become better defined.

3.4 CREW SCHEDULE SUMMARY

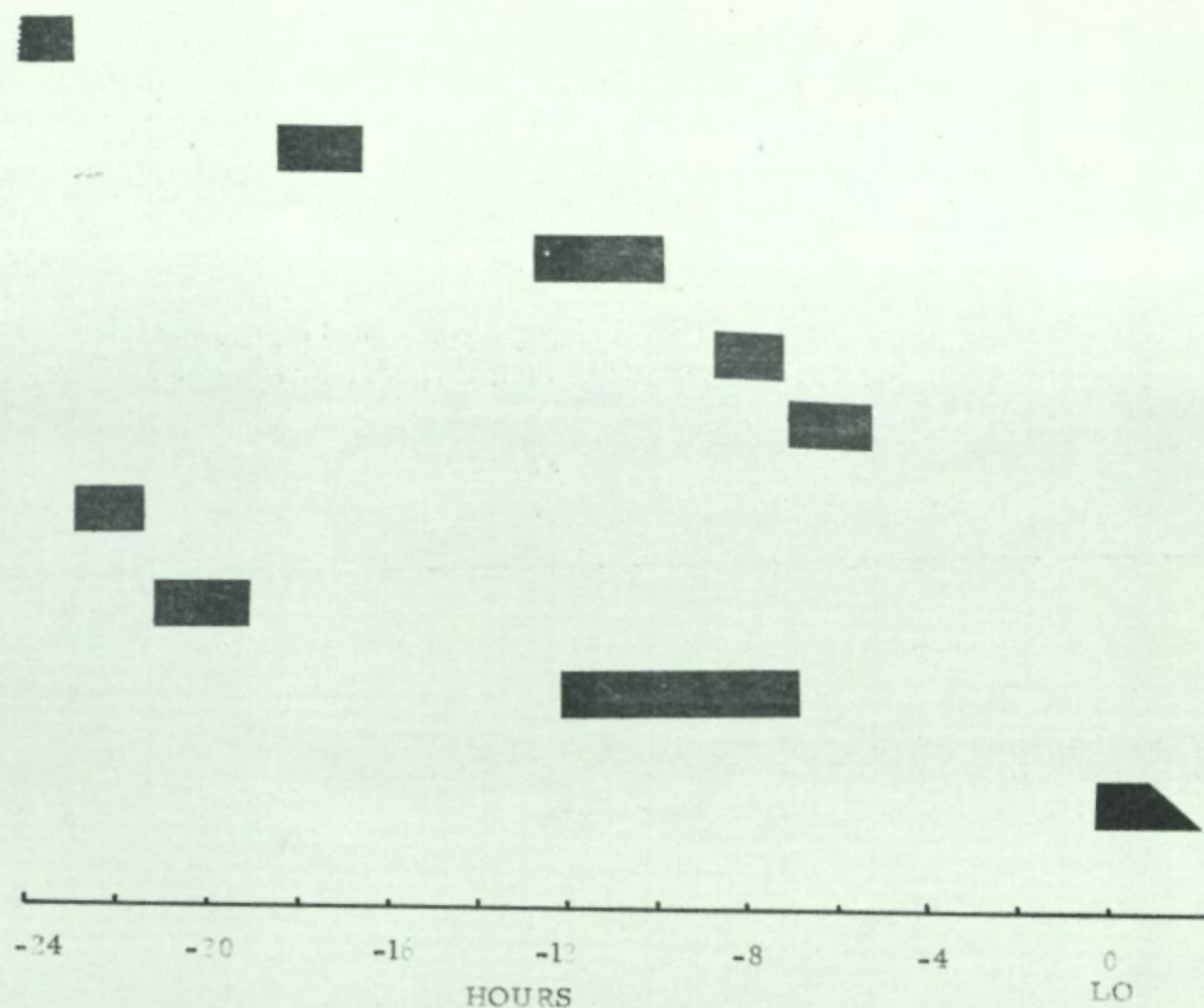
Data are presented in Figures 3.4-1 and 3.4-2 which define a typical crew schedule for each mission day through five. Specific experiments have not been selected; therefore, only gross times were included in the schedule for experiment activity. The following data describe the assumptions and legend:

- a. Astronauts sleep at same time, 7.5 hours/day - divided into two periods of 6 and 1.5 hours nap. Time between sleep varies from 6 and 10 hours.
- b. Two meals and one snack per day - 45 minutes per meal and 30 minutes per snack.
- c. A CSM check every 8 hours, ± 1 hour.
- d. Periodic safety check by each astronaut each 12 hours.
- e. Two personal hygiene periods of 30 minutes each - one period after each sleep.
- f. For each 4-hour period (max) in tank, a period of 12 hours out is required. Two astronauts maximum in tank at one time.

Prelaunch

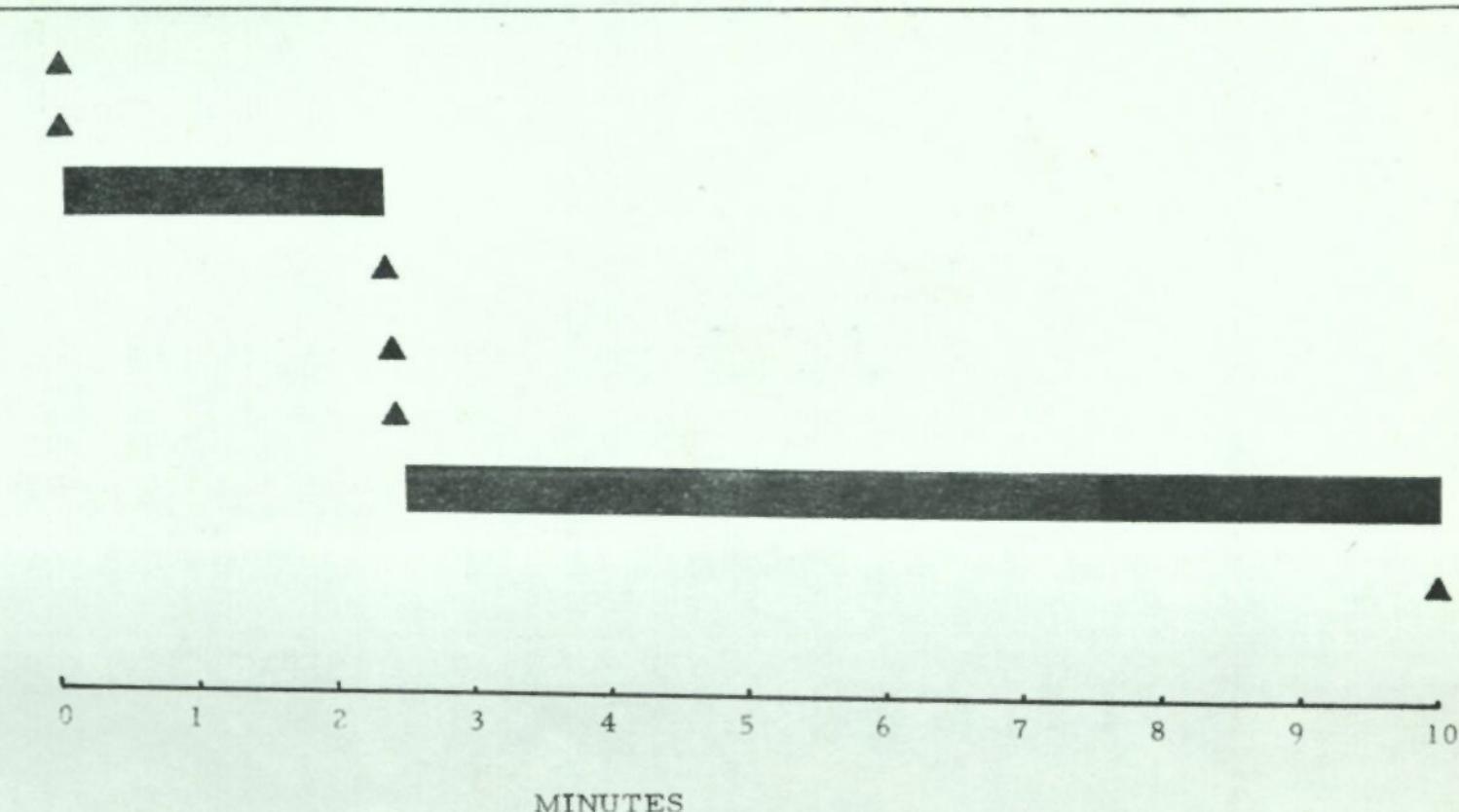
FIGURE 3.2-1. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

1. Complete Manual Equipment Check
2. Install Airlock/Workshop Batteries
3. Checkout Stage Passivation Capability
4. Airlock Purge and Leakcheck
5. Pressurize Airlock
6. Gox Sphere Purge and Leakcheck
7. Gox Sphere Prepressurization (1500 psi)
8. Gox Sphere Pressurization (3000 psi)
9. Airlock/Workshop Internal Power Mode on



NOTE: For a typical detailed Saturn IB countdown sequence
see MSFC drawing 10M30202.

1. S-IB Ignition
2. Liftoff
3. S-IB Boost
4. S-IB Cutoff
5. S-IB/S-IVB Separation
6. S-IVB Ignition
7. S-IVB Boost
8. S-IVB Cutoff

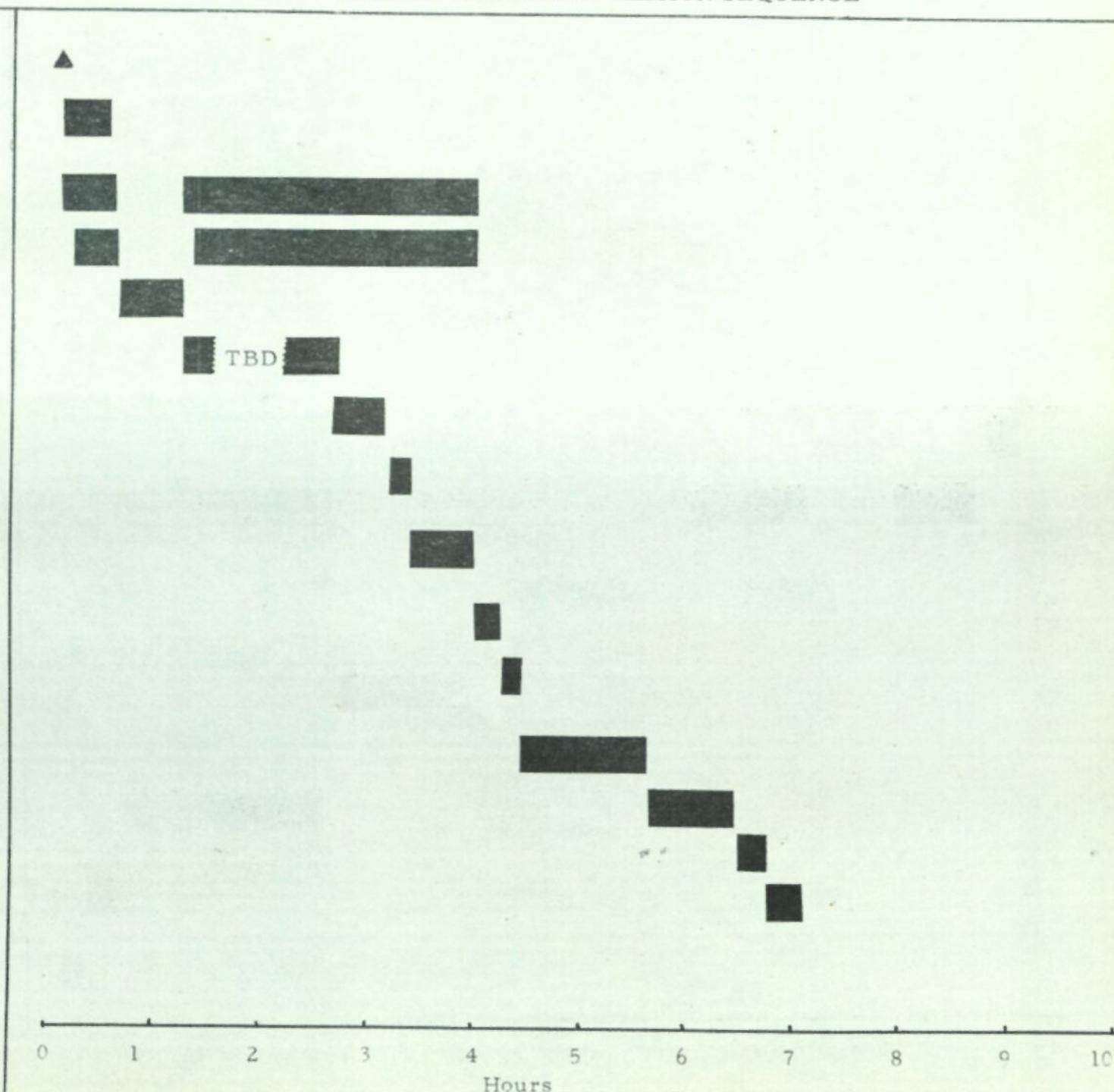


NOTE: For a typical Saturn IB Flight sequence
see MSFC drawing 10M30157.

Day 1

FIGURE 3.2-3. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

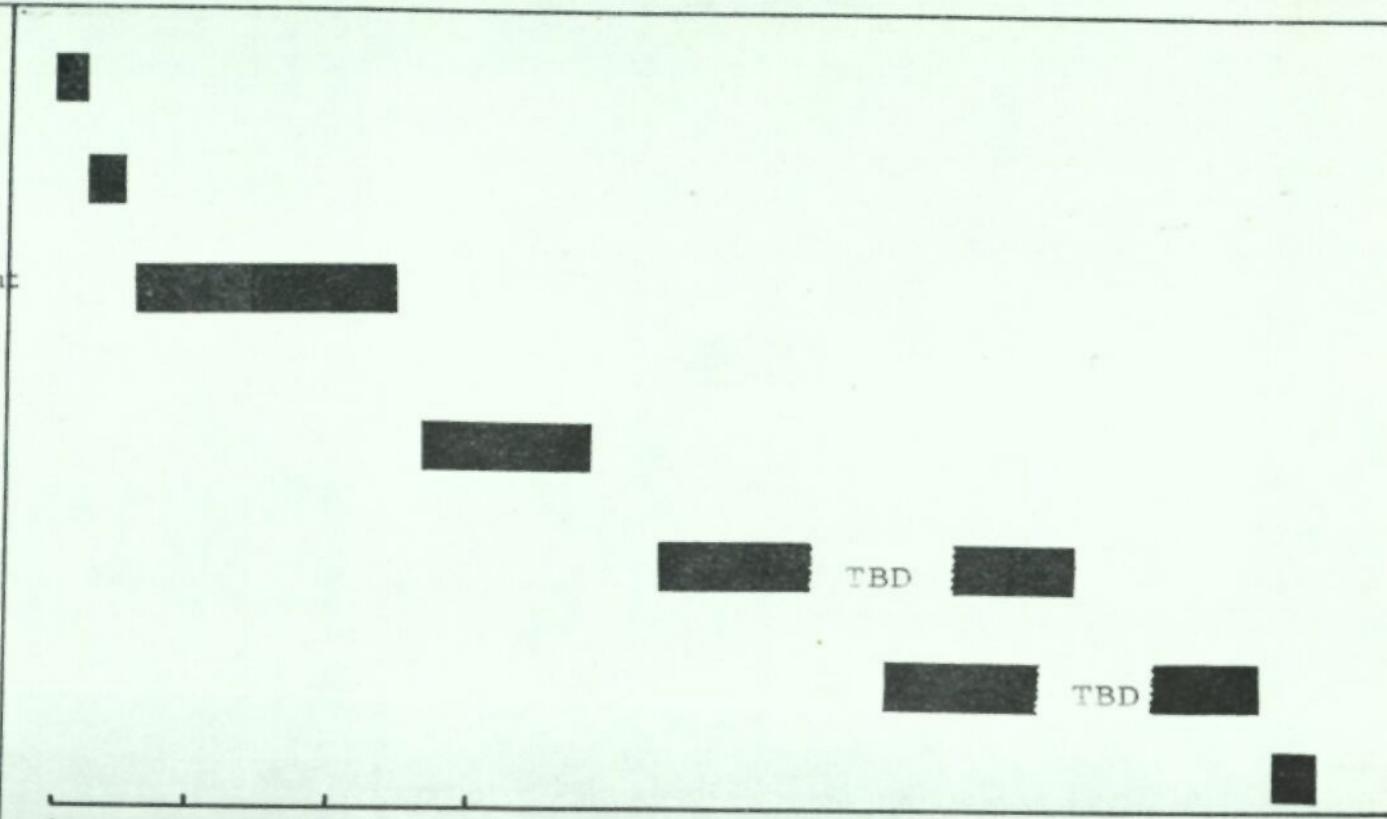
1. S-IVB Engine Cutoff
2. Confirm Orbit Systems Check
3. LH₂ Tank Venting
4. Lox Tank Passivation
5. Separate and Dock
6. CM Experiments
7. Withdraw Docking Probe
8. Enter Airlock and System Check
9. Stage Passivation - Airlock Area
10. Depressurize Airlock
11. Stage Passivation - SLA Area
12. Remove & Store Bulkhead
13. Connect Bellows
14. Pressurize Airlock
15. Return to CM



Day 2

FIGURE 3.2-4. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

1. Enter AL
2. Depress Airlock
3. Transfer and Install Equipment from Airlock Storage to Workshop
4. Transfer and Install Equipment from SLA to Workshop
5. Workshop Experiments in Unpressurized Atmosphere
6. Workshop Pressurization
7. Return to CM

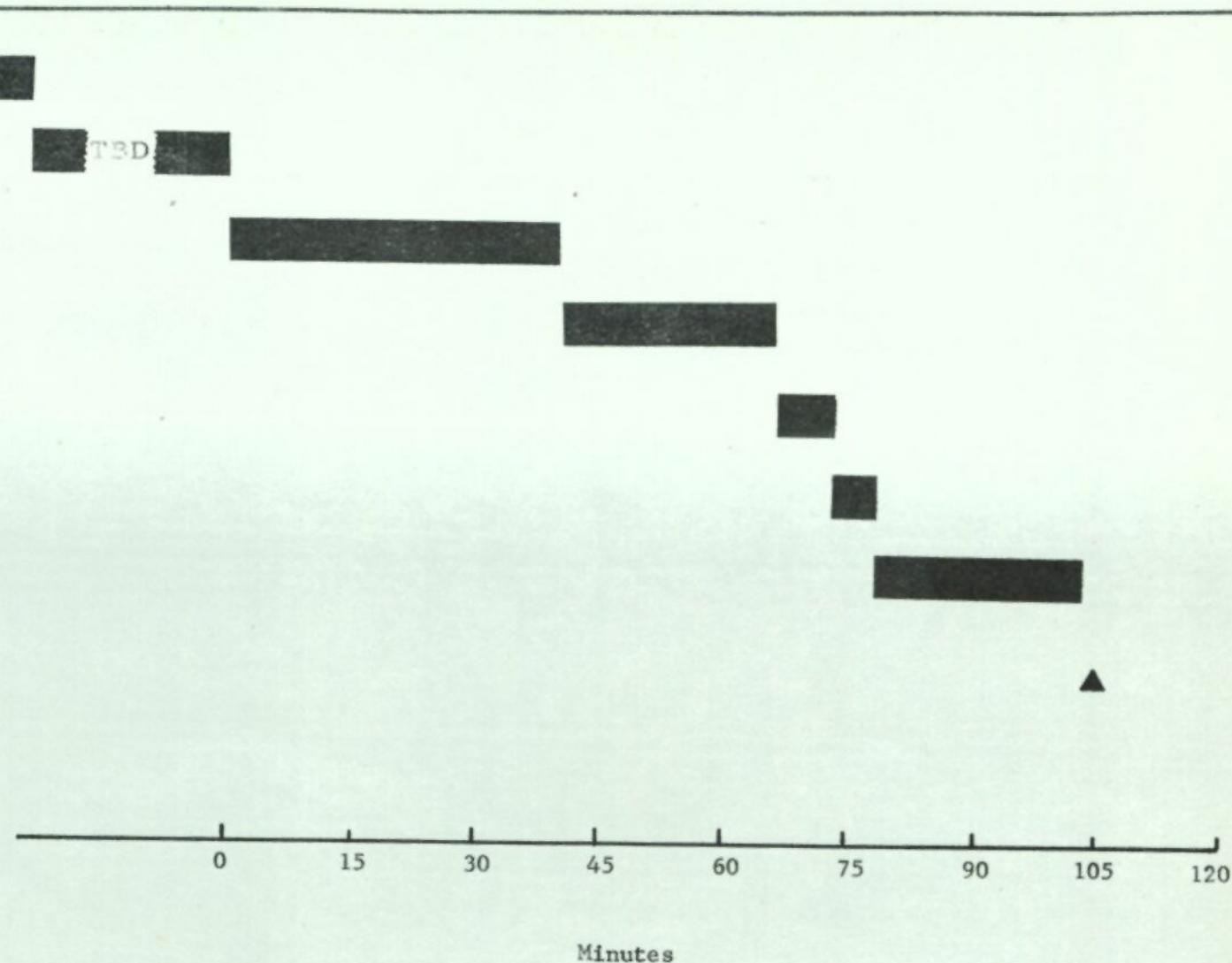


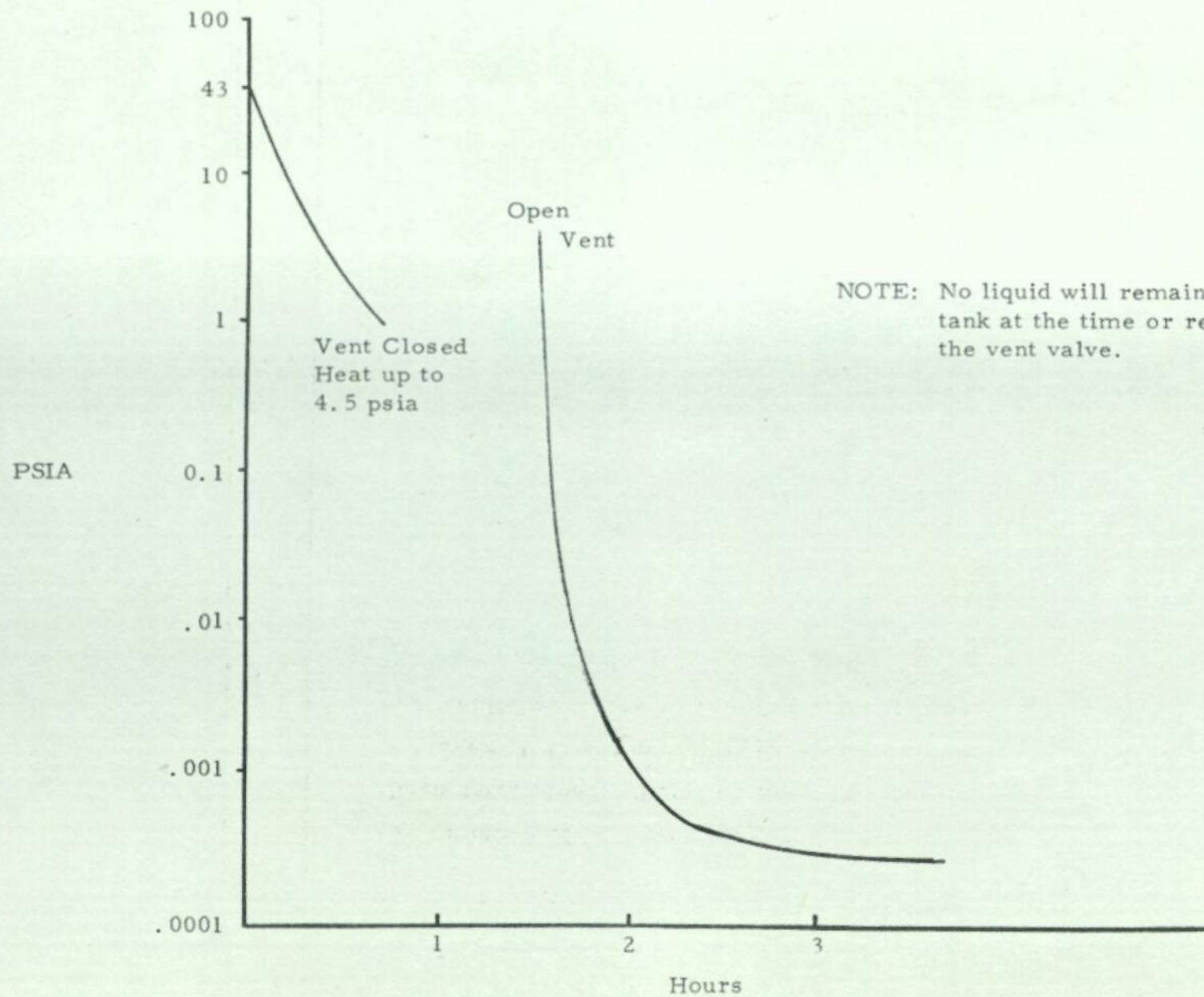
Day 3 thru 19

FIGURE 3.2-5. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

A detailed sequence on Day 3 thru Day 19
will be generated when the detailed list of
approved experiments becomes available.

1. Enter Workshop
2. Complete Workshop Experiment
3. Secure Equipment in Workshop
4. Transfer Experiment Containers to CM
5. Enter CM
6. Install Drogue Assembly
7. Install CM Hatches and System Check
8. Ready Earth Return



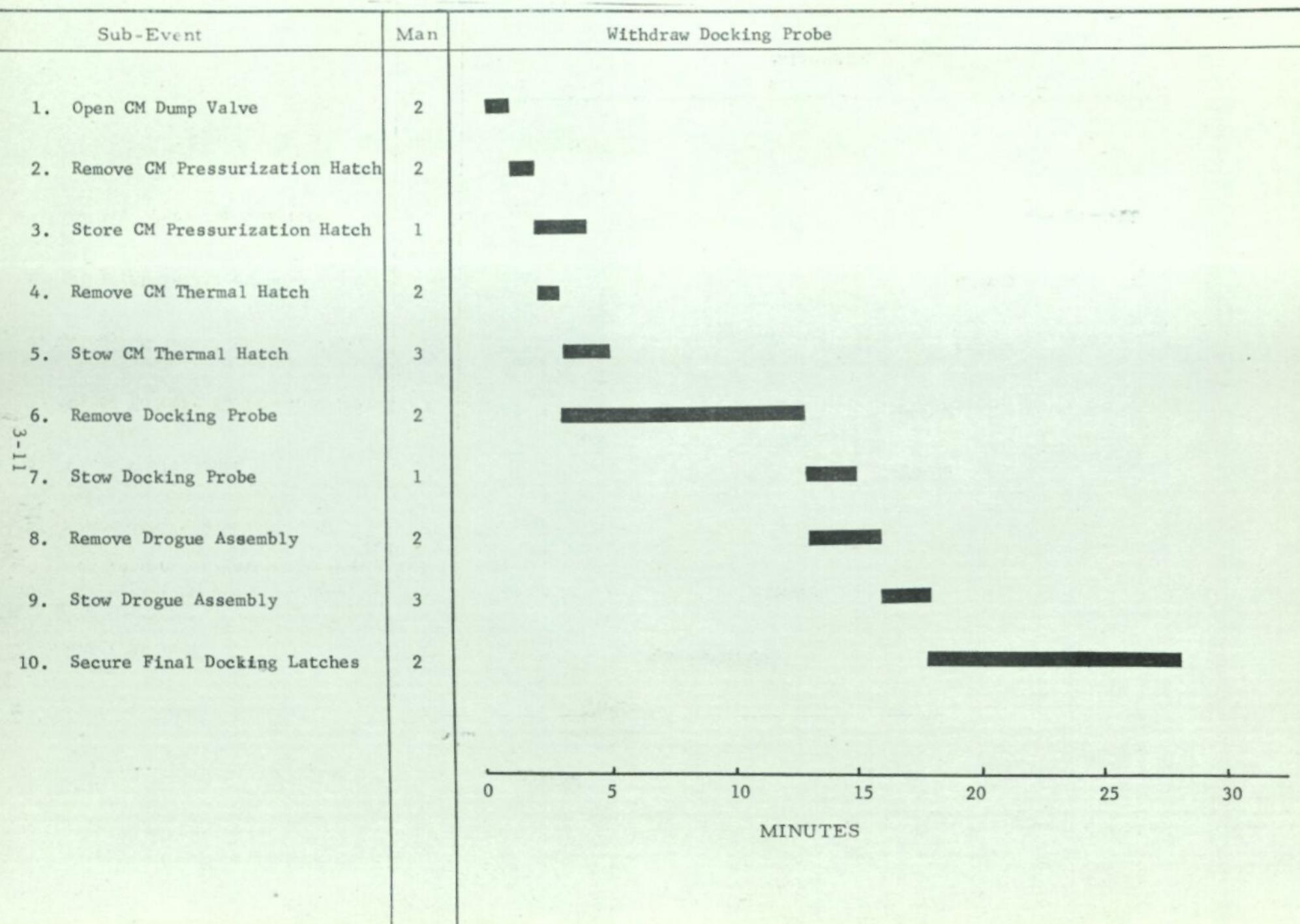
LH₂ Tank Venting

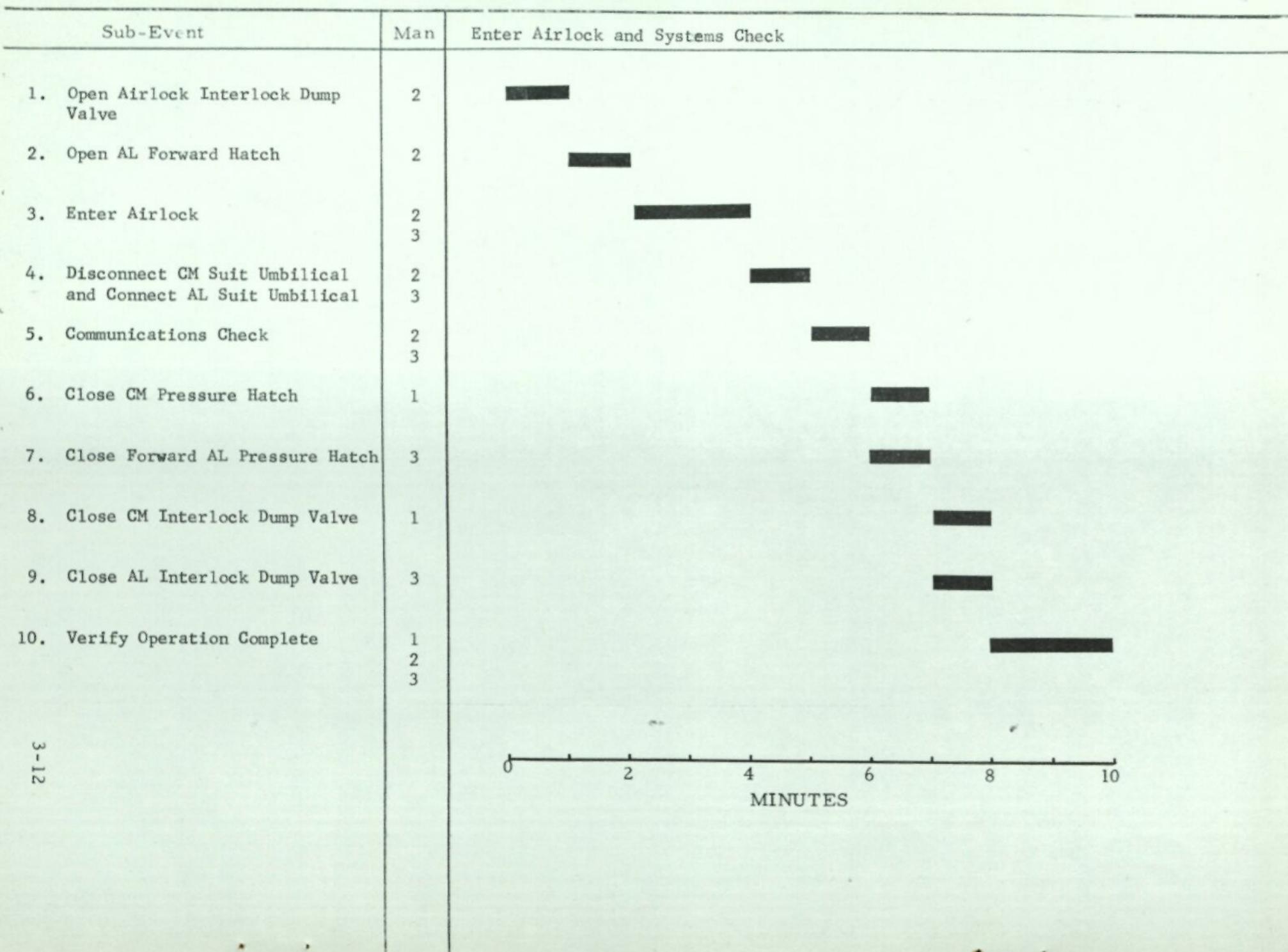
Day 1 Event 4 FIGURE 3.3-2. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

Sub-Event	Man	LOX Tank Venting
		<p>The method of LOX tank passivation has not yet been determined. Based on recent proposals, however, it is assumed that passivation can be accomplished within a three to four hour time.</p>

Day 1 Event 7

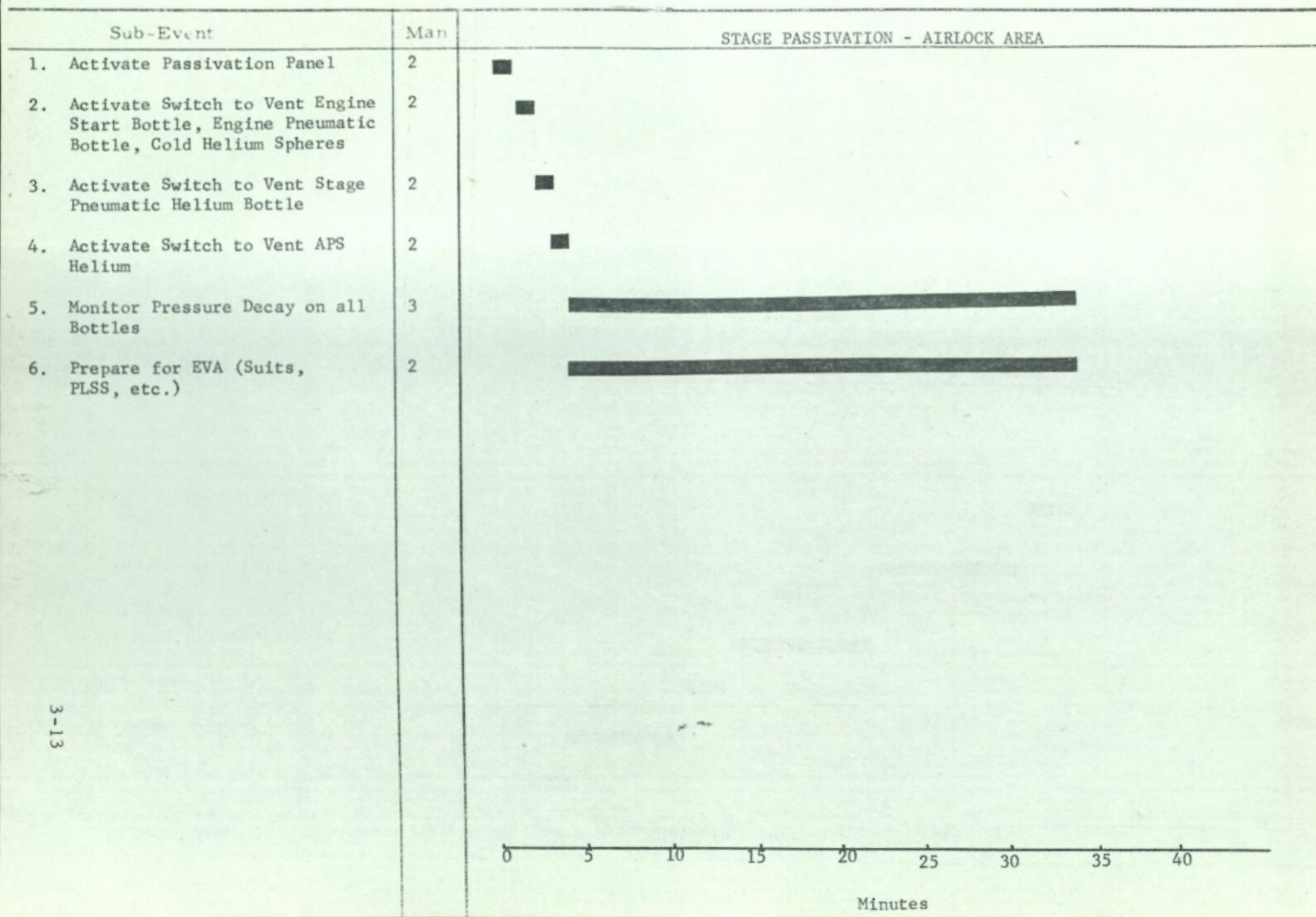
FIGURE 3.3-3. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

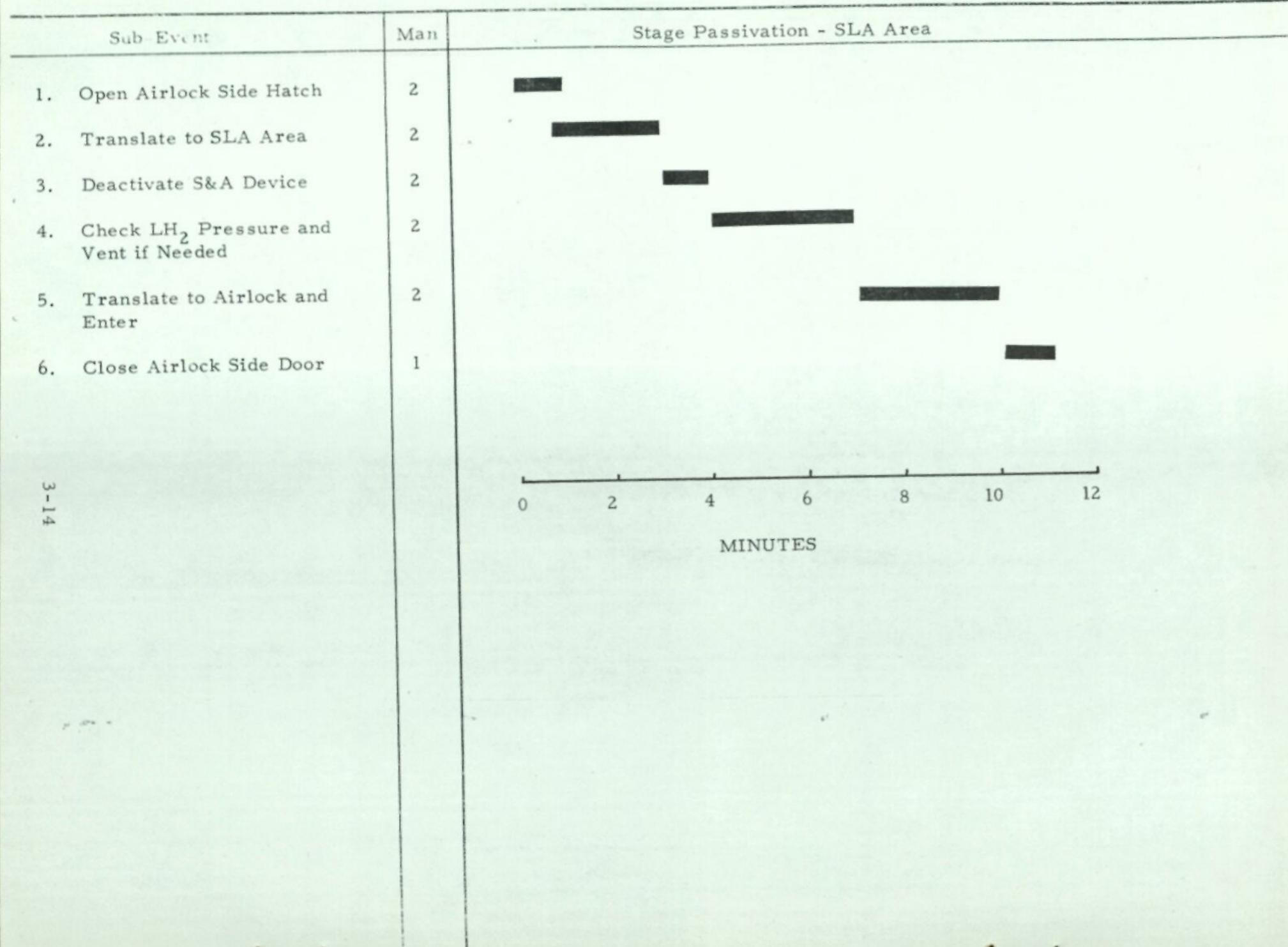




Day 1 Event 9

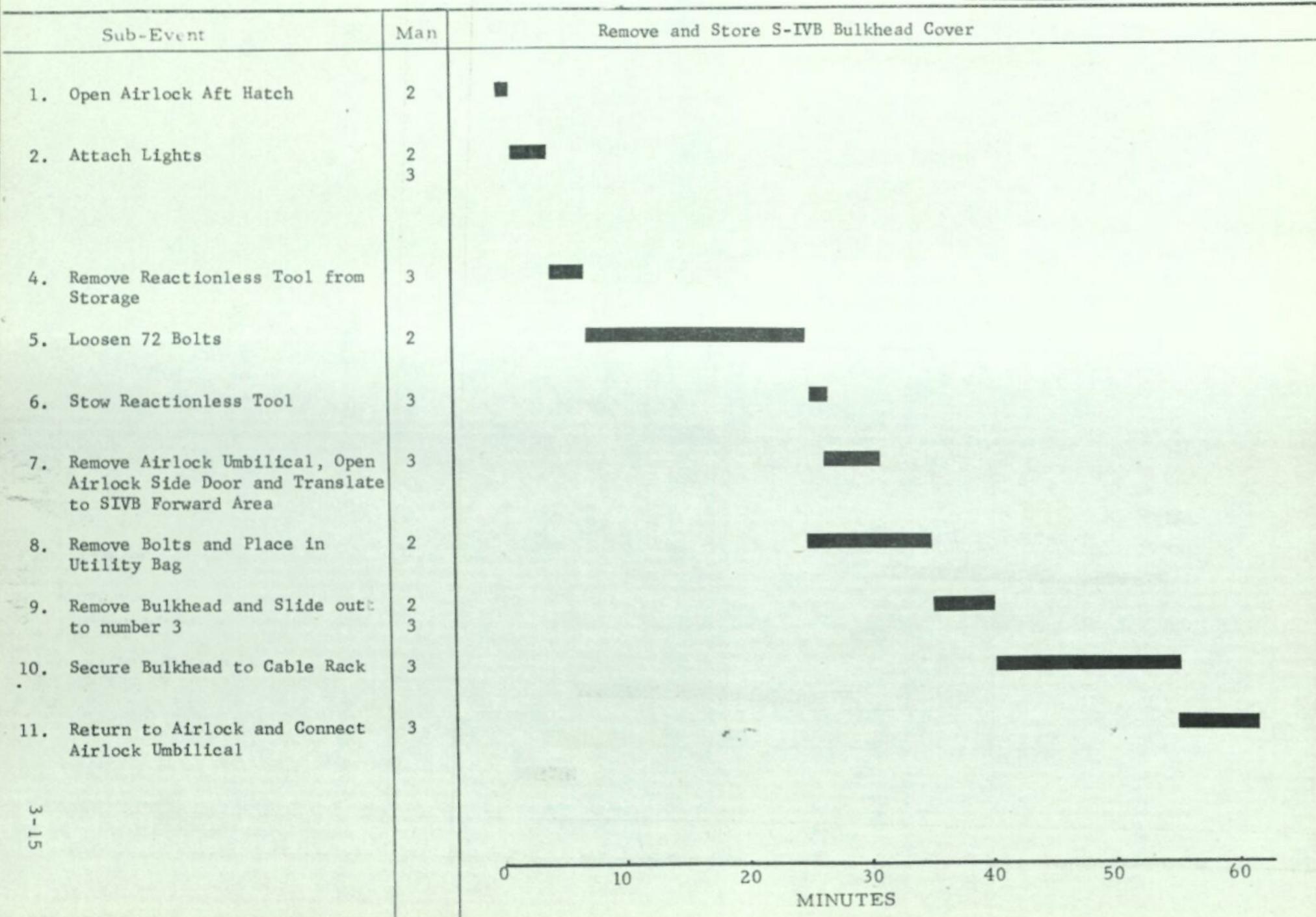
FIGURE 3.3-5. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

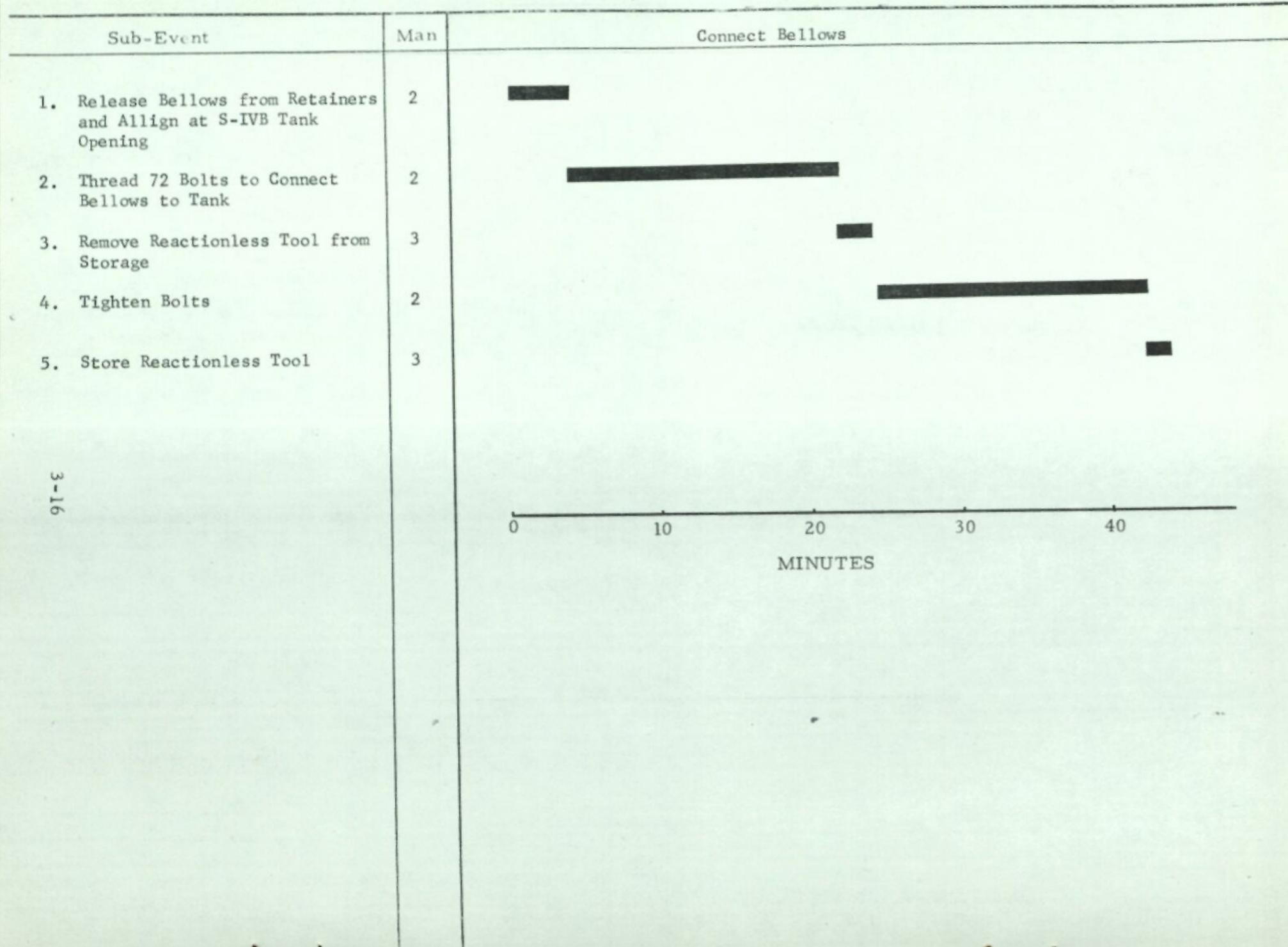




Day 1 Event 12

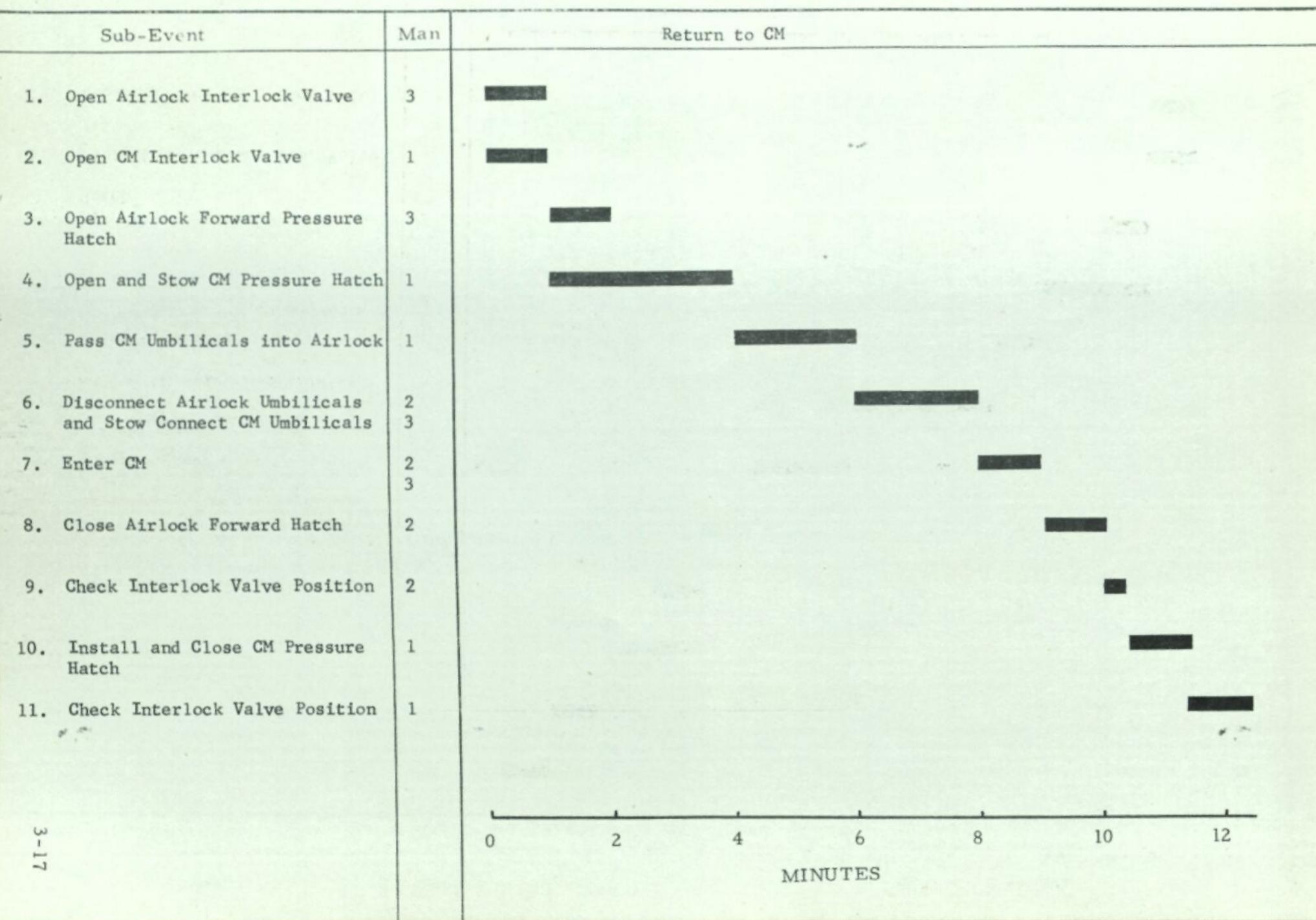
FIGURE 3.3-7. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

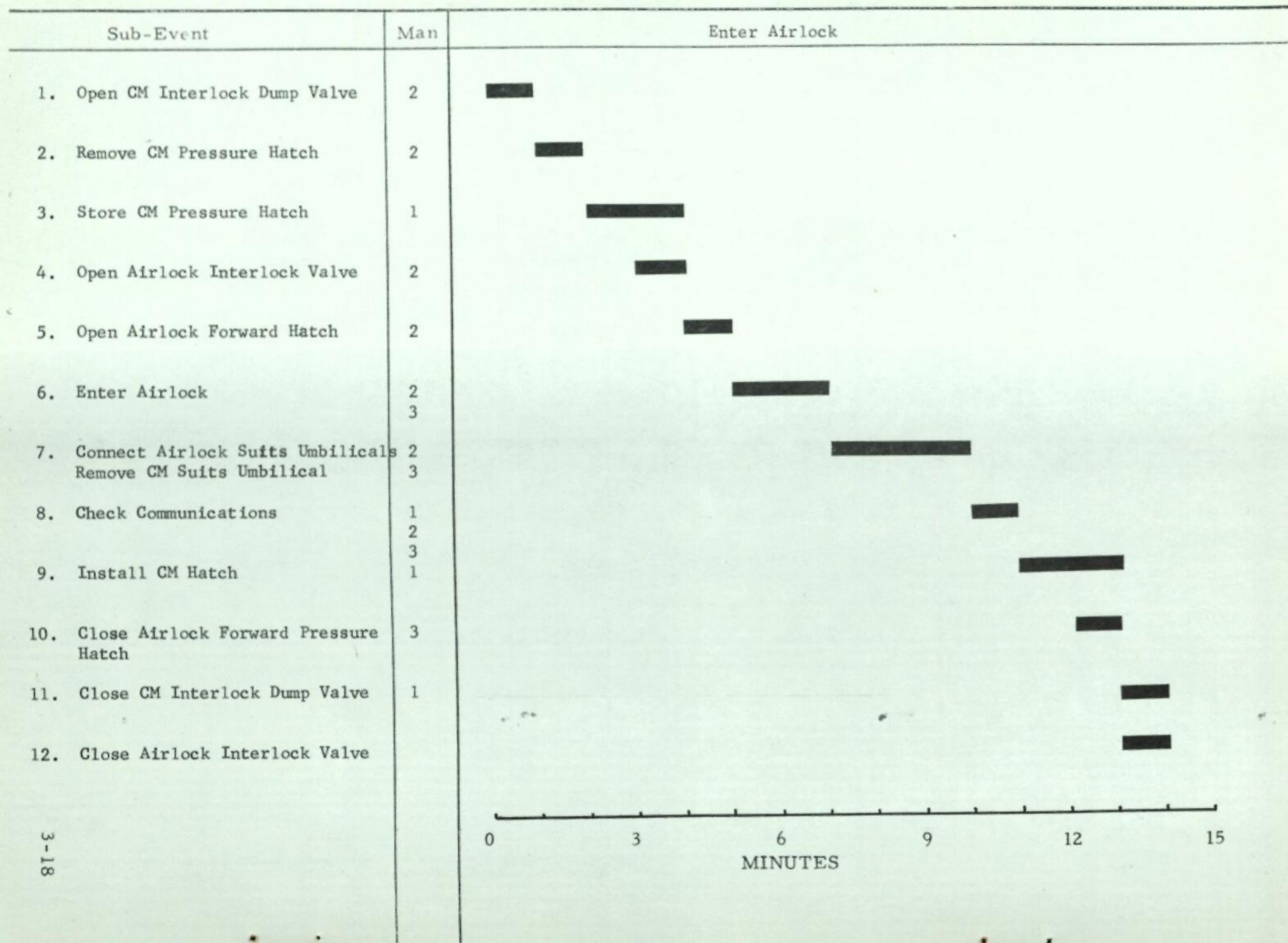




Day 1 Event 15

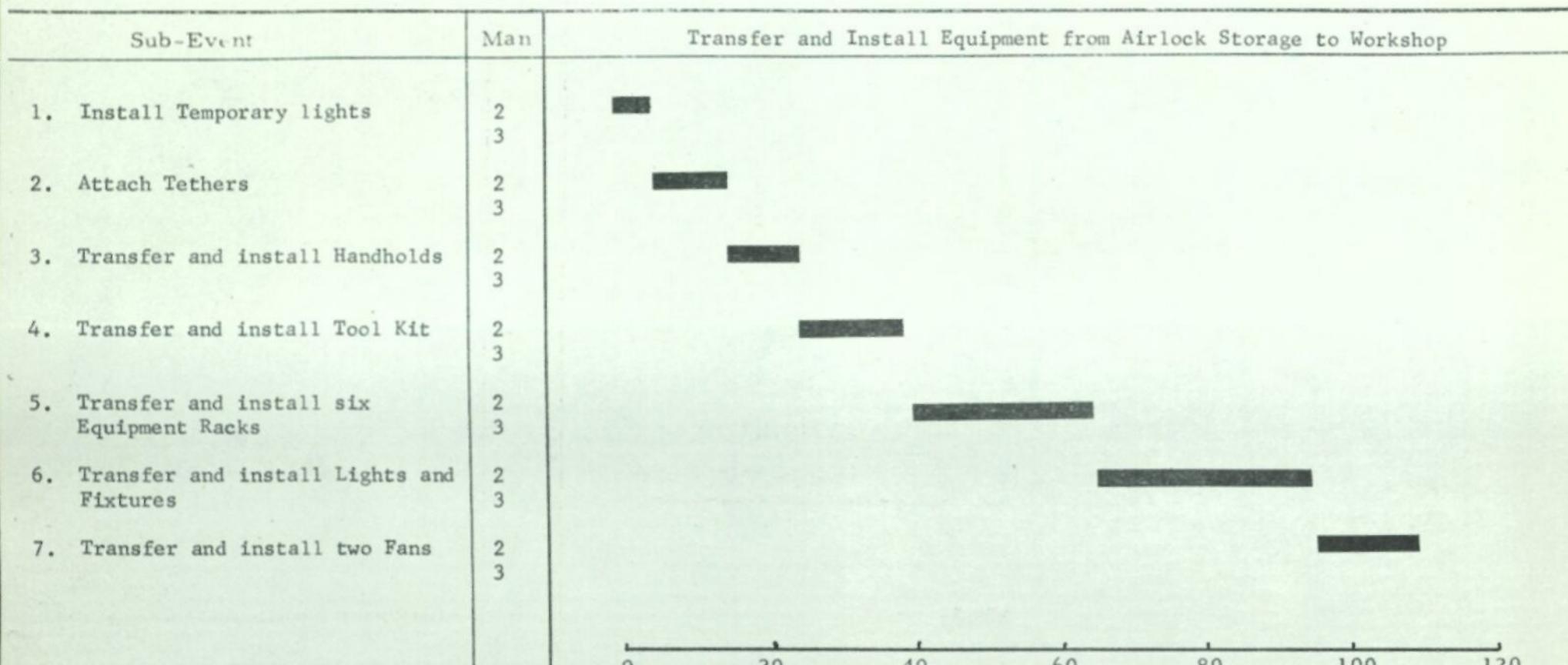
FIGURE 3.3-9. - AS-209 DESIGN REFERENCE MISSION SEQUENCE





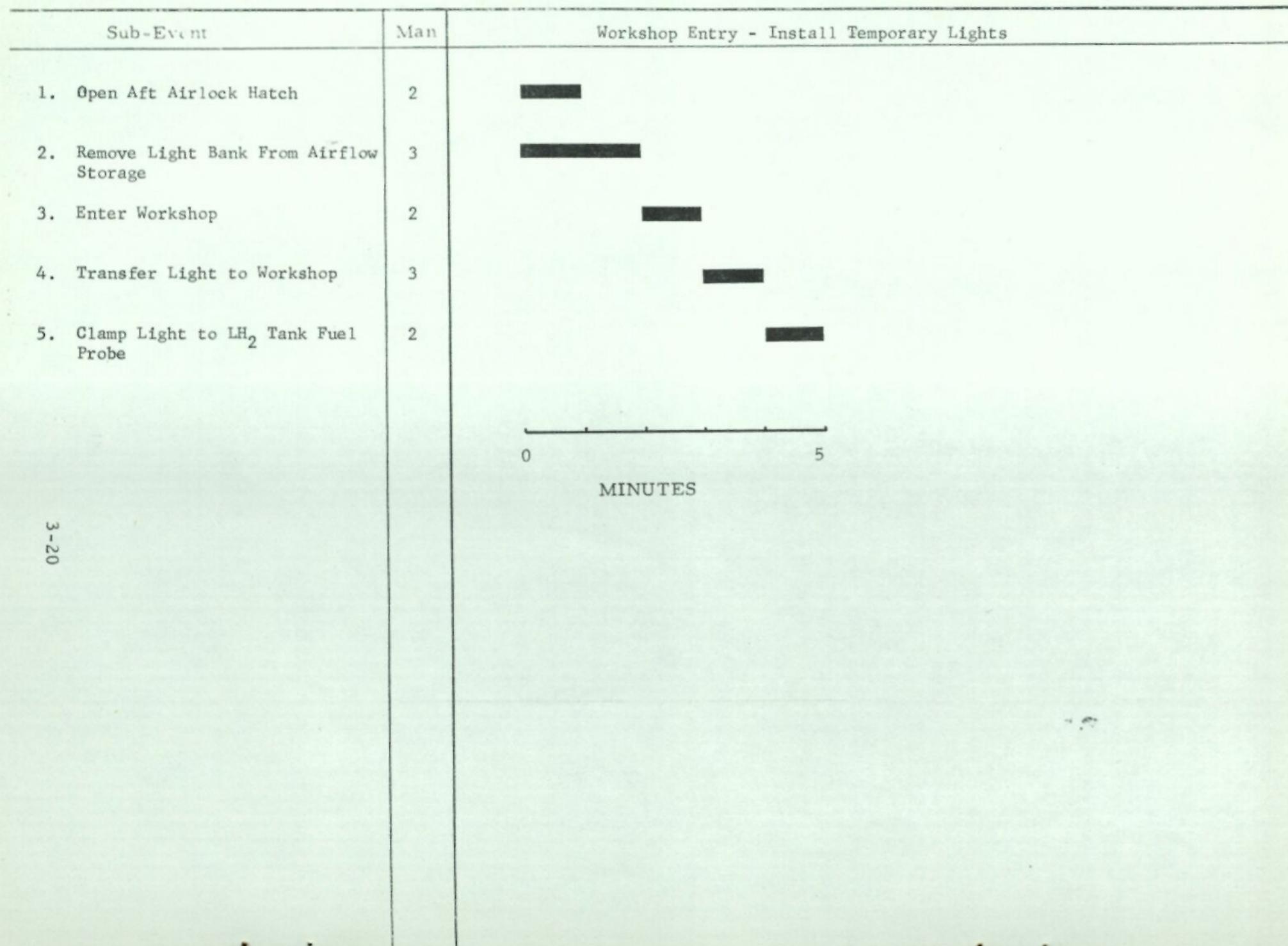
Day 2 Event 3

FIGURE 3.3-11. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



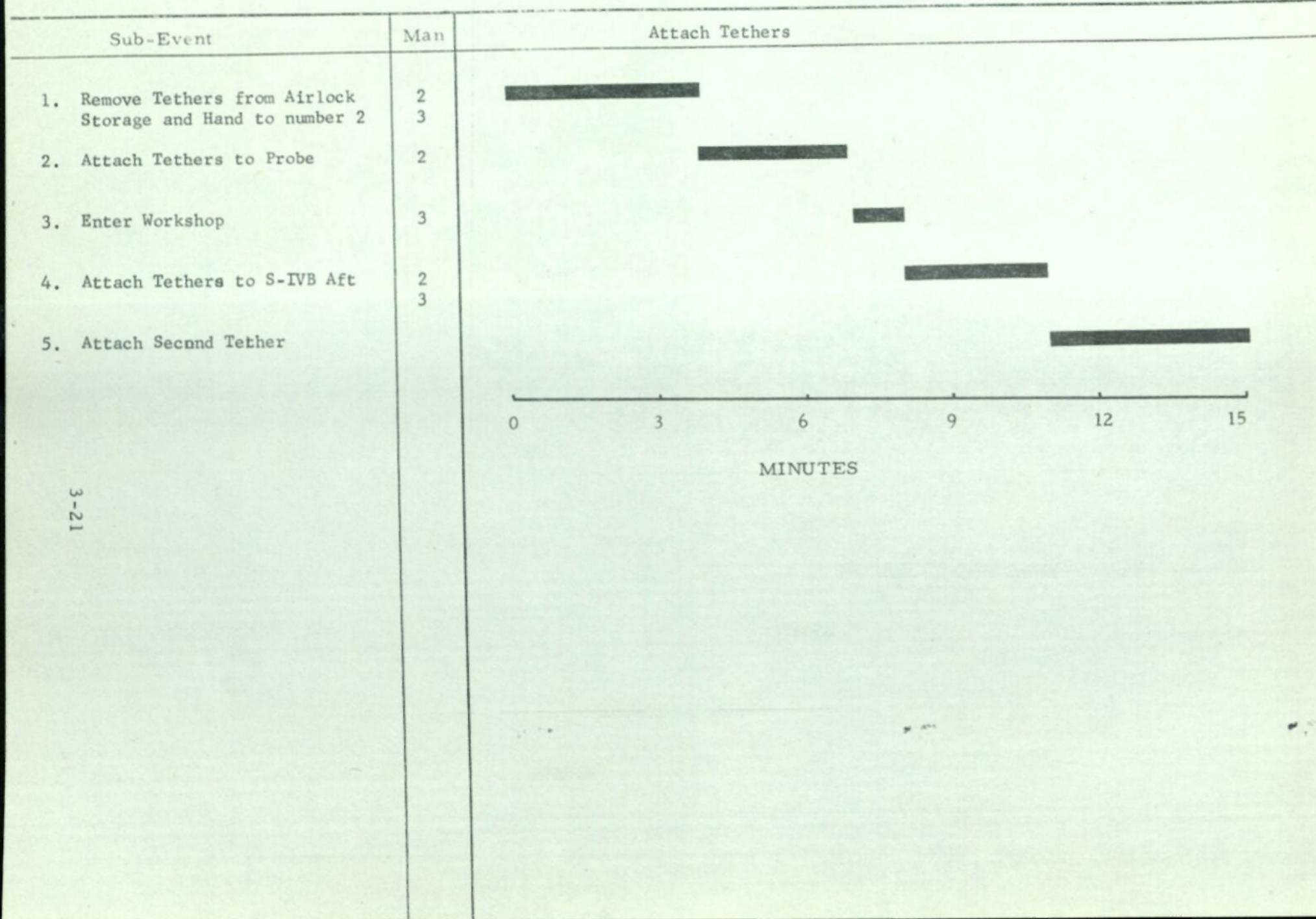
NOTE: The events on this page are broken down into
more detail in the following seven pages.

Day 2 Event: 3-1 FIGURE 3.3-12. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

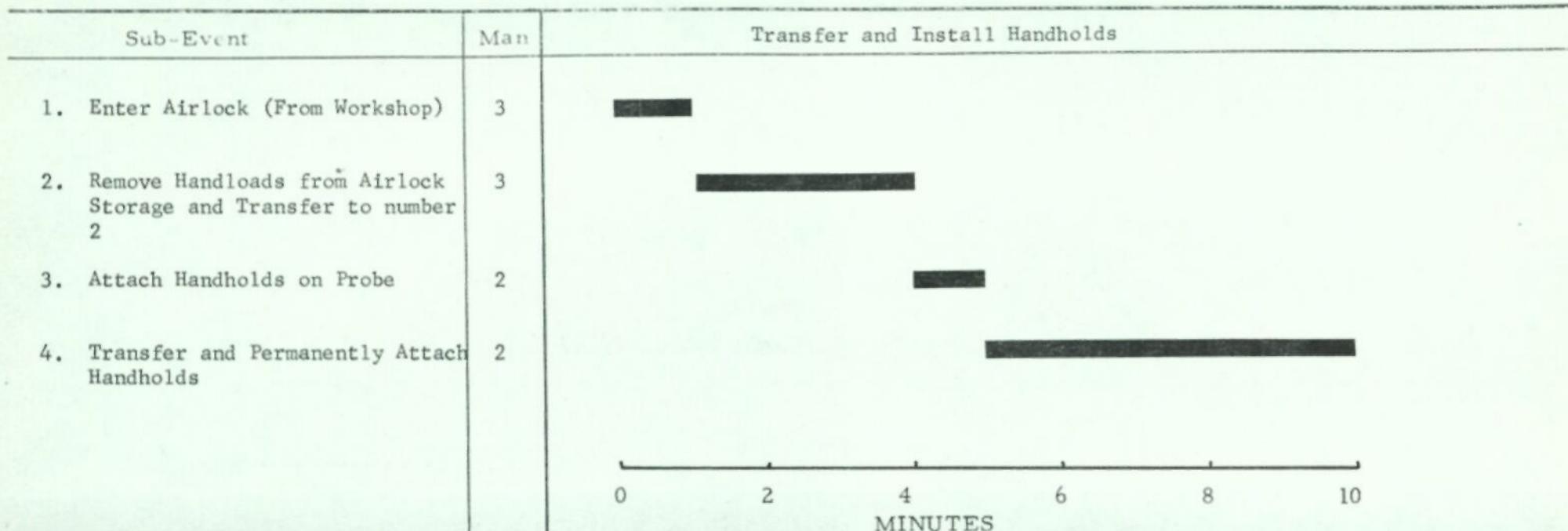


Day 2 Event 3-2

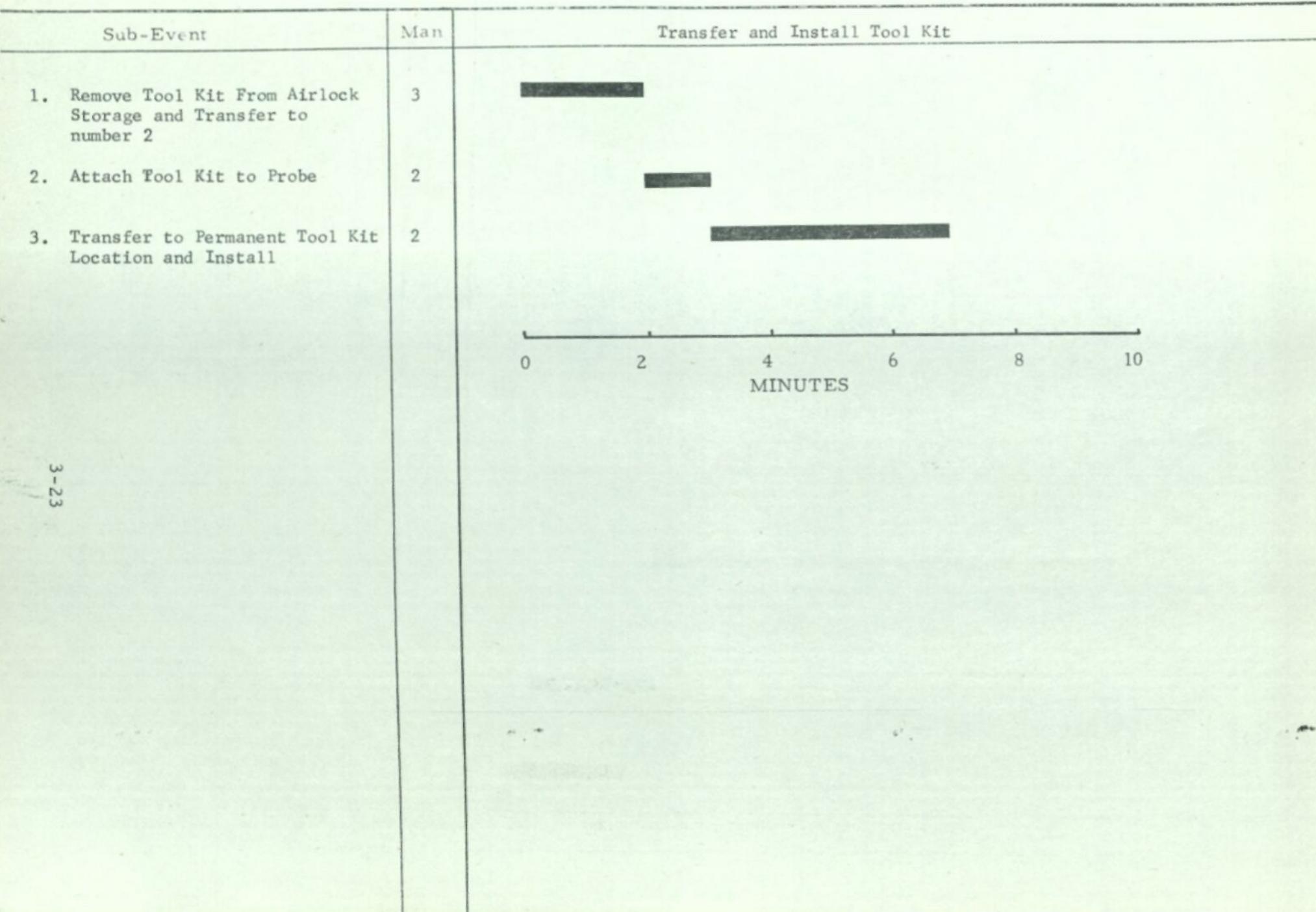
FIGURE 3.3-13. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



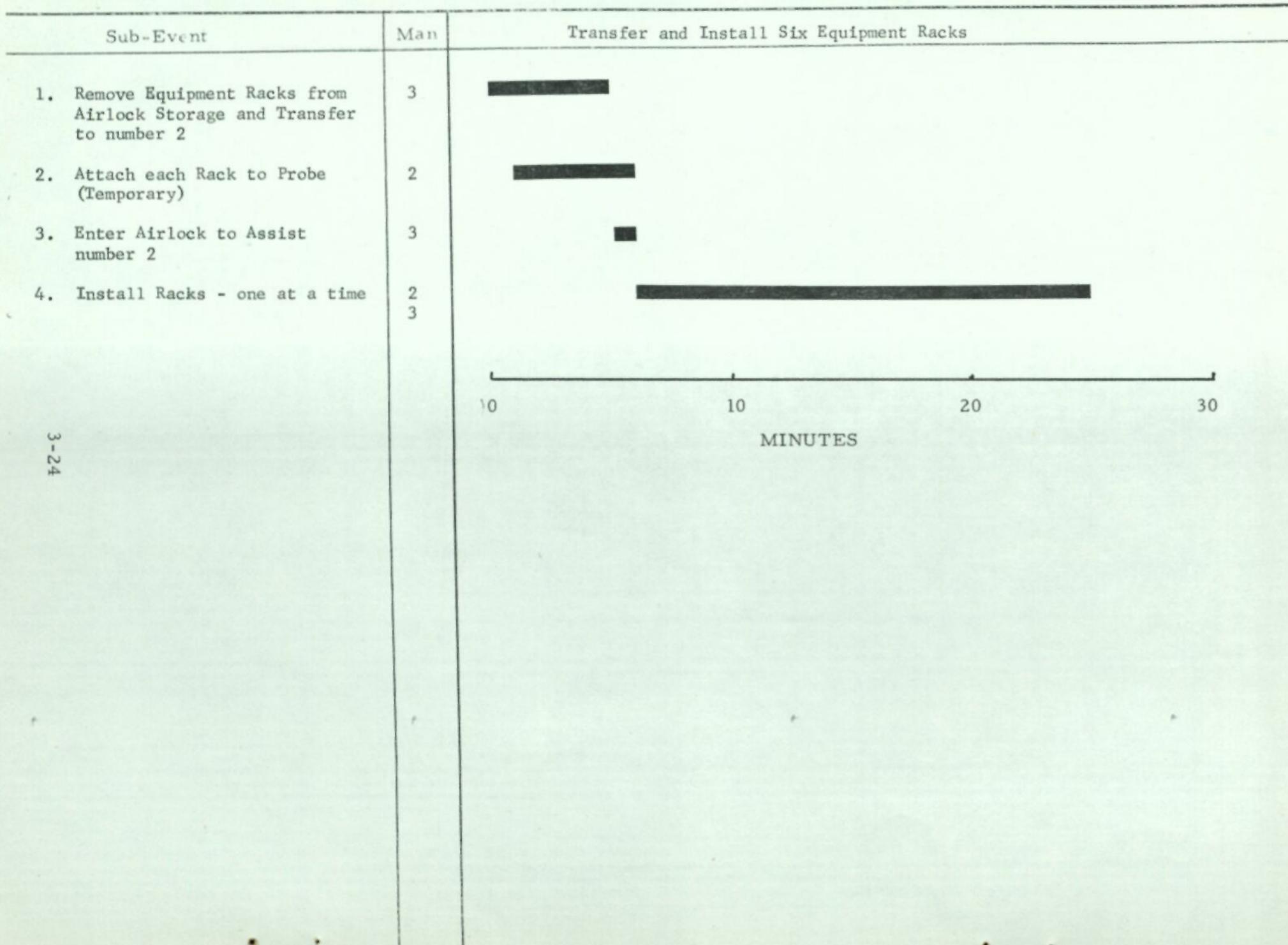
Day 2 Event 3-3 FIGURE 3.3-14. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



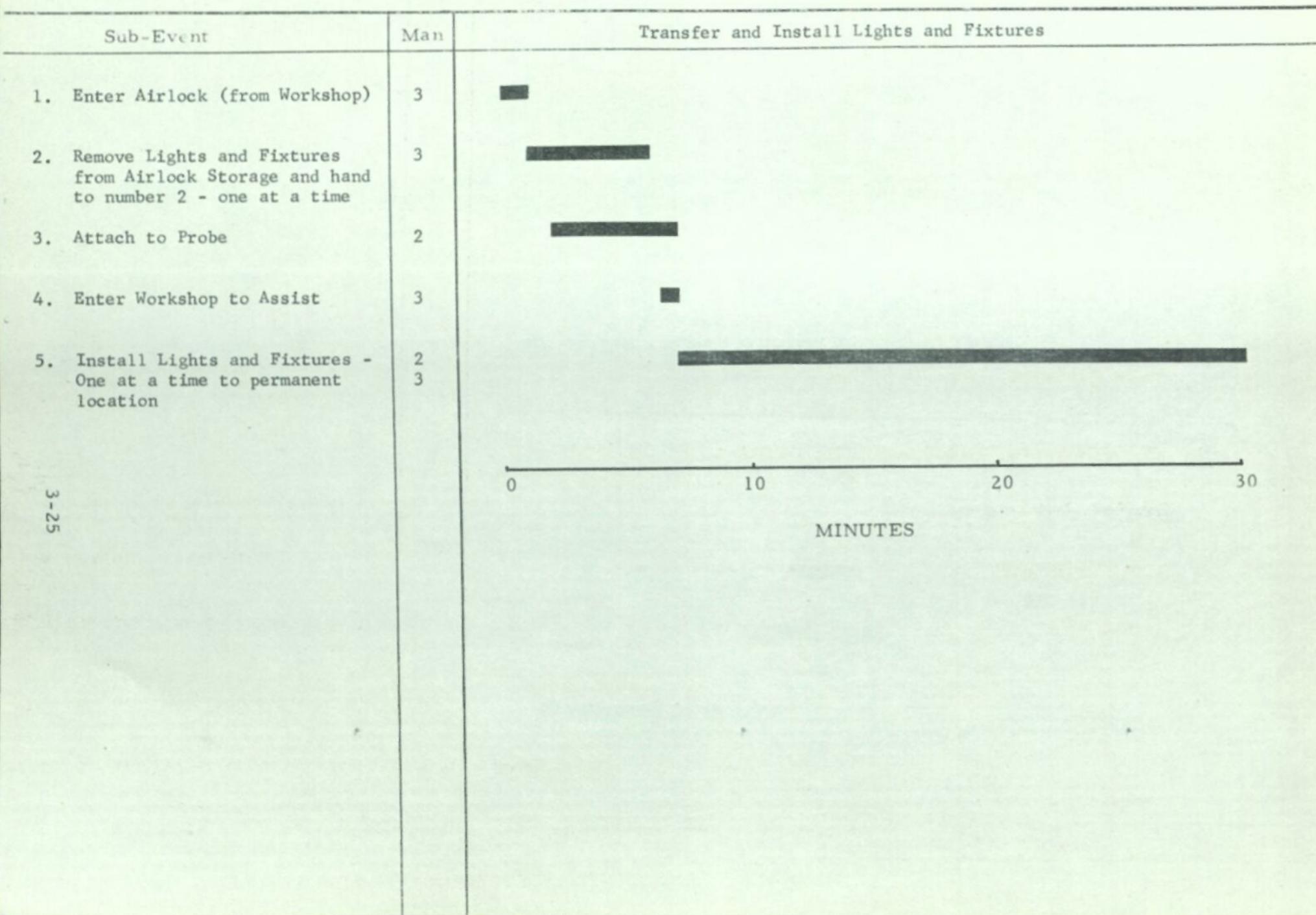
Day 2 Ever: 3-4 FIGURE 3.3-15. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



Day 2 Event 3-5 FIGURE 3.3-16. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

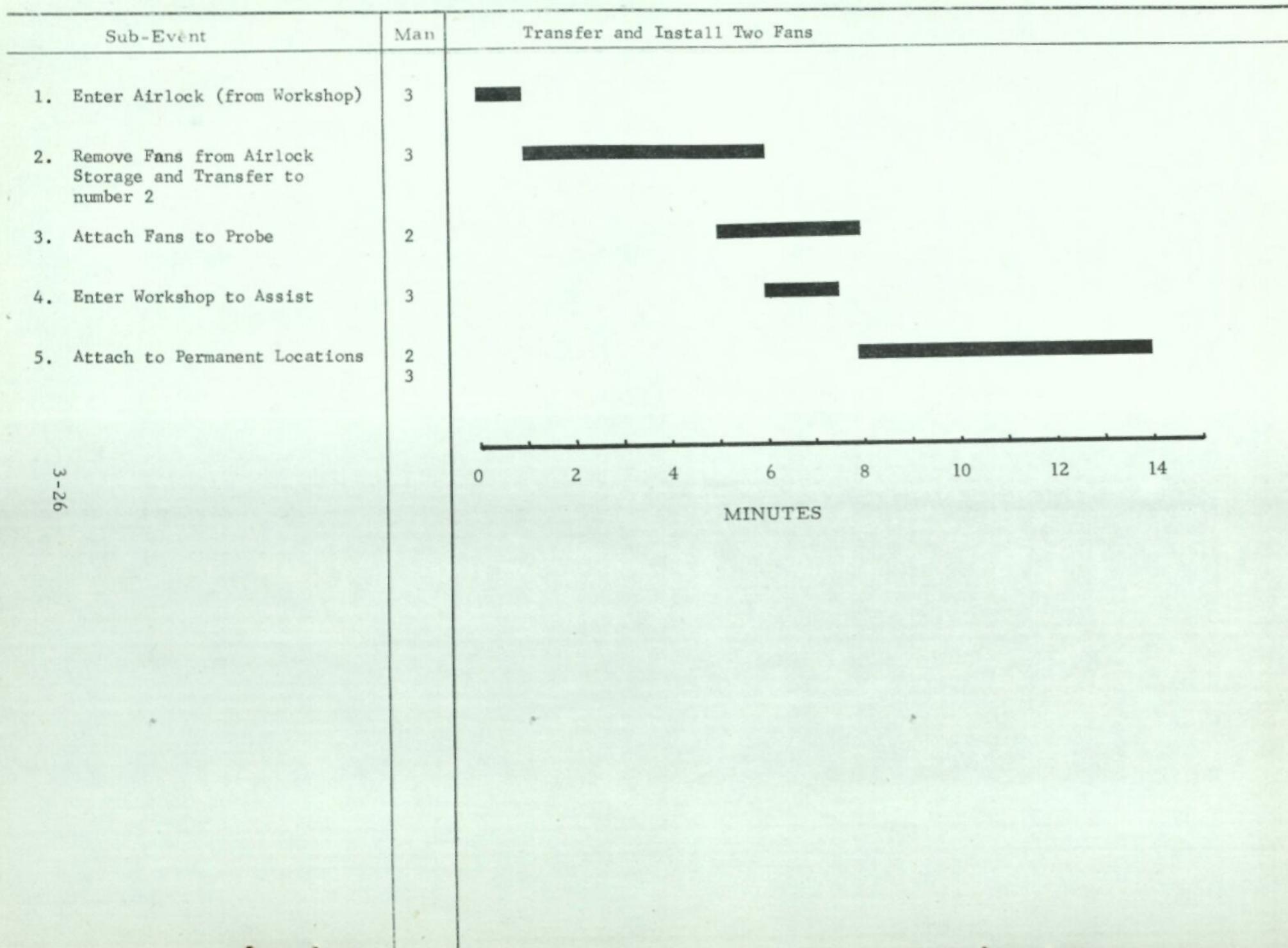


Day 2 Event: 3-6 FIGURE 3.3-17. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

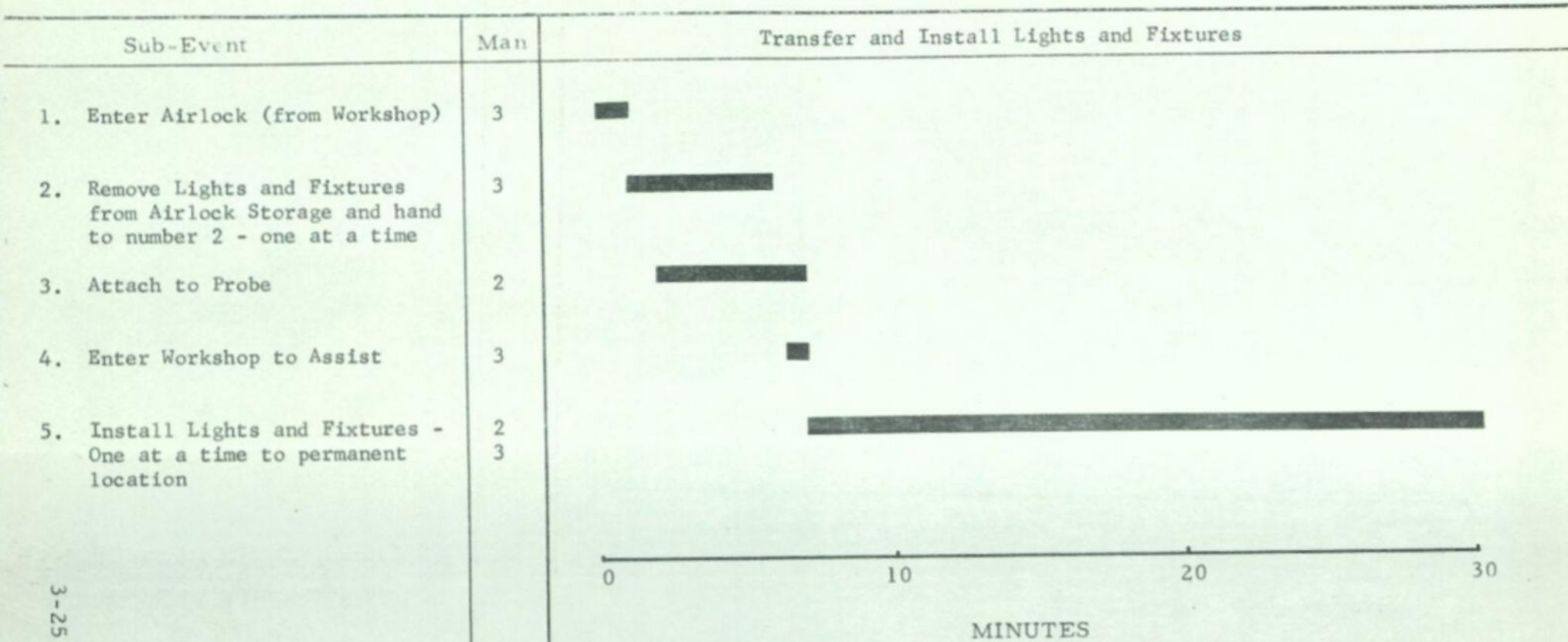


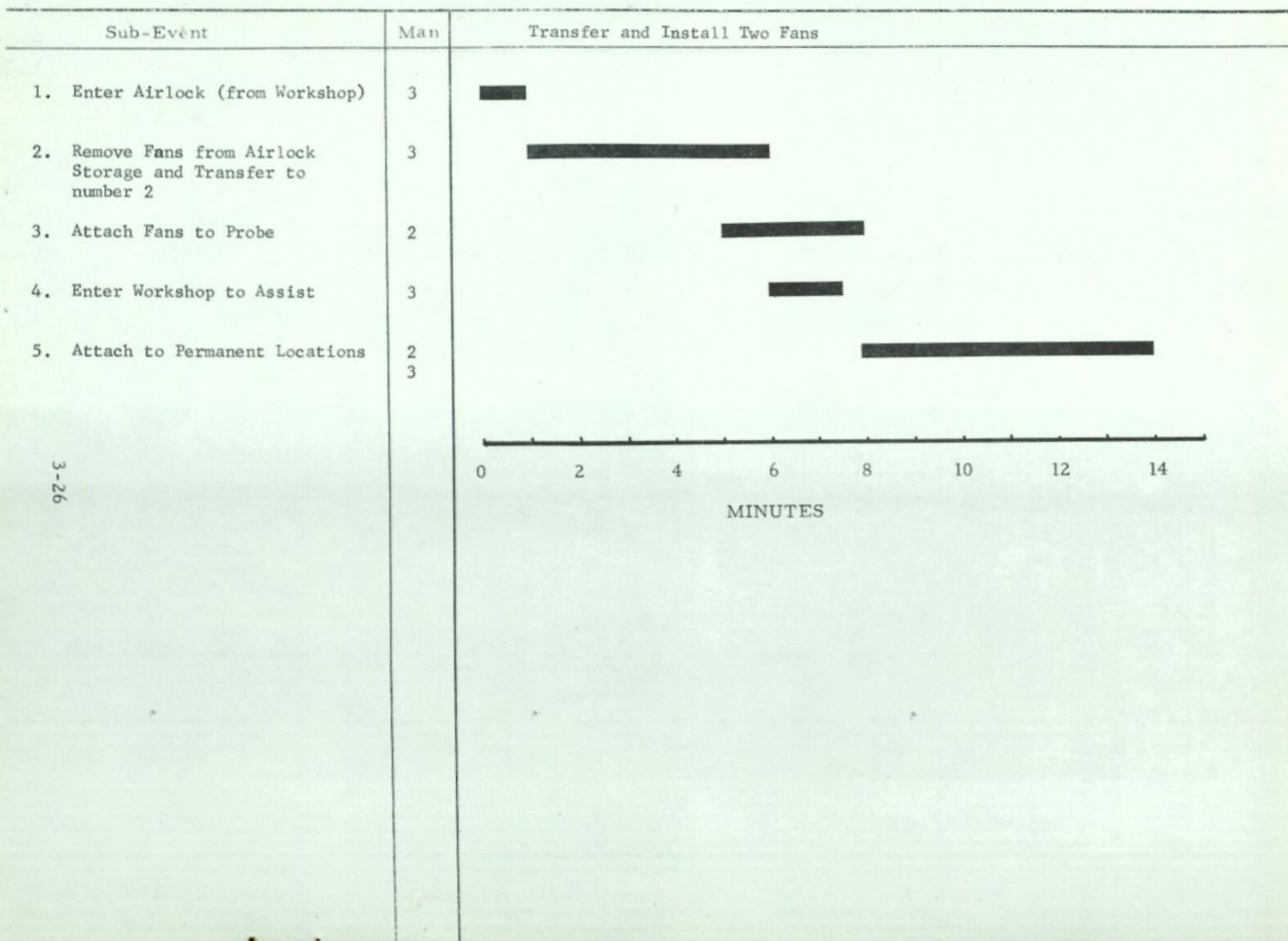
Day 2 Event 3-7

FIGURE 3.3-18. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



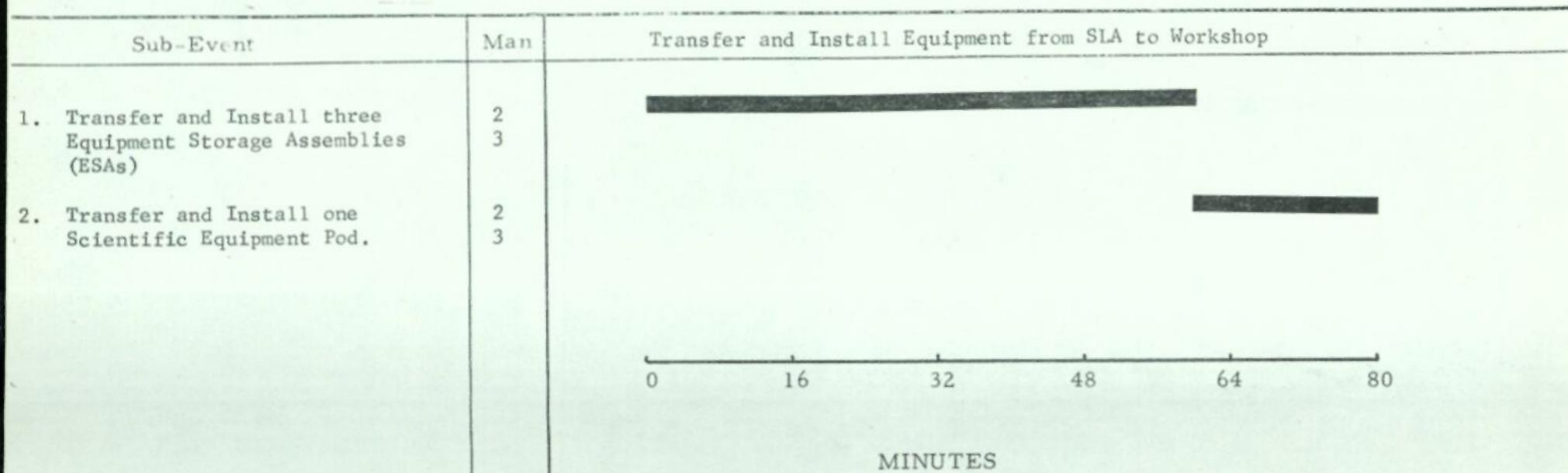
Day 2 Event: 3-6 FIGURE 3.3-17. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



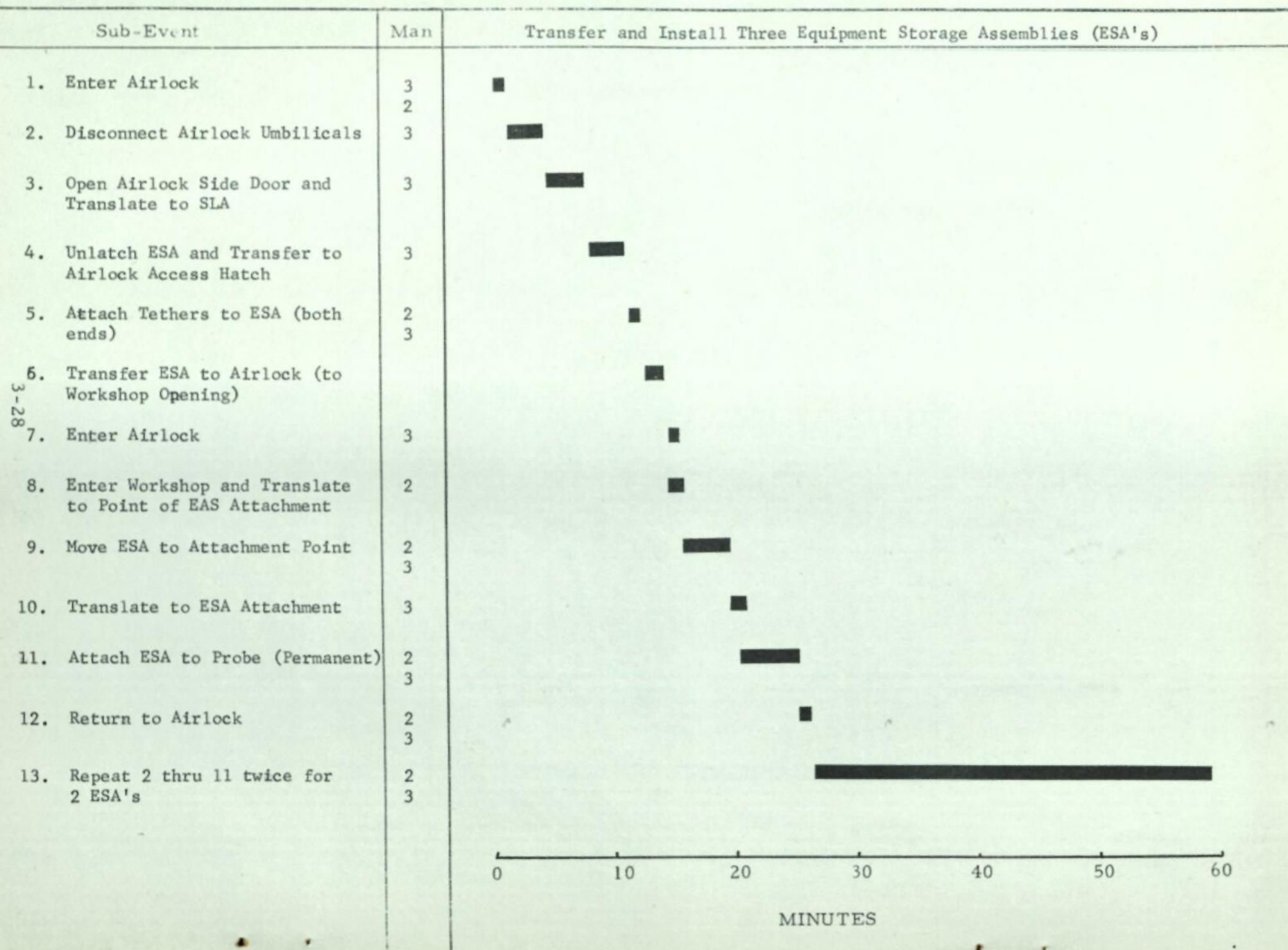


Day 2 Event 4

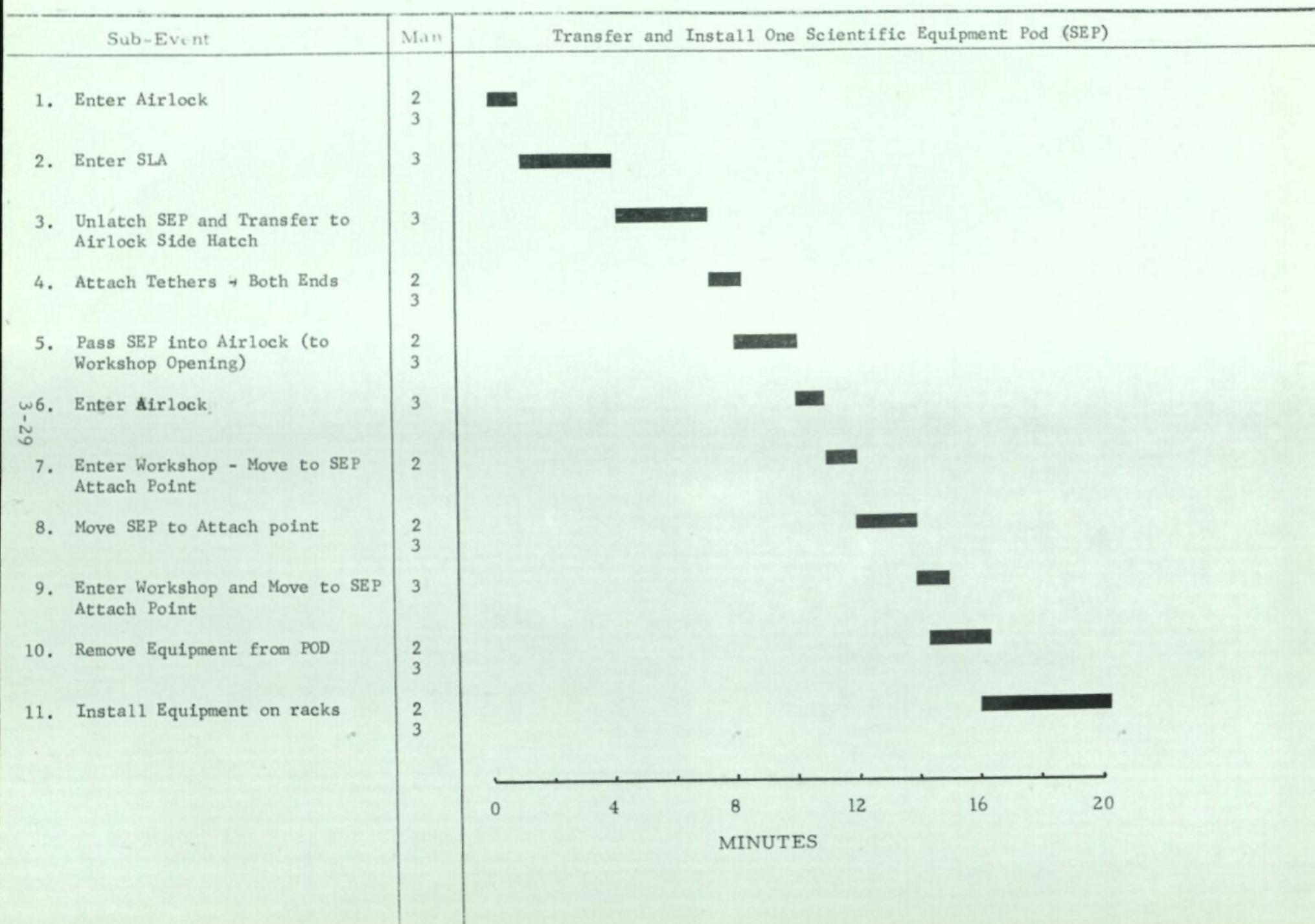
FIGURE 3.3-19. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



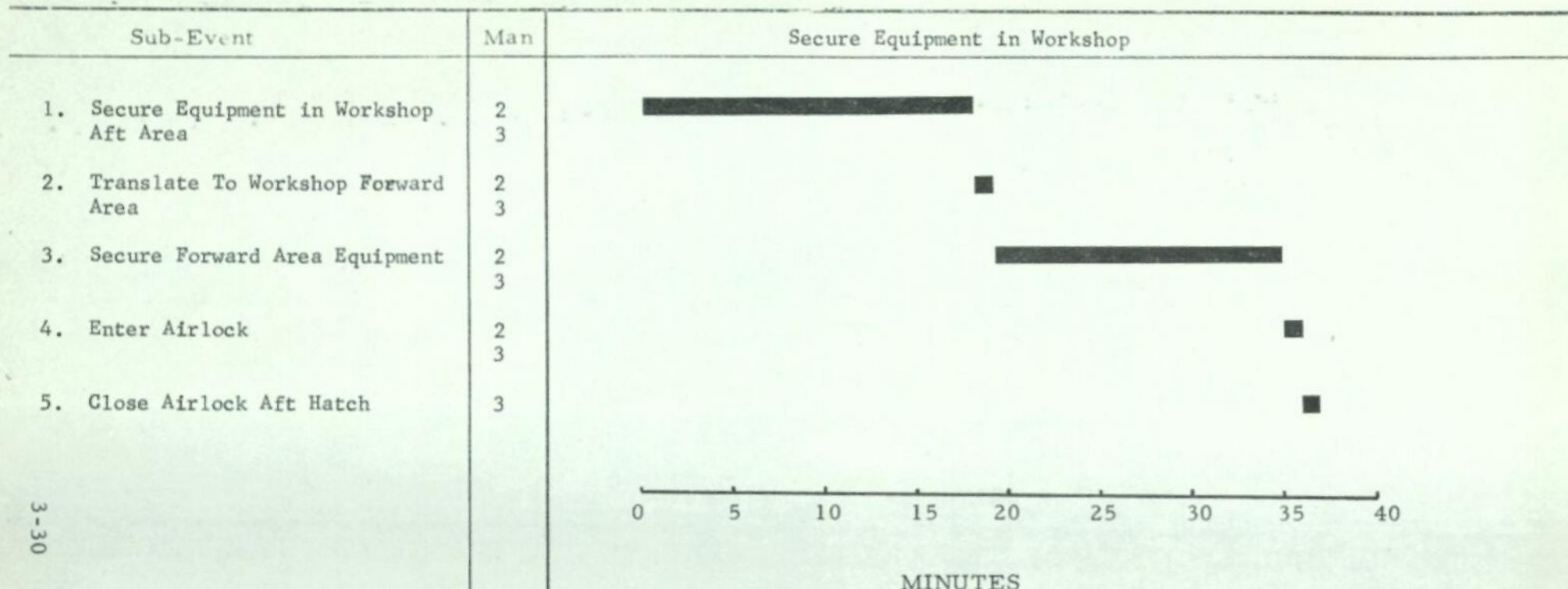
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Day 2 Event 4-2 FIGURE 3.3-21. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

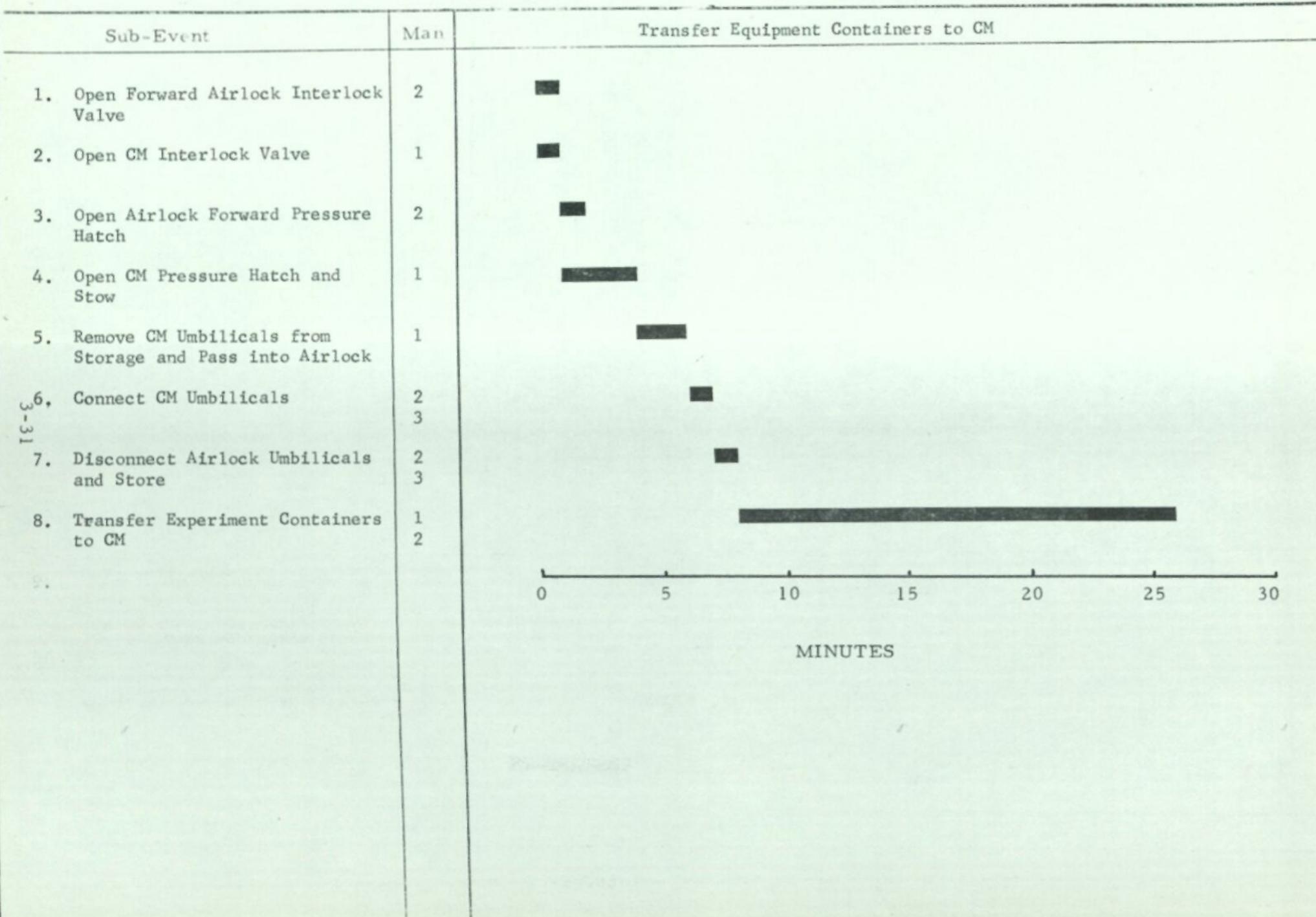


Day 20 Event 3 FIGURE 3.3-22. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



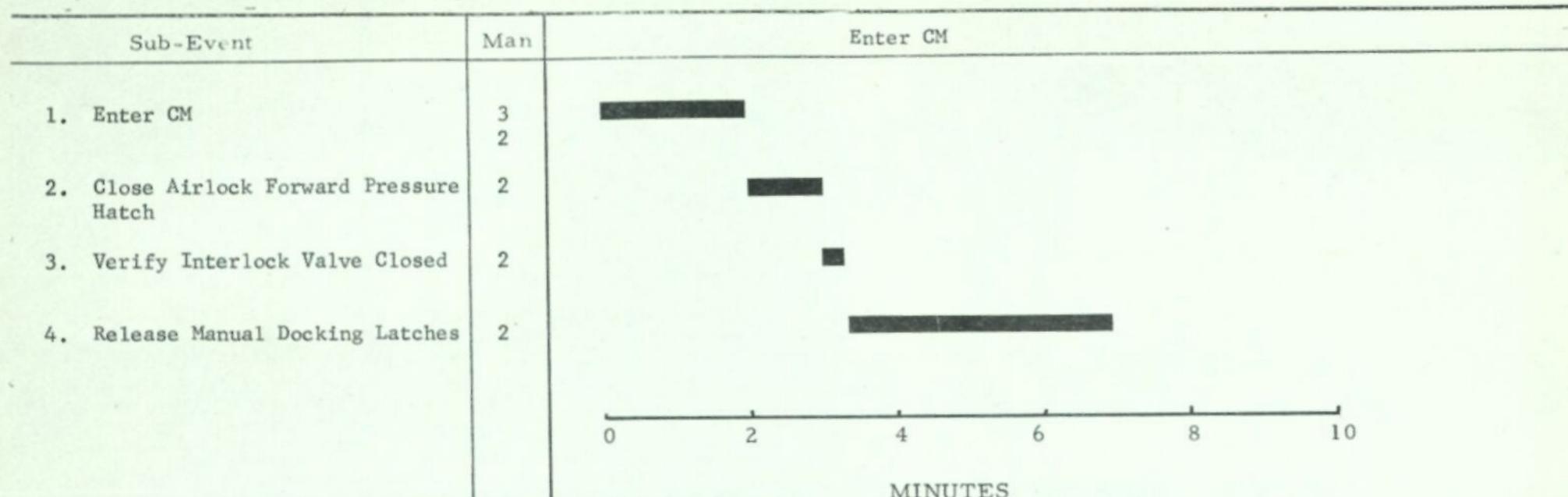
Day 20 Event: 4

FIGURE 3.3-23. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



Day 20 Event 5

FIGURE 3.3-24. - AS-209 DESIGN REFERENCE MISSION SEQUENCE



Day 20 Event 6

FIGURE 3.3-25. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

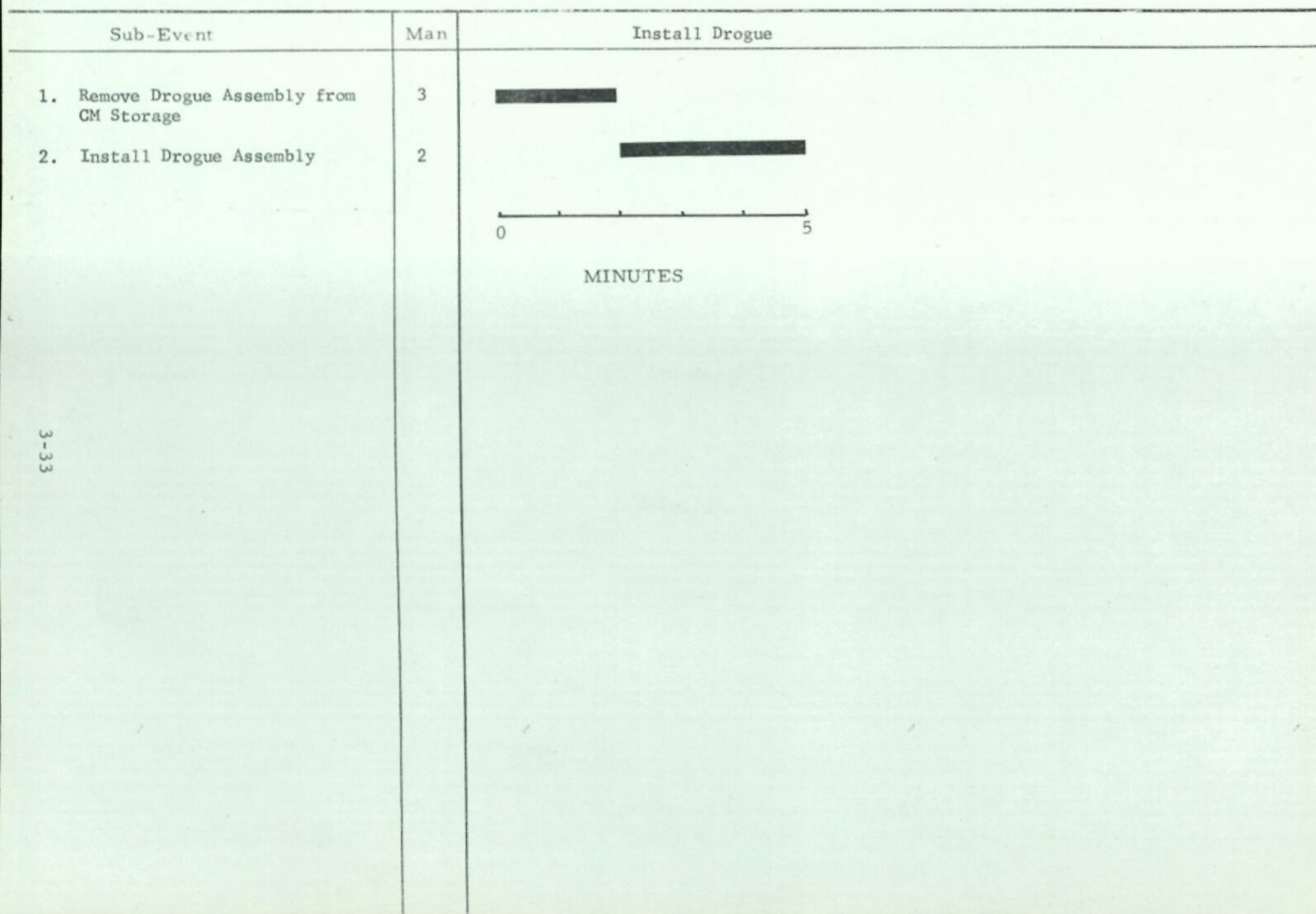


FIGURE 3.3-26. - AS-209 DESIGN REFERENCE MISSION SEQUENCE

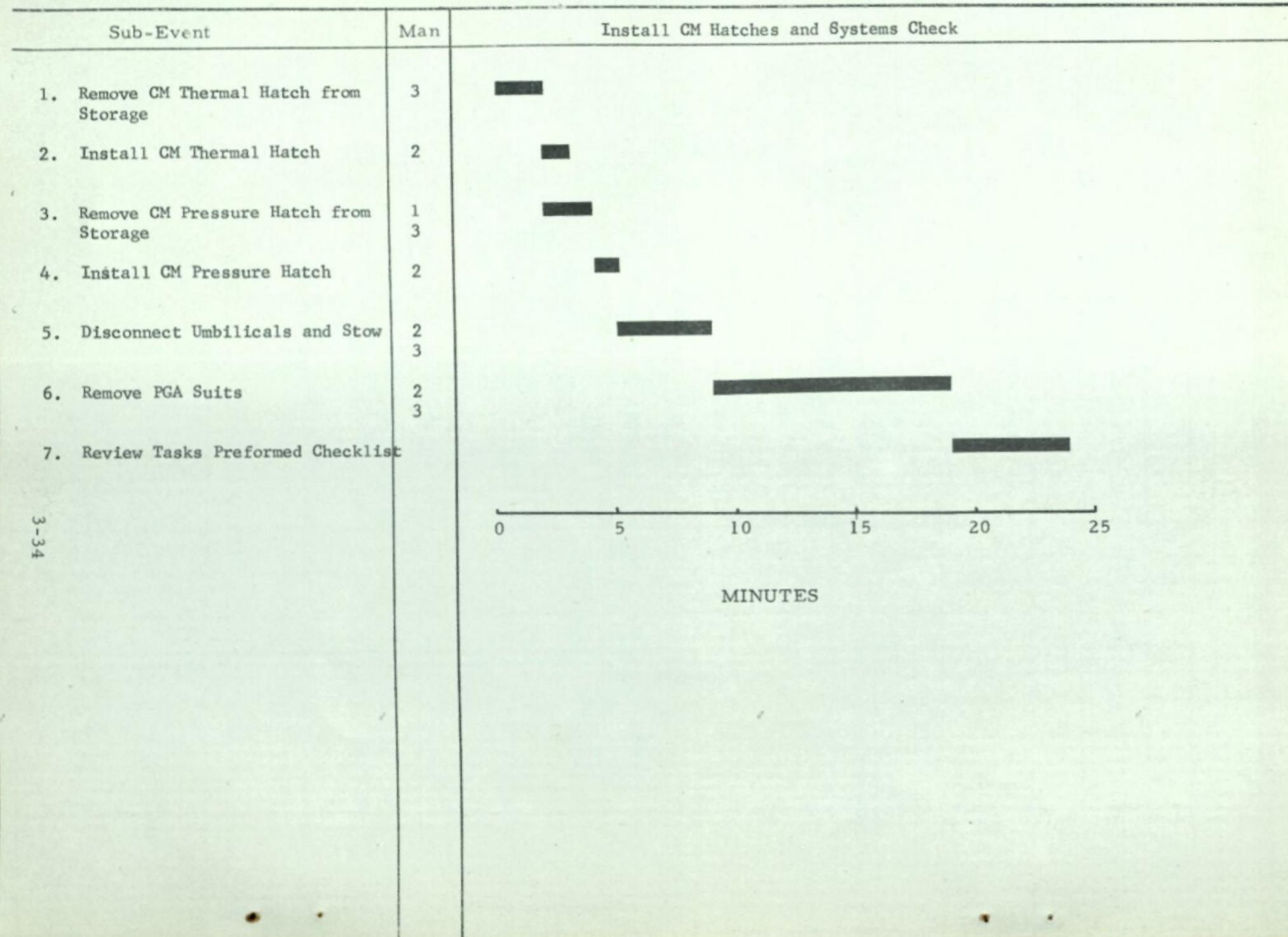


FIGURE 3.4-1. - CREW SCHEDULE

DAY 0

	0	4	8	12	16	20	24				
LAUNCH, CHECKOUT	R E A D	M E A L	P X H X X	ACCOMPLISH	S N A C K	S S M	SLEEP	P X H X X	PERFORM	M E A L	N AP
ESTABLISH AND CONFIRM DEPLOY	S Y S T E M A N S A U S	M E A L	P X H X X	STAGE	S N A C K	SLEEP	P X H X X	C S M		M E A L	N AP
ORBIT	S L A P A N E L S S M	C S N A H X X X	P X H X X	PASSIVATION	M E A L	SLEEP	P X H X X	EXPERIMENTS	M E A L	N AP	

DAY 1

0	4	8	12	16	20	24
MEAL	MEAL	MEAL	SLEEP	TRANSMITTER	TRANSMITTER	MEAL
COFFEE	COFFEE	COFFEE	COFFEE	TRANSMITTER	TRANSMITTER	NAP
AND	AND	AND	SLEEP	AND	AND	MEAL
COFFEE	COFFEE	COFFEE	SLEEP	SCIENCE	SCIENCE	NAP
MEAL	MEAL	MEAL	MEAL	SCIENCE	SCIENCE	MEAL
H2O	H2O	H2O	SLEEP	EQUIP	EQUIP	NAP
SHOWER	SHOWER	SHOWER	SHOWER	EVA	EVA	

DAY 2

FIGURE 3.4-2. - CREW SCHEDULE

DAY 3

0	4	8	12	16	20	24
C S M	X MEAL P H	X MEAL P H	SLEEP	P H S Y R	TANK T T T T	M EAL NAP
T T T T TANK T T T T	T T T T TANK T T T T	T T T T TANK T T T T	SLEEP	P H S Y R	T T T T TANK T T T T	M EAL NAP
T T T T TANK T T T T	T T T T TANK T T T T	T T T T TANK T T T T	SLEEP	P H S Y R	C	M EAL NAP

DAY 4

0	4	8	12	16	20	24
C S M	X MEAL P H	T T T T TANK T T T T	SLEEP	P H S Y R	M EAL NAP	
	X MEAL P H		C S M	SLEEP	P H S Y R	M EAL NAP
	X MEAL P H		T T T T TANK T T T T	SLEEP	C P H S M	M EAL NAP

DAY 5

0	4	8	12	16	20	24
C S M	X MEAL P H	X MEAL P H	SLEEP	P H S Y R	T T T T TANK T T T T	M EAL NAP
T T T T TANK T T T T	T T T T TANK T T T T	T T T T TANK T T T T	SLEEP	P H S Y R	T T T T TANK T T T T	M EAL NAP
T T T T TANK T T T T	T T T T TANK T T T T	T T T T TANK T T T T	SLEEP	P H S Y R	C S M	M EAL NAP

3-36

SECTION 4.0 VIBRATION AND ACOUSTIC TESTING

4.1 ACOUSTIC TEST PROCEDURES

4.1.1 Requirements

Acoustic environmental qualification testing will be performed in a reverberation chamber. Requirements are outlined in Table 4.1-1.

4.1.2 Reverberation Chamber Testing

a. The test chamber volume shall be such that the physical bulk of the item under test will not interfere with the generation and maintenance of test conditions.

b. The sound pressure field shall be measured with the test item or a suitable dummy mounted in the test chamber. Acoustic measurements shall be made in proximity to each major, dissimilar surface of the test specimen. The overall sound pressure level, reduced by six decibels, shall be introduced into the test chamber and adjusted to conform with the specified acoustic spectrum. The time required to conduct the survey shall be less than one-fourth of the specified test time, unless the specimen is replaced with a dummy. The sound pressure level and the survey time are reduced to avoid possible premature damage to the test item. The microphone shall be moved around the test item maintaining a distance of approximately 18 inches from the specimen. The measurements made within this volume shall then be averaged and the extreme values shall be noted.

c. When (b) is accomplished, the sound pressure level shall be raised to the design specification value and the test shall commence.

4.1.3 Test Spectrum

The acoustic test levels shall be those in the specification.

4.1.4 Test Duration

Generally the test shall consist of a high-level exposure, immediately followed by a low-level exposure. Time durations for the high- and low-level exposures are given in the specification.

TABLE 4.1-1. - EXTERNAL AND INTERNAL ACOUSTIC SPECIFICATIONS

One-third Octave Band Geometric Mean Freq. (cps)	External Sound Pressure Levels		Internal Sound Pressure Levels	
	High Level (dB)	Low Level (dB)	High Level (dB)	Low Level (dB)
5.0			106.5	100.0
6.3			109.0	102.5
8.0			112.5	106.0
10.0			115.5	109.0
12.5			118.0	111.5
16.0			121.5	115.5
20.0			124.5	118.0
25.0			127.5	121.0
31.5			130.5	124.0
40.0	Not Applicable	Not Applicable	133.0	126.5
50.0			136.0	129.5
63.0			139.0	132.5
80.0			139.5	133.0
100.0			139.5	133.0
125.0			140.0	133.5
160.0			140.0	133.5
200.0			140.0	133.5
250.0			140.5	134.0
315.0			140.5	134.0
400.0			141.0	134.5
500.0			138.5	132.0
630.0			136.5	130.0
800.0			135.0	128.5
1000.0			134.0	127.5
1250.0			133.0	126.5
1600.0			131.0	124.5
2000.0			129.5	123.0
2500.0			127.0	120.5
3150.0			124.5	118.0
4000.0			121.5	115.0
5000.0			118.0	111.5
6300.0			115.0	108.5
8000.0			111.0	104.5
10,000.0			107.5	101.0
Overall Sound Pressure Level			151.0	144.5

TABLE 4.1-1.- Concluded

STAGE: S-IVB

MAJOR ZONE: 15, Station 1541 to Station 1663 - The portion of the S-IVB Stage lying between the plane of juncture of the LH₂ container cylindrical section with the forward LH₂ bulkhead and the plane of the field splice with the IU.

One-Third Octave Band Acoustical Specifications in dB re 2×10^{-5} N/M²

Test Duration:	High Level <u>3.0 Minutes</u>
	Low Level <u>15.0 Minutes</u>

4.1.4 Tolerances

a. The test time shall be within -0 to +10 percent of the time set forth in the test specifications.

b. For reverberation chamber testing, the overall sound pressure level and the individual one-third octave band, sound pressure levels shall be within -0 to +4 decibels of the levels set forth in the test specification with the test specimen installed.

4.2 VIBRATION AND SHOCK CRITERIA

4.2.1 General

Preliminary flight vibration and shock criteria for the S-IVB Spent Stage Experiment SSESM are presented below, and in Figures 4.2-1 through 4.2-10. Vibration criteria are presented for (1) Saturn IB primary structure input to the SSESM assembly, and (2) primary unloaded SSESM structure. Detailed individual component vibration test specifications will be derived as required.

4.2.2 Air lock Assembly Shock and Vibration Criteria

a. Sinusoidal Vibration Criteria (see Figure 4.2-1)

5 to 14 cps @ .044 In. Double Amp. Disp.
14 to 50 cps @ 0.44 g's peak
50 to 111 cps @ 0.0034 In. Double Amp. Disp.
111 to 600 cps @ 2.2 g's peak
600 to 2000 cps @ -1 g's Peak/Octave
2000 cps @ 0.46 g's peak

b. Random Vibration Criteria (see Figure 4.2-2).- Shall consist of three minutes of random noise over the frequency band 5 to 2000 cps at the following input levels:

5 cps @ 0.000204 g²/cps
5 to 35 cps @ 6 db/octave
35 to 400 cps @ 0.01 g²/cps
400 to 2000 cps @ -2 db/octave
2000 cps @ 0.00343 g²/cps

Composite Level = 3.5 G_{rms}

c. Assembly Shock Criteria

(1) Lift-off and separation shock pulse shall consist of a 10-g half sine wave for a duration of 10 milliseconds.

(2) Docking shock pulse shall consist of a 20-g half sine wave for a duration of 10 milliseconds.

4.2.3 SSESM Unloaded Structure Vibration Criteria

a. Skin Panel Structure

(1) Sinusoidal Vibration Criteria

(a) Lift-off and mainstage sinusoidal vibration criteria (see Figure 4.2-3).

5 to 70 cps @ 0.03 In. Double Amp. Disp.
70 to 210 cps @ 7.5 g's peak
210 to 305 cps @ .0033 In. Double Amp. Disp.
305 to 500 cps @ 15.6 g's peak
500 to 2000 cps @ -6.45 g's peak/octave
2000 cps @ 2.7 g's peak

(b) Mach 1 and Max Q sinusoidal vibration criteria (see Figure 4.2-4).

5 to 66 cps @ 0.0705 In. Double Amp. Disp.
66 to 210 cps @ 15.6 g's peak
210 to 305 cps @ 0.0069 In. Double Amp. Disp.
305 to 500 cps @ 33 g's peak
500 to 2000 cps @ -13.8 g's peak/octave
2000 cps @ 5.4 g's peak

(2) Random Vibration Criteria

(a) Lift-off and mainstage random vibration criteria (see Figure 4.2-5). - Shall consist of 2 minutes of random noise over the frequency band 20 to 2000 cps at the following levels:

20 cps @ 0.0023 g²/cps
20 to 63 cps @ 9 db/octave
63 cps @ 0.07 g²/cps
63 to 380 cps @ 3.4 db/octave
380 to 420 cps @ 0.54 g²/cps

420 to 800 cps @ -3.75 db/octave
800 cps @ 0.24 g²/cps
800 to 2000 cps @ -9 db/octave
2000 cps @ 0.155 g²/cps
Composite Level = 17.41 G_{rms}

(b) Mach 1 and Max Q random vibration criteria
(see Figure 4.2-6).- Shall consist of one minute of random noise over the frequency band 20 to 2000 cps at the following levels:

20 cps @ 0.01 g²/cps
20 to 63 cps @ 9 db/octave
63 cps @ 0.31 g²/cps
63 to 380 cps @ 3.4 db/octave
380 to 400 cps @ 2.4 g²/cps
400 to 850 cps @ -3.5 db/octave
850 cps @ 1.0 g²/cps
850 to 2000 cps @ -1.5 db/octave
2000 cps @ 0.065 g²/cps

Composite Level = 45.38 G_{rms}

(3) Shock Criteria.- The shock pulse shall consist of a 20-g half sine wave for a duration of 10 milliseconds.

b. Skin Stiffener Structure

(1) Sinusoidal Vibration Criteria

(a) Lift-off and mainstage sinusoidal vibration criteria (see Figure 4.2-7)

5 to 50 cps @ 0.0354 In. Double Amp. Disp.
50 to 158 cps @ 4.5 g's peak
158 to 200 cps @ 0.00351 In. Double Amp. Disp.
200 to 500 cps @ 7.2 g's peak
500 to 2000 cps @ -2.4 g's peak/octave
2000 cps @ 2.4 g's peak

(b) Mach 1 and Max Q sinusoidal vibration criteria
(see Figure 4.2-8)

5 to 50 cps @ 0.075 In. Double Amp. Disp.
50 to 169 cps @ 9.6 g's peak
169 to 210 cps @ 0.0066 In. Double Amp. Disp.
210 to 500 cps @ 15 g's peak
500 to 2000 cps @ -4.8 g's peak/octave
2000 cps @ 5.4 g's peak

(2) Random Vibration Criteria

(a) Lift-off and mainstage random vibration criteria (see Figure 4.2-9). - Shall consist of 2 minutes of random noise over the frequency band 20 to 2000 cps at the following levels:

20 cps @ 0.0008 g²/cps
20 to 72 cps @ 8 db/octave
72 cps @ 0.027 g²/cps
72 to 400 cps @ 2.8 db/octave
400 cps @ 0.13 g²/cps
400 to 1000 cps @ -3 db/octave
1000 cps @ 0.052 g²/cps
1000 to 1600 cps @ -10.5 db/octave
1600 to 2000 cps @ 0.01 g²/cps

Composite Level = 6.76 G_{rms}

(b) Mach 1 and Max Q random vibration criteria (see Figure 4.2-10). - Shall consist of one minute of random noise over the frequency band 20 to 2000 cps at the following levels:

20 cps @ 0.0035 g²/cps
20 to 70 cps @ 3 db/octave
70 cps @ 0.12 g²/cps
70 to 400 cps @ 2.65 db/octave
400 cps @ 0.56 g²/cps
400 to 1000 cps @ -2.8 db/octave
1000 cps @ 0.24 g²/cps
1000 to 1600 cps @ -10.8 db/octave
1600 to 2000 cps @ 0.044 g²/cps

Composite Level = 10.85 G_{rms}

(3) Shock Criteria. - The shock pulse shall consist of a 20-g half sine wave for a duration of 10 milliseconds.

FIGURE 4.2-1

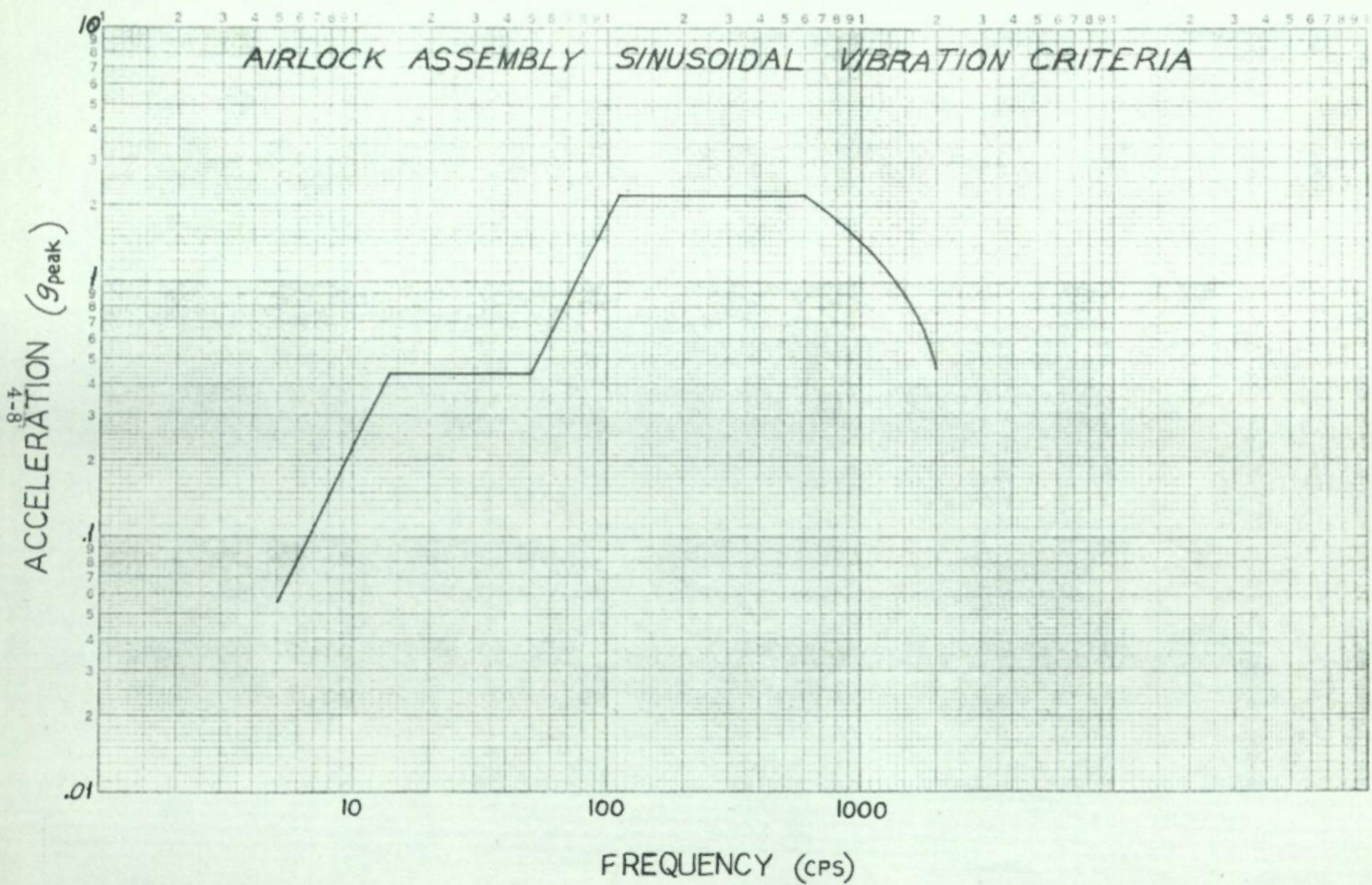


FIGURE 4.2-2

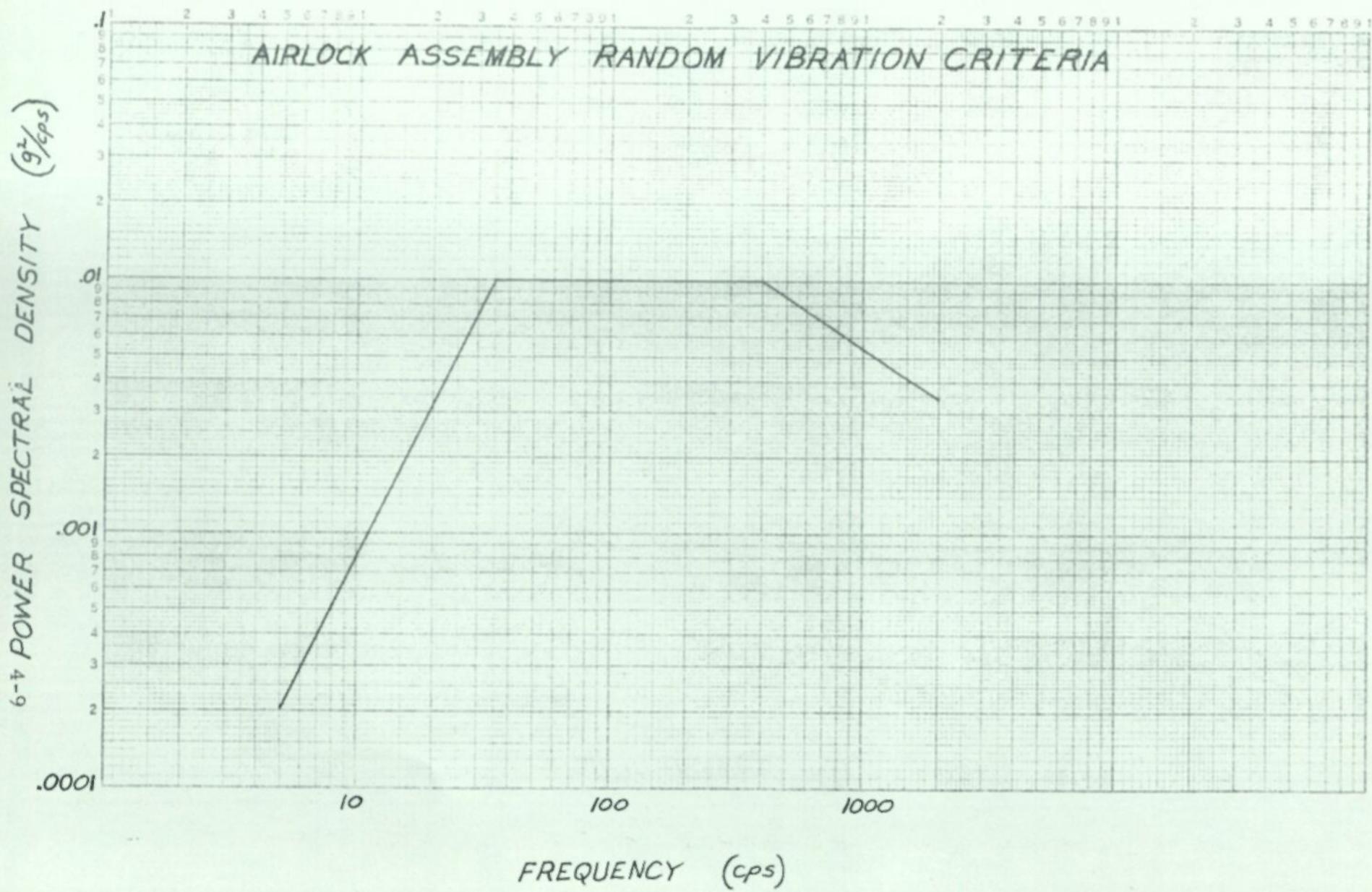


FIGURE 4.2-3

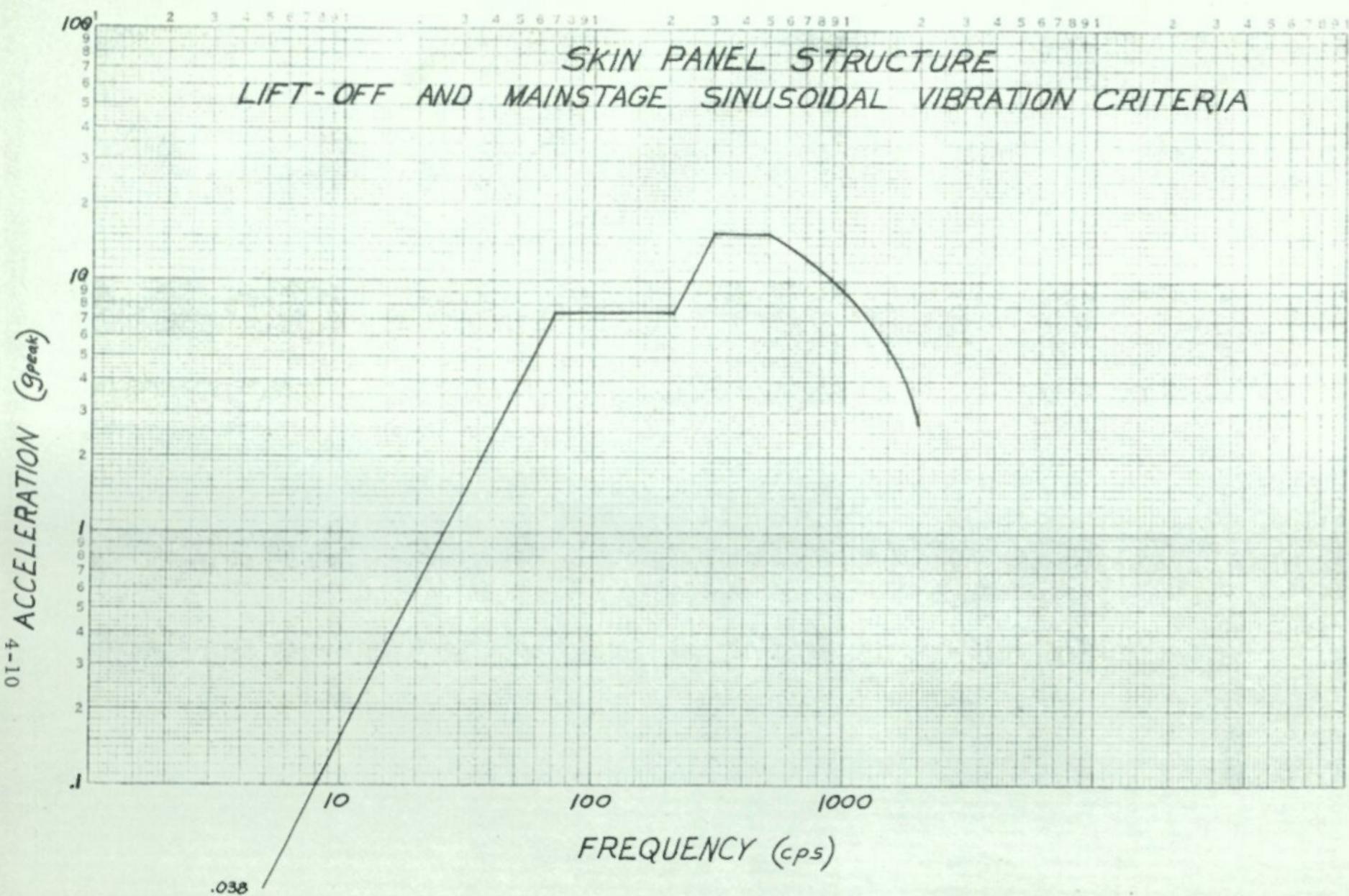


FIGURE 4.2-4

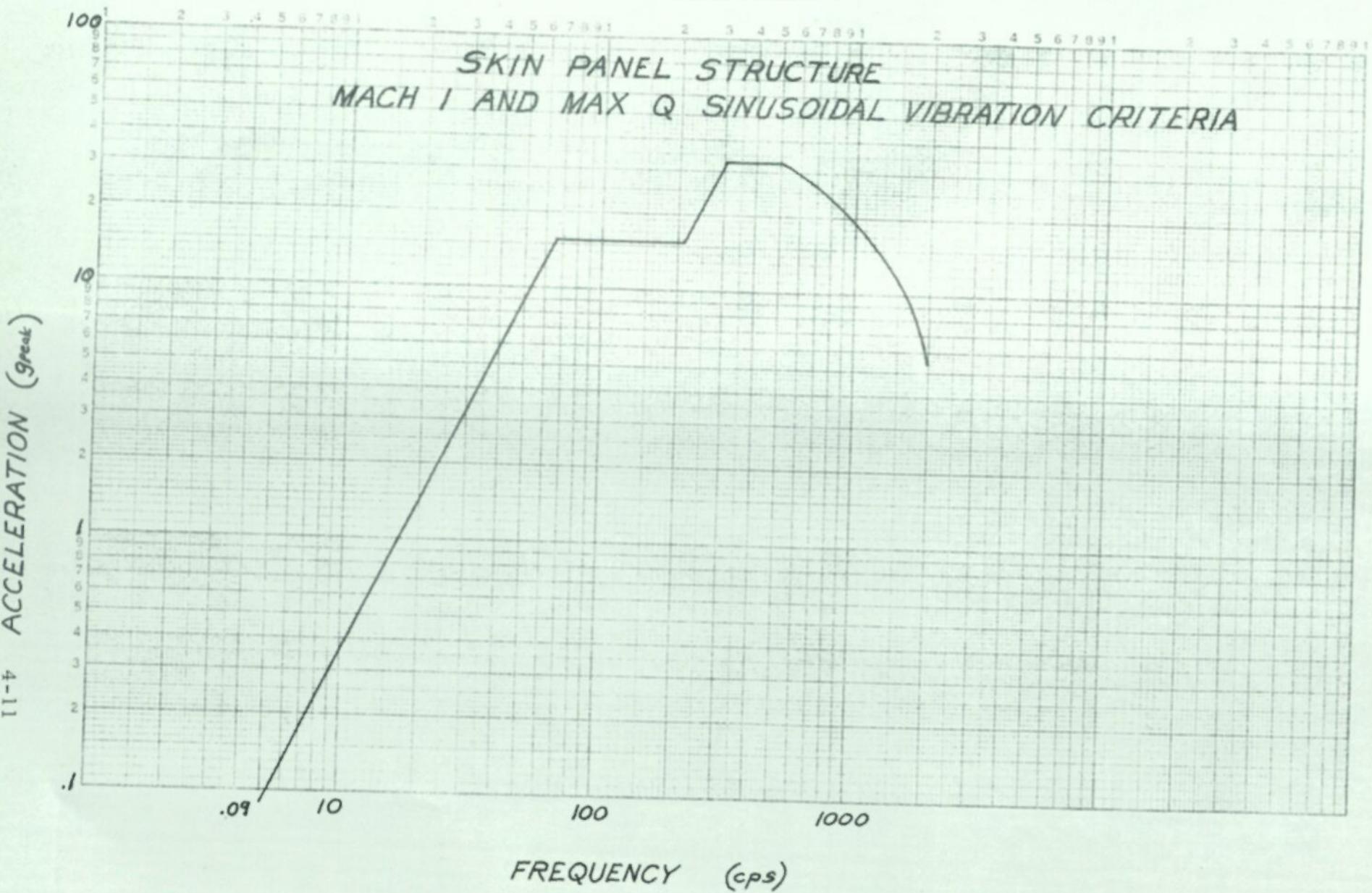


FIGURE 4.2-5

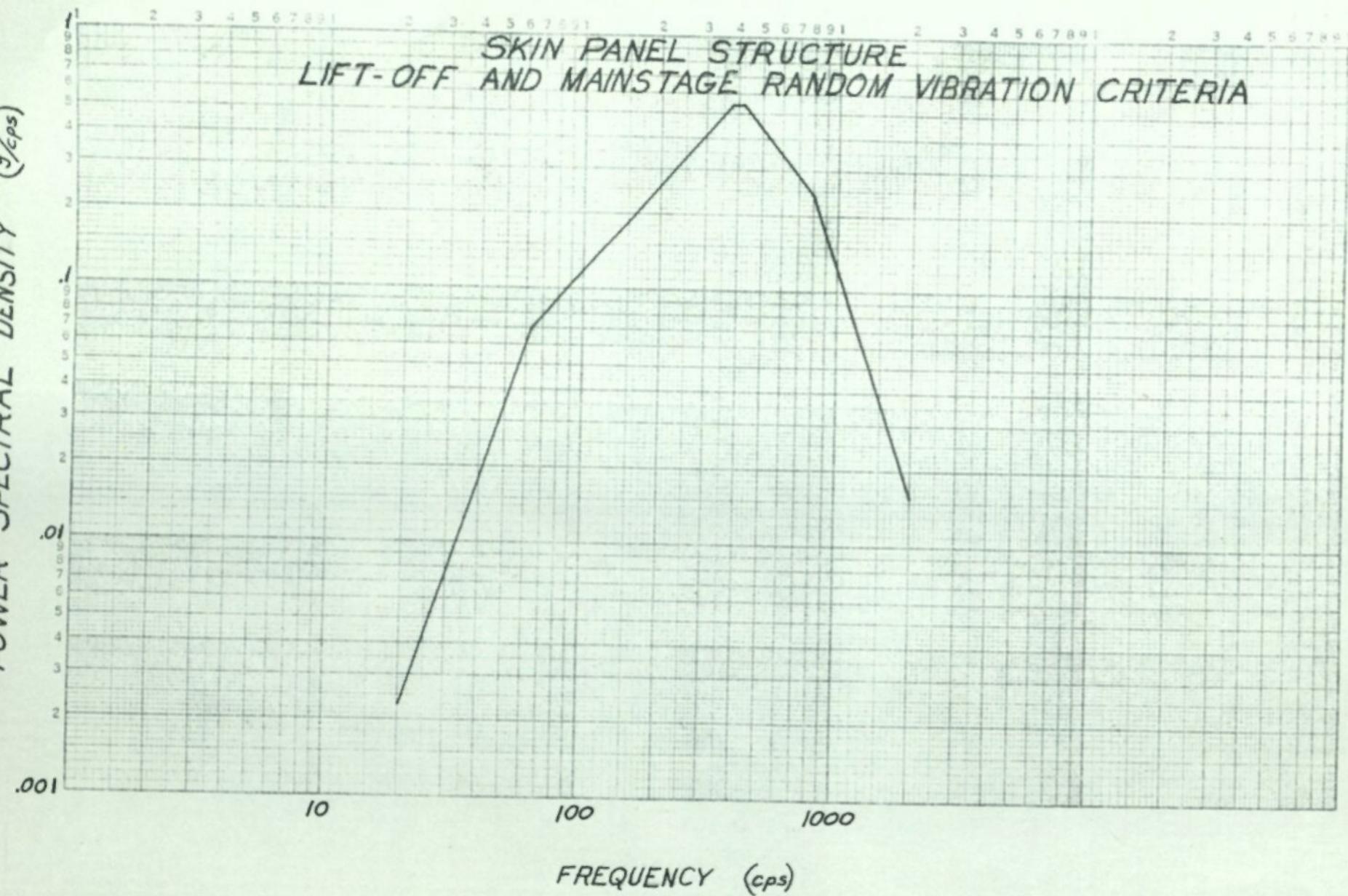


FIGURE 4.2-6

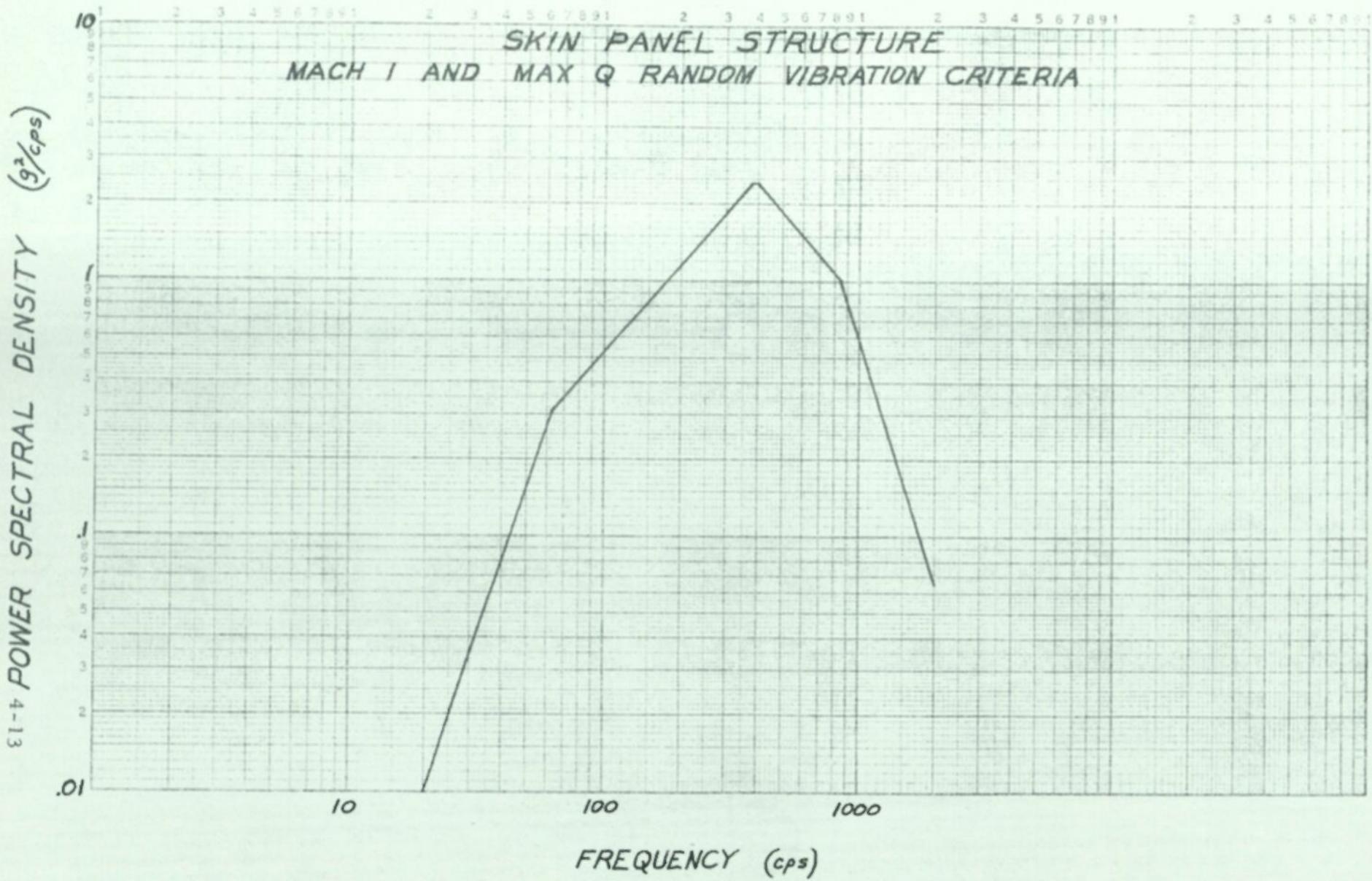


FIGURE 4.2-7

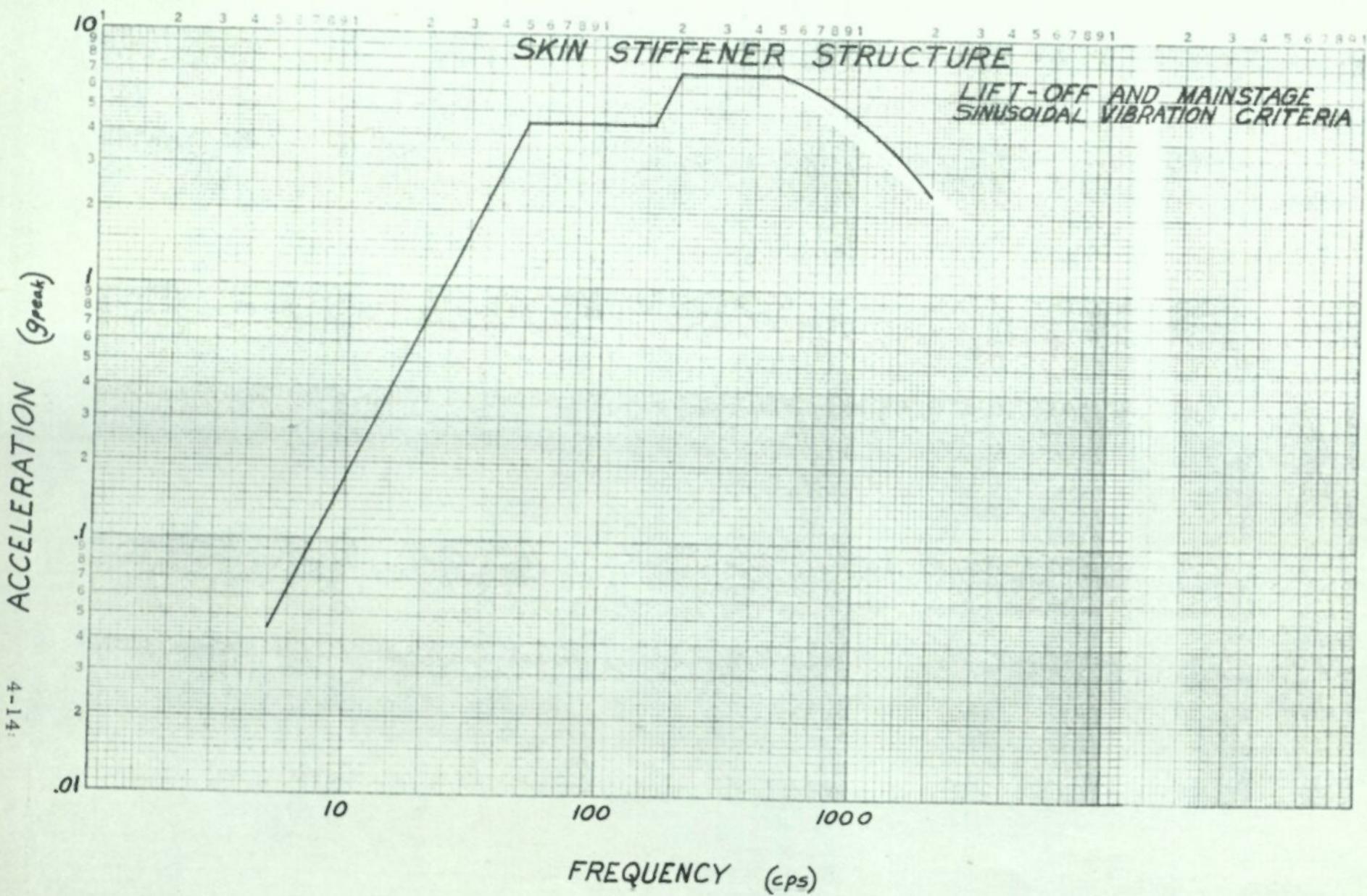


FIGURE 4.2-8

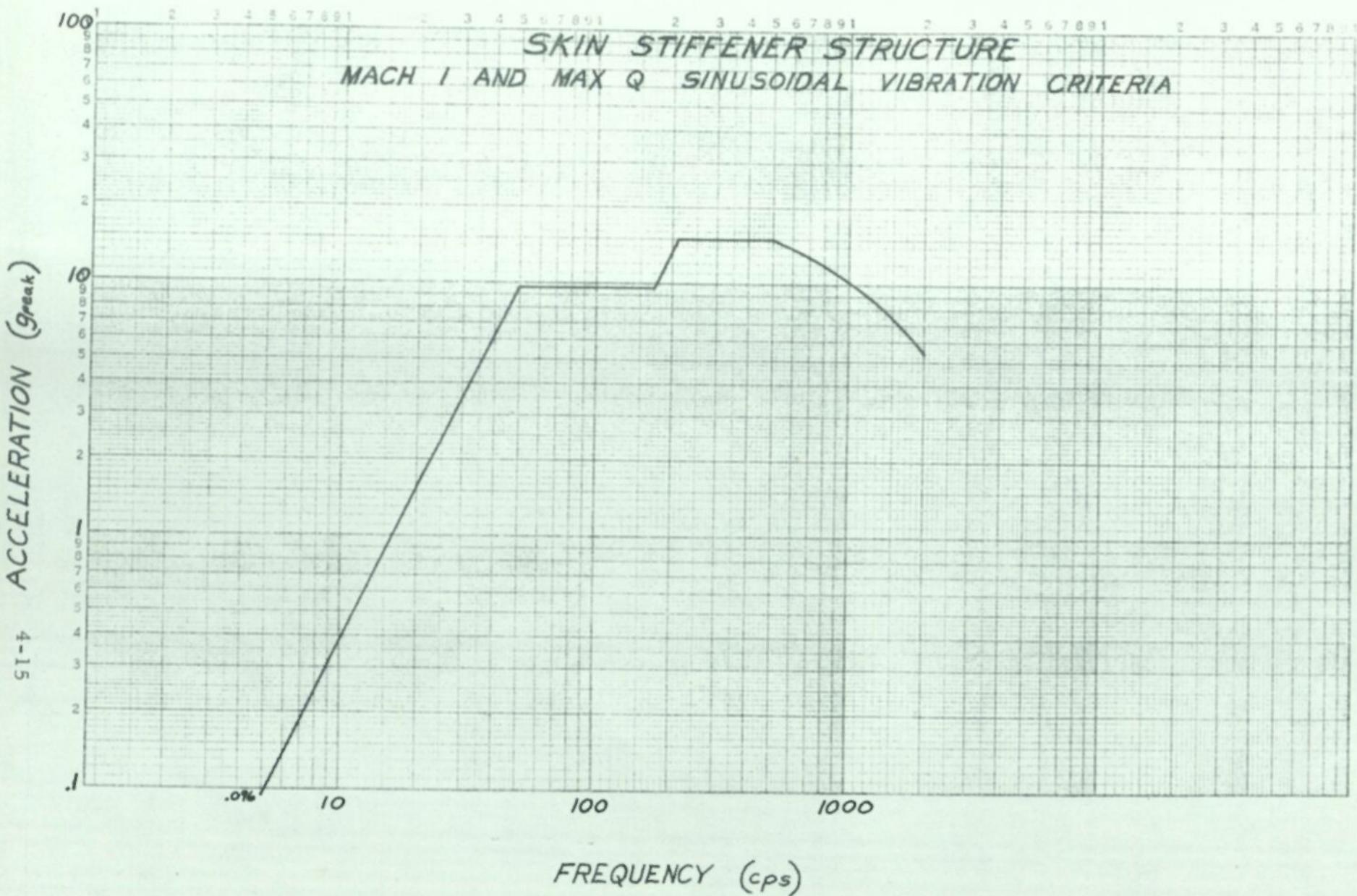


FIGURE 4.2-9

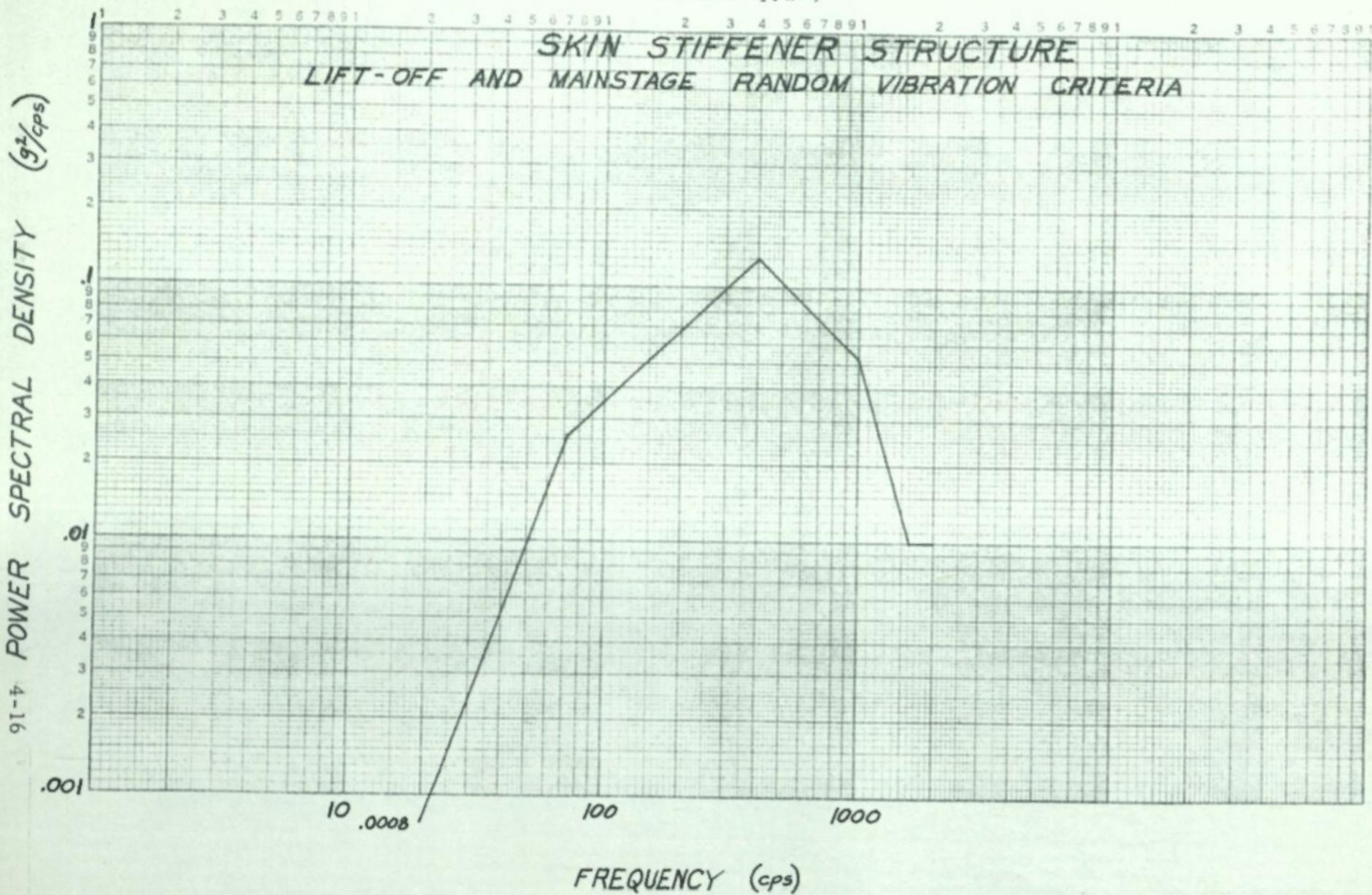
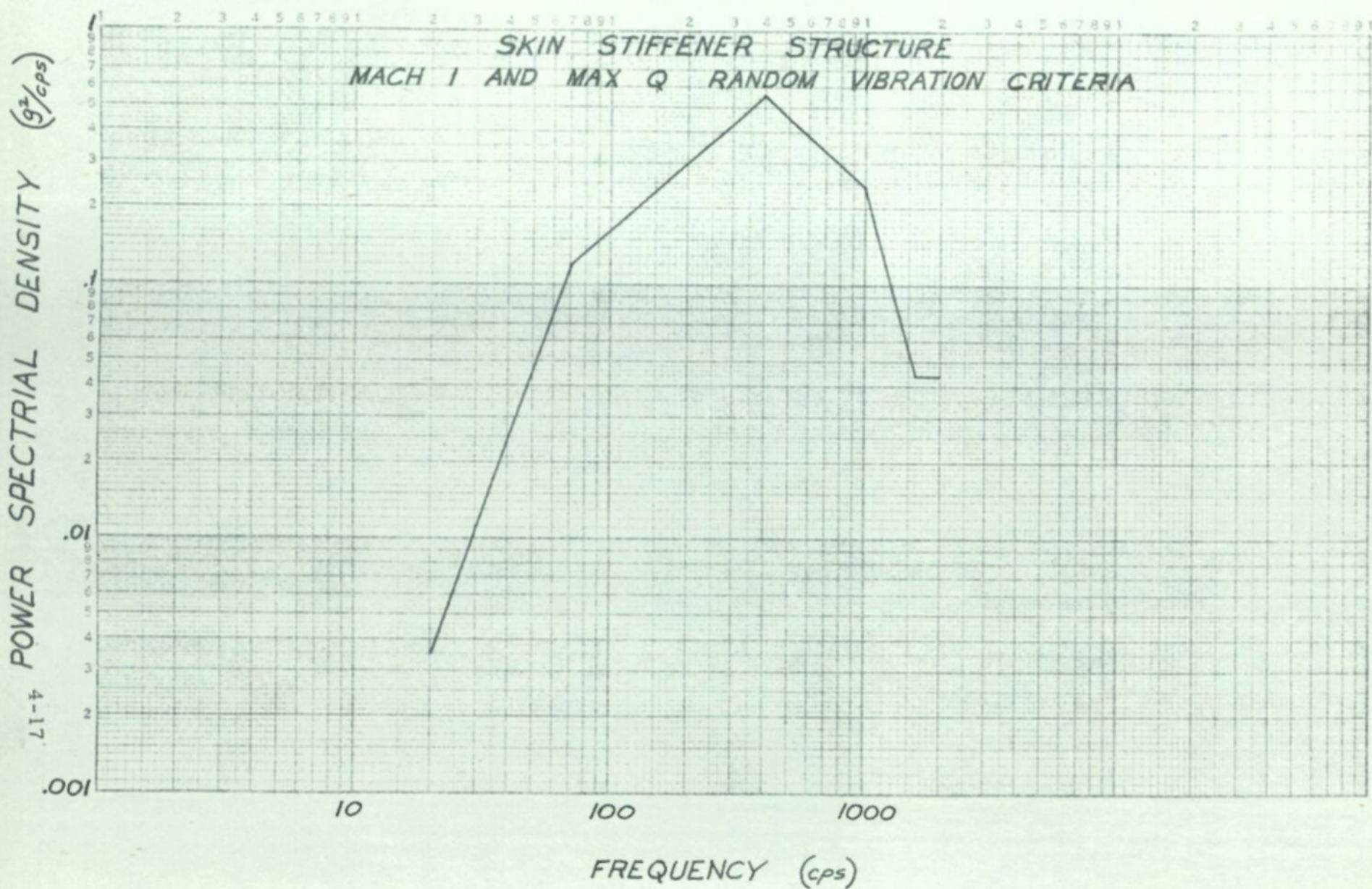
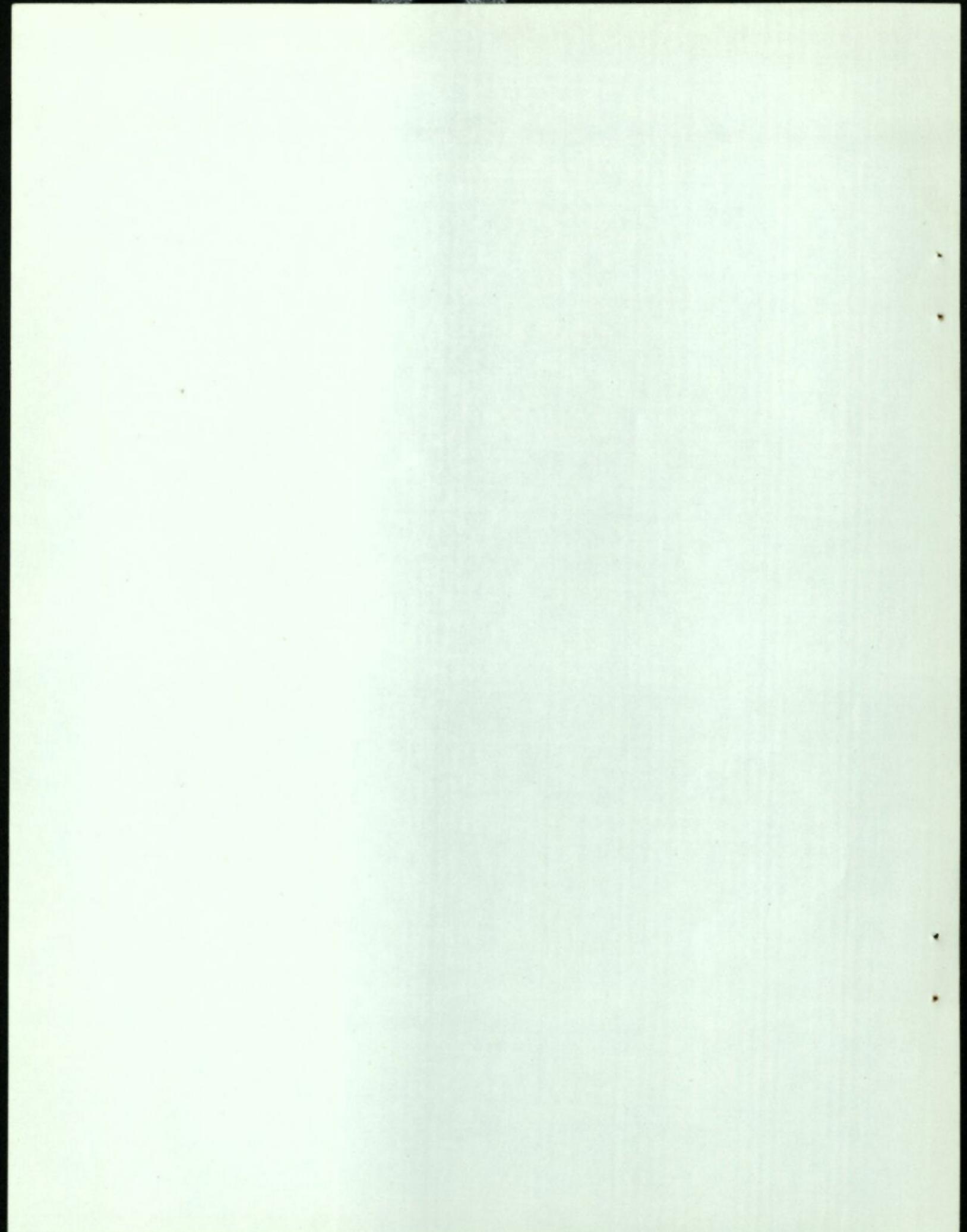


FIGURE 4.2-10





SECTION 5.0 ELECTRICAL SYSTEM SCHEMATICS

Preliminary schematics are provided here to further define the design and electrical system interfaces as presented in the proposal document. Figures 5.0-1 and -2 define the cable interconnect diagram for the entire electrical power system. Figures 5.0-3 through -19 are schematics outlining, in detail, interfaces of the electrical power distribution system. No provision has been included in this distribution system for corollary experiments.

Figure 5.0-1

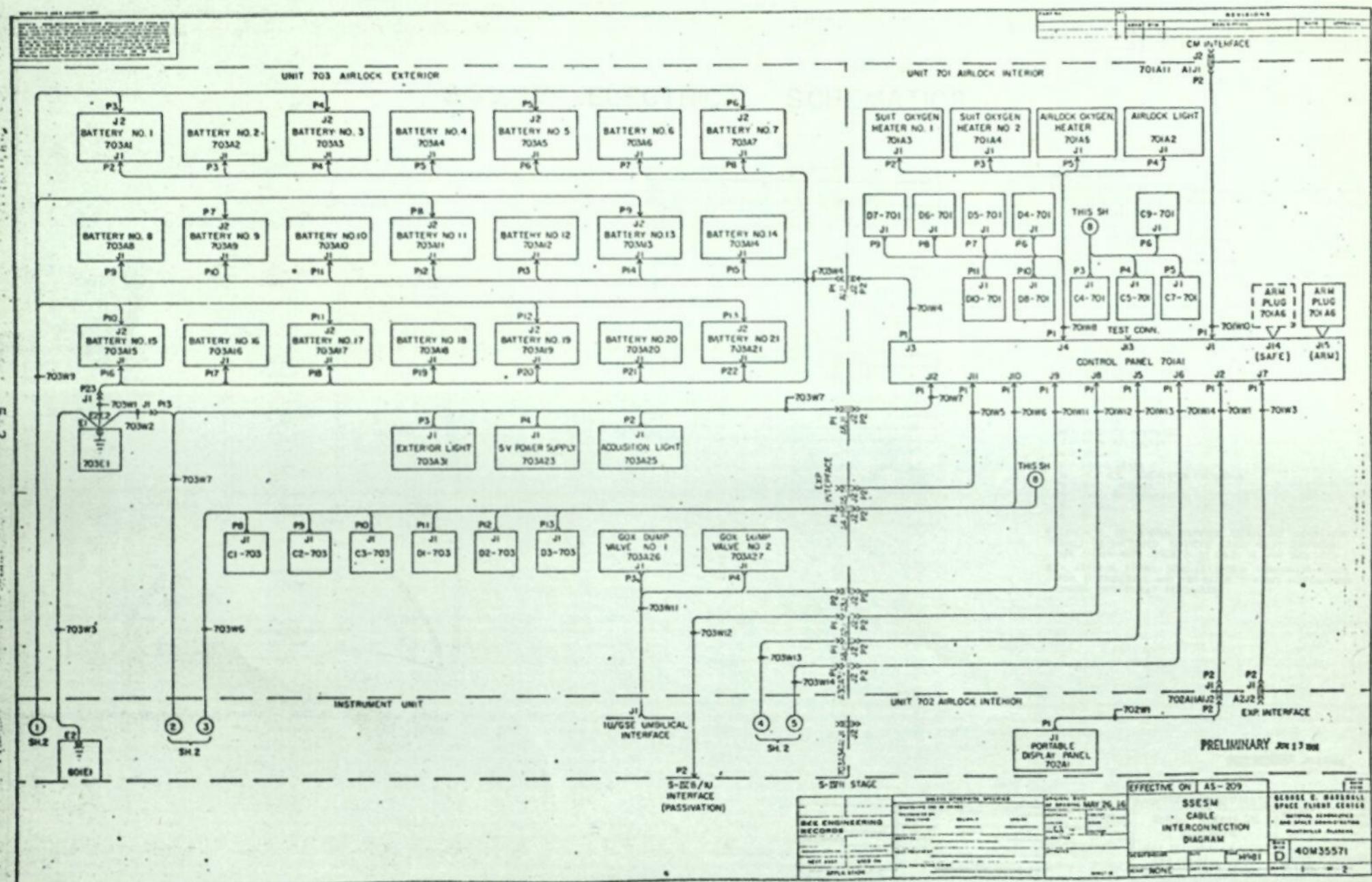


Figure 5.0-2

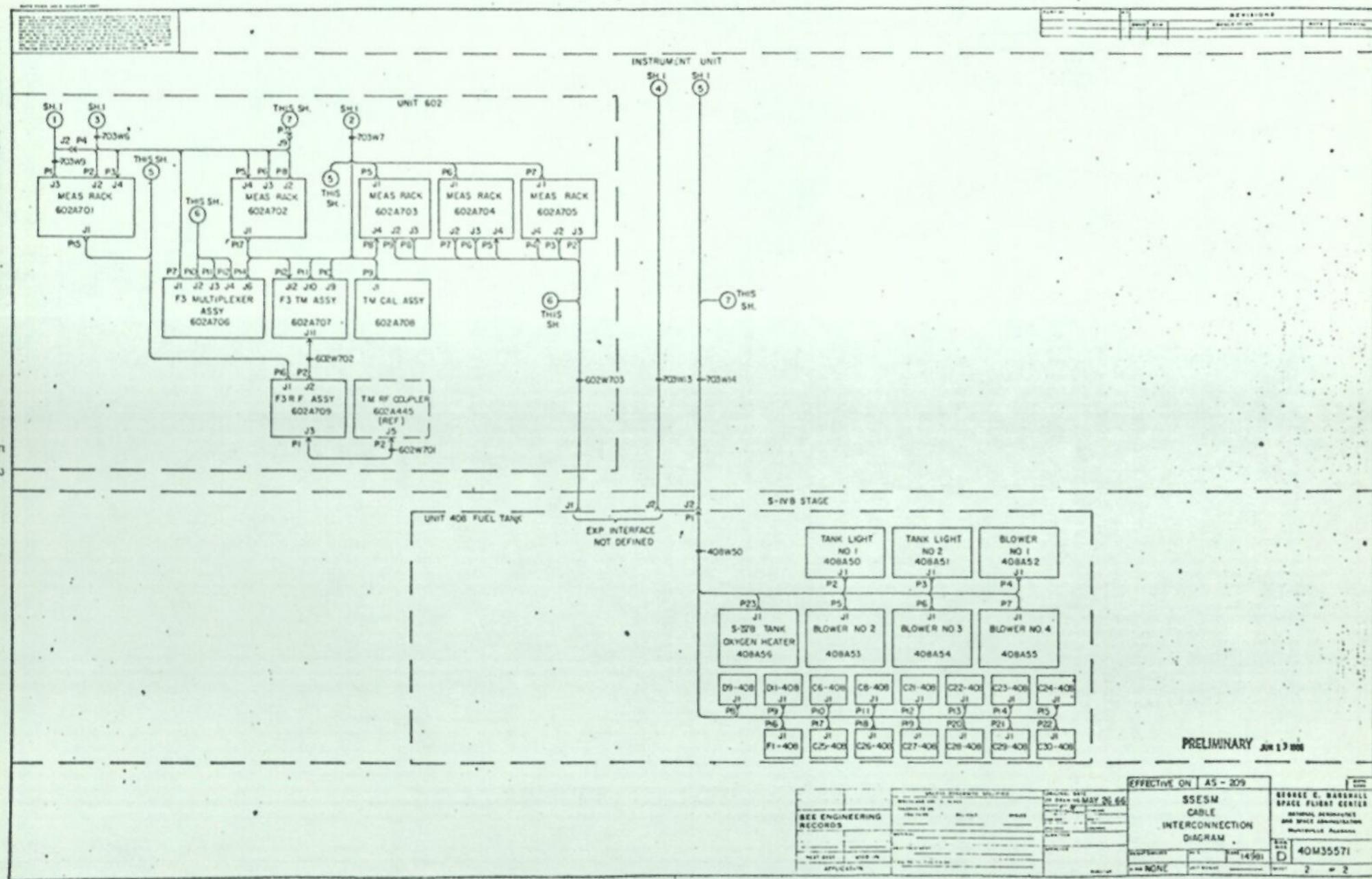
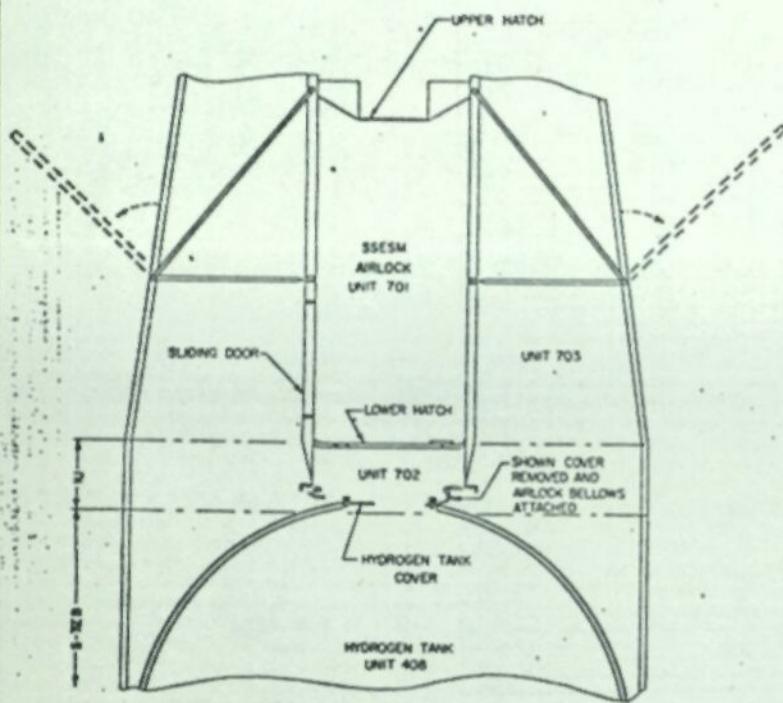


Figure 5.0-3

SSESMS ELECTRICAL SCHEMATICS



INDEX X	
SH	TITLE
1	UNIT DESIGNATIONS, INDEX & GENERAL NOTES
2	COMPONENT INDEX, CONTROL PANEL
3	COMPONENT INDEX, PORTABLE DISPLAY PANEL
4	POWER DISTRIBUTION
5	POWER DISTRIBUTION, CONTROL AND DISPLAY PANEL
6	POWER DISTRIBUTION
7	POWER DISTRIBUTION
8	SIX-THREE STAGE PASSIVATION SYSTEM
9	TELEMETRY POWER DISTRIBUTION
10	TELEMETRY POWER DISTRIBUTION
11	MEAS RACK LOCATOR CHANNELS 1-10
12	MEAS RACK LOCATOR CHANNELS 11-20
13	MEAS RACK LOCATOR CHANNELS 1-10
14	MEAS RACK LOCATOR CHANNELS 11-20
15	ECS PRESSURE MEASUREMENTS
16	EVENT MEASUREMENTS
17	CURRENT VOLTAGE AND EVENT MEASUREMENTS
18	
19	
20	

GENERAL NOTES

1. ELECTRICAL REFERENCE DESIGNATIONS ARE IN ACCORDANCE WITH MSFC-STD-349. THE UNIT DIVISION OF THE SSESIM IS SHOWN TO THE LEFT OF THIS SHEET.
 2. PARTIAL REFERENCE DESIGNATIONS ARE SHOWN WHERE THE APPROPRIATE UNITS, ASSEMBLIES, AND SUB-ASSEMBLIES ARE EVIDENT FOR COMPLETE REFERENCE DESIGNATION PREFIX WITH UNIT AND/OR ASSEMBLY DESIGNATION.
 3. EACH MEASUREMENT IS DENOTED BY A MEASUREMENT NUMBER AS LISTED IN THE INSTRUMENTATION PROGRAM AND COMPONENT LIST. THIS NUMBER IS COMPOSED OF A LETTER INDICATING THE PARAMETER MEASURED, ONE OR MORE DIGITS INDICATING THE SEQUENCE OF EACH MEASUREMENT OF A PARAMETER AND A DASH NUMBER INDICATING THE UNIT IN WHICH THE MEASUREMENT ORIGINATES.

THE PARAMETERS ARE DESIGNATED AS FOLLOWS:

 - A - ACCELERATION
 - B - ACOUSTICS
 - C - ^A TEMPERATURE
 - D - PRESSURE
 - E - VIBRATION
 - F - FLOW RATE
 - G - POSITION
 - H - GUIDANCE & CONTROL
 - J - RF & TELEMETRY
 - K - SIGNAL
 - L - LIQUID LEVEL
 - M - VOLTAGE, CURRENT & FREQUENCY
 - N - MISCELLANEOUS
 - R - ANGULAR VELOCITY
 - S - STRAIN
 - R - RPM
 4. CONTACTS OF GENERAL PURPOSE RELAYS ARE SHOWN WITH COILS DE-ENERGIZED. MAGNETIC LATCH RELAY CONTACTS ARE SHOWN WITH COILS 21-22 OR 21-19 LAST ENERGIZED.
 5. * ASTERISK SYMBOL DENOTES SHIELD TERMINATION POINTS FOR DISTRIBUTORS AND FOR CABLE SHIELDED WIRES UNLESS SHOWN INDIVIDUALLY TERMINATED.

PRELIMINARY Jan 13 2000

Figure 5.0-4

CONTROL PANEL TOAI						CONTROL PANEL TOAI						CONTROL PANEL TOAI						
RESISTOR DESIGN	POS NO	PURPOSE	SH NO	RATING W	TYPE OR DWG NO	RELAY DESIGN	POS NO	RELAY PURPOSE	CONTACTS AND CIRCUIT IDENTIFICATION	CONTACTS	CIRCUIT IDENTIFICATION	SWITCH DESIGN	PURPOSE	SH NO	TYPE OR DWG NO			
Z0A1R1		SHUNT	5			Z0A1R1		ENERGY/EVACUATION POWER BUS +700 VOLTAGE LOW	12 1-3 4-5 6-7 8-9 10-11 13-14 15-16 17-18 19-20	4	5	Z0A1S1	ECS TEMPERATURE SELECT	5				
Z0A1R2		SHUNT	5			Z0A1R2		ENERGY/EVACUATION POWER BUS +700 VOLTAGE LOW	12 1-3 4-5 6-7 8-9 10-11 13-14 15-16 17-18 19-20	4	5	Z0A1S2	ECS PRESSURE SELECT	5				
Z0A1R3		SHUNT	5			Z0A1R3		MEASUREMENT TRANSFER	10 10 10 10 10 10 15 15	-	-	Z0A1S3	BUS VOLTAGE MONITOR SELECT	5				
Z0A1R4		IMPEDANCE MATCHING	5			Z0A1R4		MEASUREMENT TRANSFER	15 15 15 15 17 17	-	-	Z0A1S4	BUS CURRENT SELECT +700/+720	5				
Z0A1R5		IMPEDANCE MATCHING	5			Z0A1R5		MEASUREMENT TRANSFER	17 17 17 17	-	-	Z0A1S5	BUS CURRENT SELECT +700/+720	5				
Z0A1R6		IMPEDANCE MATCHING	5			Z0A1R6		RF ASSISTANT INHIBIT	9	-	-	Z0A1S6	MATRIX SWITCHING EMER. POWER	5				
Z0A1R7		IMPEDANCE MATCHING	5			Z0A1R7		RF ASSISTANT INHIBIT	10 10 10 10 10 10 15 15	-	-	Z0A1S7	CDT VOLTAGE SET +700/+720	5				
Z0A1R8		IMPEDANCE MATCHING	5			Z0A1R8		IMPEDANCE MATCHING	5	-	-	Z0A1S8	+700 VOLTAGE SET +700/+720	5				
Z0A1R9		IMPEDANCE MATCHING	5			Z0A1R9		IMPEDANCE MATCHING	5	-	-	Z0A1S9	- PRIVATE PASSIVATION COMPONENTS	5				
Z0A1R10		VOLTAGE UV IR	17			Z0A1R10		IMPEDANCE MATCHING	5	-	-	Z0A1S10	- PRIVATE PASSIVATION COMPONENTS	5				
Z0A1R11		VOLTAGE UV IR	17			Z0A1R11		ACQUISITION LIGHT INHIBIT	9	-	-	Z0A1S11	ACTIVITY PASSIVATION COMPONENTS	5				
Z0A1R12		VOLTAGE UV IR	17			Z0A1R12		ACQUISITION LIGHT INHIBIT	10 10 10 10 10 10 15 15	-	-	Z0A1S12	ACTIVITY PASSIVATION COMPONENTS	5				
Z0A1R13		VOLTAGE UV IR	17			Z0A1R13		VOLTAGE UV IR	17	-	-	Z0A1S13	CMO - CALIBRATION/POWER	5				
Z0A1R14		VOLTAGE UV IR	17			Z0A1R14		VOLTAGE UV IR	17	-	-							
Z0A1R15		VOLTAGE UV IR	17			Z0A1R15		VOLTAGE UV IR	17	-	-							
Z0A1R16		VOLTAGE UV IR	17			Z0A1R16		VOLTAGE UV IR	17	-	-							
Z0A1R17		VOLTAGE UV IR	17			Z0A1R17		VOLTAGE UV IR	17	-	-							
Z0A1R18		VOLTAGE UV IR	17			Z0A1R18		VOLTAGE UV IR	17	-	-							
Z0A1R19		VOLTAGE UV IR	17			Z0A1R19		VOLTAGE UV IR	17	-	-							
Z0A1R20		VOLTAGE UV IR	17			Z0A1R20		VOLTAGE UV IR	17	-	-							
Z0A1R21		VOLTAGE UV IR	17			Z0A1R21		VOLTAGE UV IR	17	-	-							
Z0A1R22		VOLTAGE UV IR	17			Z0A1R22		VOLTAGE UV IR	17	-	-							
Z0A1R23		VOLTAGE UV IR	17			Z0A1R23		VOLTAGE UV IR	17	-	-							
Z0A1R24		VOLTAGE UV IR	17			Z0A1R24		VOLTAGE UV IR	17	-	-							
Z0A1R25		VOLTAGE UV IR	17			Z0A1R25		VOLTAGE UV IR	17	-	-							
Z0A1R26		VOLTAGE UV IR	17			Z0A1R26		VOLTAGE UV IR	17	-	-							
Z0A1R27		VOLTAGE UV IR	17			Z0A1R27		VOLTAGE UV IR	17	-	-							
Z0A1R28		VOLTAGE UV IR	17			Z0A1R28		VOLTAGE UV IR	17	-	-							
Z0A1R29		VOLTAGE UV IR	17			Z0A1R29		VOLTAGE UV IR	17	-	-							
Z0A1R30		VOLTAGE UV IR	17			Z0A1R30		VOLTAGE UV IR	17	-	-							
Z0A1R31		VOLTAGE UV IR	17			Z0A1R31		VOLTAGE UV IR	17	-	-							
Z0A1R32		VOLTAGE UV IR	17			Z0A1R32		VOLTAGE UV IR	17	-	-							
Z0A1R33		VOLTAGE UV IR	17			Z0A1R33		VOLTAGE UV IR	17	-	-							
Z0A1R34		VOLTAGE UV IR	17			Z0A1R34		VOLTAGE UV IR	17	-	-							
Z0A1R35		VOLTAGE UV IR	17			Z0A1R35		VOLTAGE UV IR	17	-	-							
Z0A1R36		VOLTAGE UV IR	17			Z0A1R36		VOLTAGE UV IR	17	-	-							
Z0A1R37		VOLTAGE UV IR	17			Z0A1R37		VOLTAGE UV IR	17	-	-							
Z0A1R38		VOLTAGE UV IR	17			Z0A1R38		VOLTAGE UV IR	17	-	-							
Z0A1R39		VOLTAGE UV IR	17			Z0A1R39		VOLTAGE UV IR	17	-	-							
Z0A1R40		VOLTAGE UV IR	17			Z0A1R40		VOLTAGE UV IR	17	-	-							
Z0A1R41		VOLTAGE UV IR	17			Z0A1R41		VOLTAGE UV IR	17	-	-							
Z0A1R42		VOLTAGE UV IR	17			Z0A1R42		VOLTAGE UV IR	17	-	-							
Z0A1R43		VOLTAGE UV IR	17			Z0A1R43		VOLTAGE UV IR	17	-	-							
Z0A1R44		VOLTAGE UV IR	17			Z0A1R44		VOLTAGE UV IR	17	-	-							
Z0A1R45		VOLTAGE UV IR	17			Z0A1R45		VOLTAGE UV IR	17	-	-							
Z0A1R46		VOLTAGE UV IR	17			Z0A1R46		VOLTAGE UV IR	17	-	-							
Z0A1R47		VOLTAGE UV IR	17			Z0A1R47		VOLTAGE UV IR	17	-	-							
Z0A1R48		VOLTAGE UV IR	17			Z0A1R48		VOLTAGE UV IR	17	-	-							
CONTROL PANEL TOAI						CONTROL PANEL TOAI						CONTROL PANEL TOAI						
DIOD DESIGN	PURPOSE	SH NO	RATING AMP	TYPE OR DWG NO		LAMP DESIGN	PURPOSE	SH NO	TYPE OR DWG NO			DIODE DESIGN	PURPOSE	SH NO	TYPE OR DWG NO			
Z0A1C1	EXTERIOR LIGHT +700 POWER	6			Z0A1L1	INDICATION +700 VOLTAGE LOW	5		Z0A1C2	BLOCKING	6		Z0A1C3	BLOCKING	6			
Z0A1C2	ACQUISITION LIGHT +700 POWER	6			Z0A1L2	INDICATION +700 VOLTAGE LOW	5		Z0A1C4	BLOCKING	6		Z0A1C5	BLOCKING	6			
Z0A1C3	ACQUISITION LIGHT +700 POWER	6			Z0A1L3	INDICATION EMERGENCY POWER ON	5		Z0A1C6	BLOCKING	6		Z0A1C7	BLOCKING	6			
Z0A1C4	TANK LIGHT #1 +700 POWER	6			Z0A1L4	INDICATION PASSIVATION READY +700	5		Z0A1C8	BLOCKING	6		Z0A1C9	BLOCKING	6			
Z0A1C5	TANK LIGHT #2 +700 POWER	6			Z0A1L5	INDICATION PASSIVATION READY +700	5		Z0A1C10	BLOCKING	6		Z0A1C11	BLOCKING	6			
Z0A1C6	TANK LIGHT #3 +700 POWER	6			Z0A1L6	INDICATION PASSIVATION READY +700	5		Z0A1C12	BLOCKING	6		Z0A1C13	BLOCKING	6			
Z0A1C7	TANK LIGHT #4 +700 POWER	6			Z0A1L7	INDICATION PASSIVATION READY +700	5		Z0A1C14	BLOCKING	6		Z0A1C15	BLOCKING	6			
Z0A1C8	TANK LIGHT #5 +700 POWER	6			Z0A1L8	INDICATION PASSIVATION READY +700	5		Z0A1C16	BLOCKING	6		Z0A1C17	BLOCKING	6			
Z0A1C9	TANK LIGHT #6 +700 POWER	6			Z0A1L9	INDICATION PASSIVATION READY +700	5		Z0A1C18	BLOCKING	6		Z0A1C19	BLOCKING	6			
Z0A1C10	TANK LIGHT #7 +700 POWER	6			Z0A1L10	INDICATION PASSIVATION READY +700	5		Z0A1C20	BLOCKING	6		Z0A1C21	BLOCKING	6			
Z0A1C11	TANK LIGHT #8 +700 POWER	6			Z0A1L11	INDICATION PASSIVATION READY +700	5		Z0A1C22	BLOCKING	6		Z0A1C23	BLOCKING	6			
Z0A1C12	TANK LIGHT #9 +700 POWER	6			Z0A1L12	INDICATION PASSIVATION READY +700	5		Z0A1C24	BLOCKING	6		Z0A1C25	BLOCKING	6			
Z0A1C13	TANK LIGHT #10 +700 POWER	6			Z0A1L13	INDICATION PASSIVATION READY +700	5		Z0A1C26	BLOCKING	6		Z0A1C27	BLOCKING	6			
Z0A1C14	TANK LIGHT #11 +700 POWER	6			Z0A1L14	INDICATION PASSIVATION READY +700	5		Z0A1C28	BLOCKING	6		Z0A1C29	BLOCKING	6			
Z0A1C15	TANK LIGHT #12 +700 POWER	6			Z0A1L15	INDICATION PASSIVATION READY +700	5		Z0A1C30	BLOCKING	6		Z0A1C31	BLOCKING	6			
Z0A1C16	TANK LIGHT #13 +700 POWER	6			Z0A1L16	INDICATION PASSIVATION READY +700	5		Z0A1C32	BLOCKING	6		Z0A1C33	BLOCKING	6			
Z0A1C17	TANK LIGHT #14 +700 POWER	6			Z0A1L17	INDICATION PASSIVATION READY +700	5		Z0A1C34	BLOCKING	6		Z0A1C35	BLOCKING	6			
Z0A1C18	TANK LIGHT #15 +700 POWER	6			Z0A1L18	INDICATION PASSIVATION READY +700	5		Z0A1C36	BLOCKING	6		Z0A1C37	BLOCKING	6			
Z0A1C19	TANK LIGHT #16 +700 POWER	6			Z0A1L19	INDICATION PASSIVATION READY +700	5		Z0A1C38	BLOCKING	6		Z0A1C39	BLOCKING	6			
Z0A1C20	TANK LIGHT #17 +700 POWER	6			Z0A1L20	INDICATION PASSIVATION READY +700	5		Z0A1C40	BLOCKING	6		Z0A1C41	BLOCKING	6			
Z0A1C21	TANK LIGHT #18 +700 POWER	6			Z0A1L21	INDICATION PASSIVATION READY +700	5		Z0A1C42	BLOCKING	6		Z0A1C43	BLOCKING	6			
Z0A1C22	TANK LIGHT #19 +700 POWER	6			Z0A1L22	INDICATION PASSIVATION READY +700	5		Z0A1C44	BLOCKING	6		Z0A1C45	BLOCKING	6			
Z0A1C23	TANK LIGHT #20 +700 POWER	6			Z0A1L23	INDICATION PASSIVATION READY +700	5		Z0A1C46	BLOCKING	6		Z0A1C47	BLOCKING	6			
Z0A1C24	TANK LIGHT #21 +700 POWER	6			Z0A1L24	INDICATION PASSIVATION READY +700	5		Z0A1C48	BLOCKING	6		Z0A1C49	BLOCKING	6			
Z0A1C25	TANK LIGHT #22 +700 POWER	6			Z0A1L25	INDICATION PASSIVATION READY +700	5		Z0A1C50	BLOCKING	6		Z0A1C51	BLOCKING	6			
Z0A1C26	TANK LIGHT #23 +700 POWER	6			Z0A1L26	INDICATION PASSIVATION READY +700	5		Z0A1C52	BLOCKING	6		Z0A1C53	BLOCKING	6			
Z0A1C27	TANK LIGHT #24 +700 POWER	6			Z0A1L27	INDICATION PASSIVATION READY +700	5		Z0A1C54	BLOCKING	6		Z0A1C55	BLOCKING	6			
Z0A1C28	TANK LIGHT #25 +700 POWER	6			Z0A1L28	INDICATION PASSIVATION READY +700	5		Z0A1C56	BLOCKING	6		Z0A1C57	BLOCKING	6			
Z0A1C29	TANK LIGHT #26 +700 POWER	6			Z0A1L29	INDICATION PASSIVATION READY +700	5		Z0A1C58	BLOCKING	6		Z0A1C59	BLOCKING	6			
Z0A1C30	TANK LIGHT #27 +700 POWER	6			Z0A1L30	INDICATION PASSIVATION READY +700	5		Z0A1C60	BLOCKING	6		Z0A1C61	BLOCKING	6			
Z0A1C31	TANK LIGHT #28 +700 POWER	6			Z0A1L31	INDICATION PASSIVATION READY +700	5		Z0A1C62	BLOCKING	6		Z0A1C63	BLOCKING	6			
Z0A1C32	TANK LIGHT #29 +700 POWER	6			Z0A1L32	INDICATION PASSIVATION READY +700	5		Z0A1C64	BLOCKING	6		Z0A1C65	BLOCKING	6			
Z0A1C33	TANK LIGHT #30 +700 POWER	6			Z0A1L33	INDICATION PASSIVATION READY +700	5		Z0A1C66	BLOCKING	6		Z0A1C67	BLOCKING	6			
Z0A1C34	TANK LIGHT #31 +700 POWER	6		</														

Figure 5.0-5

Figure 5.0-6

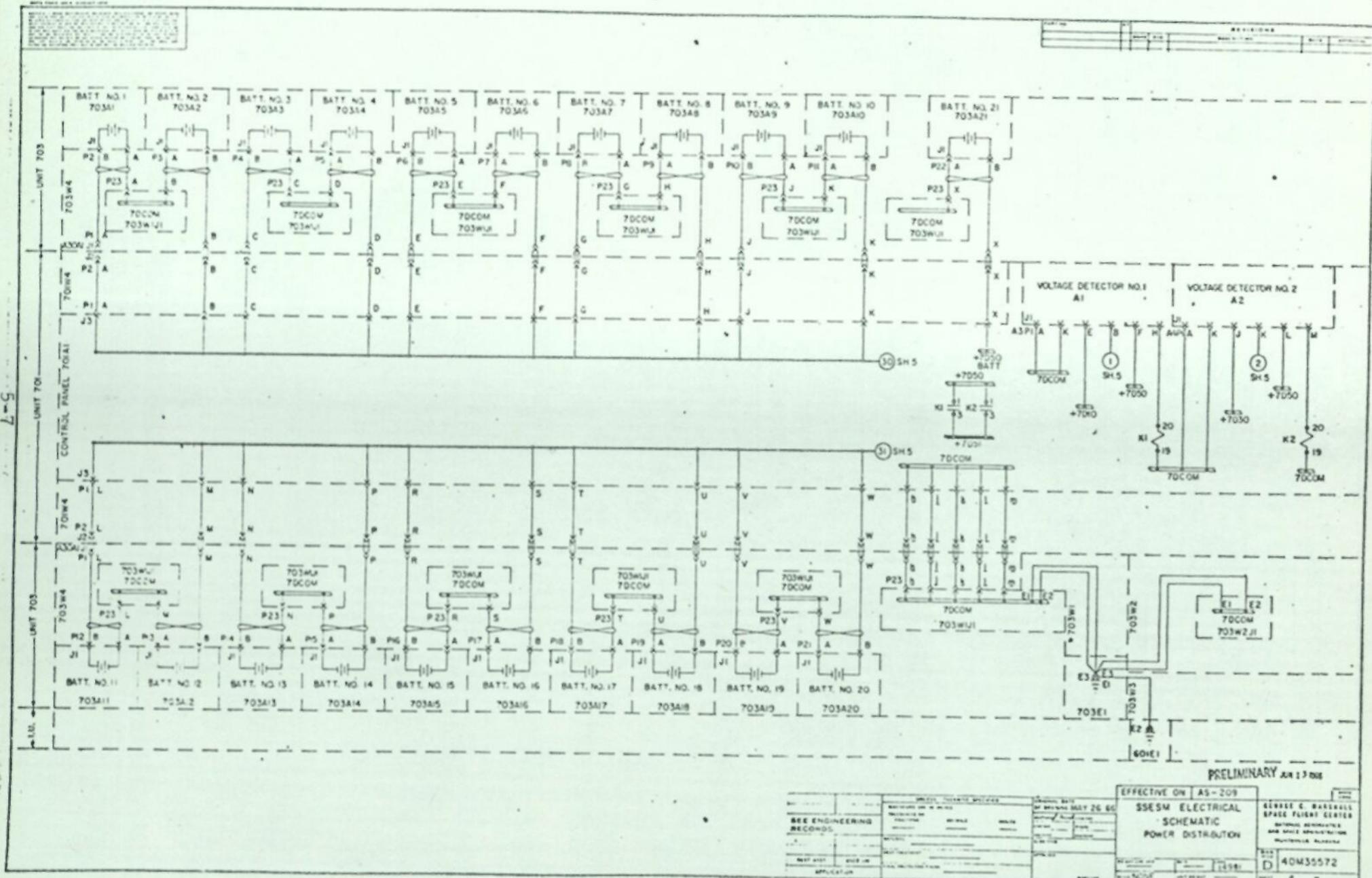


Figure 5.0-7

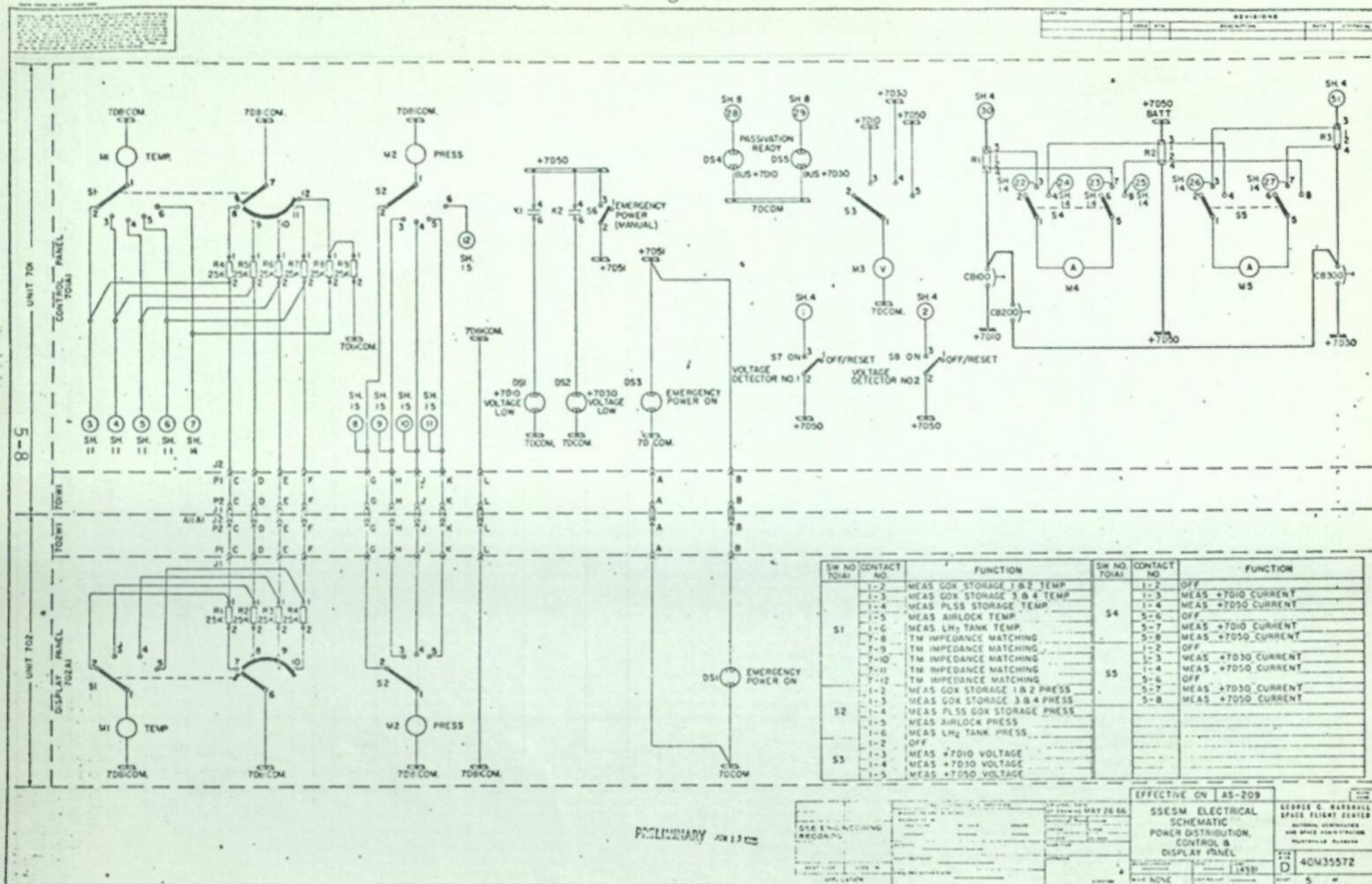


Figure 5.0-8

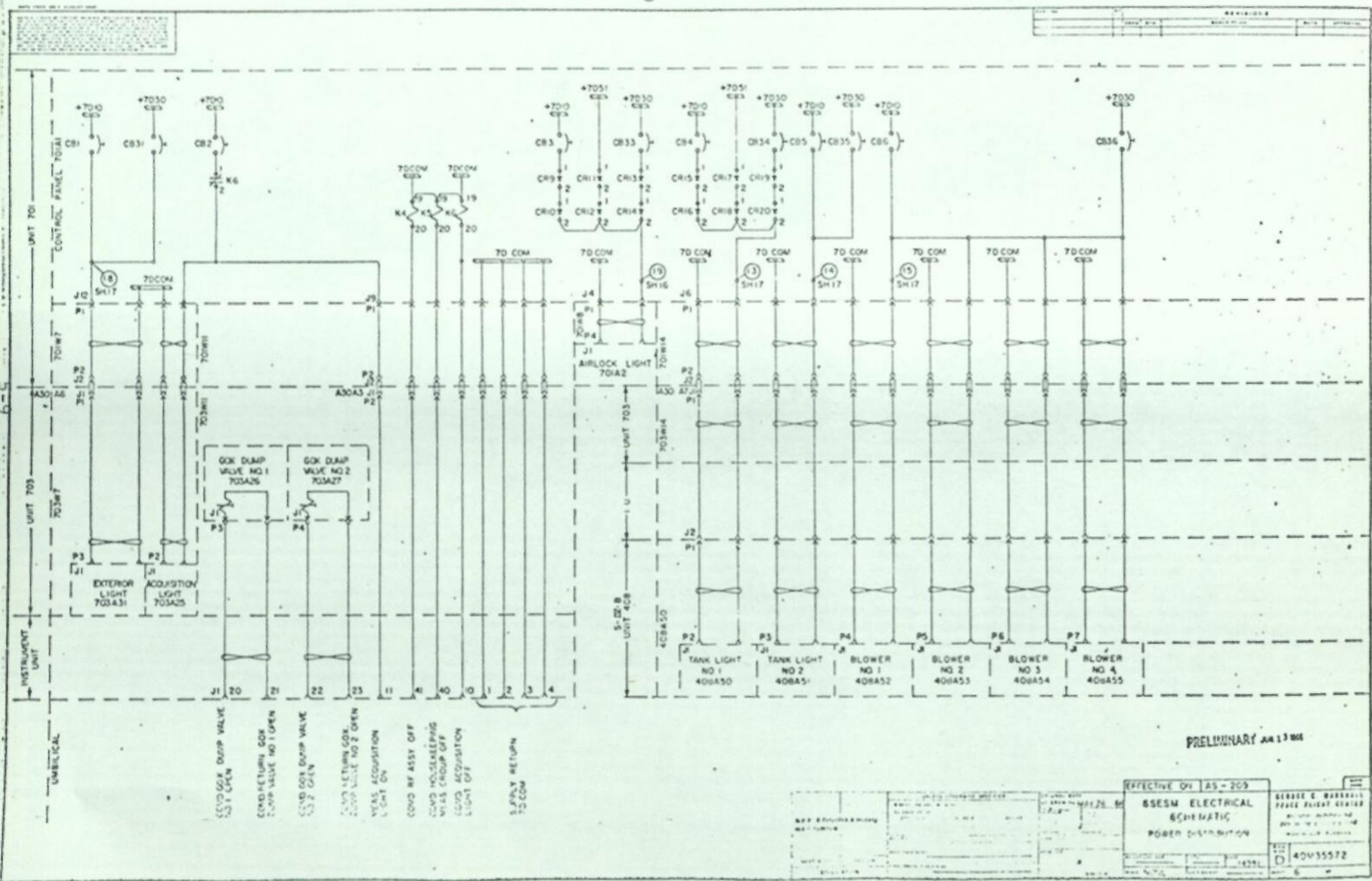


Figure 5.0-9

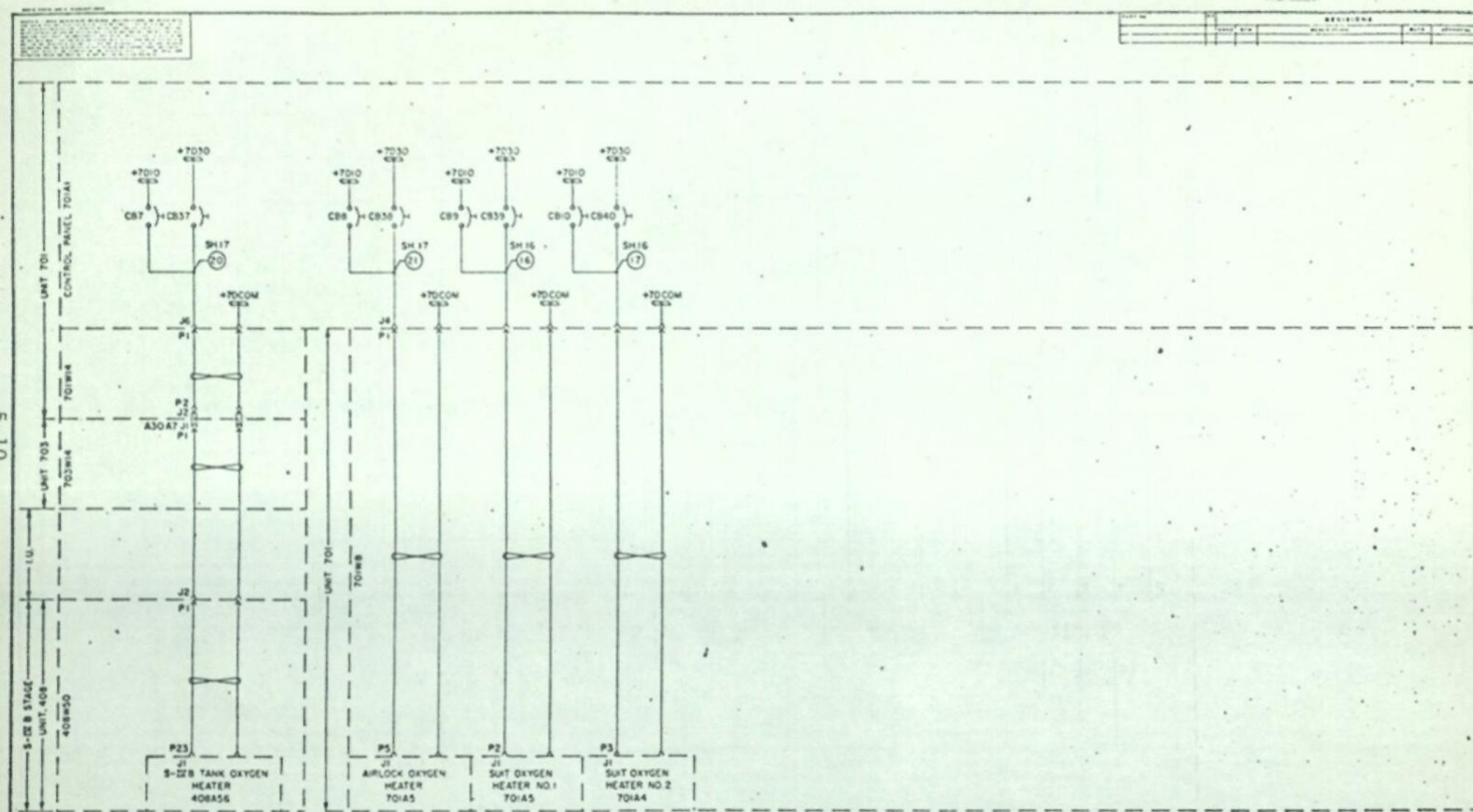
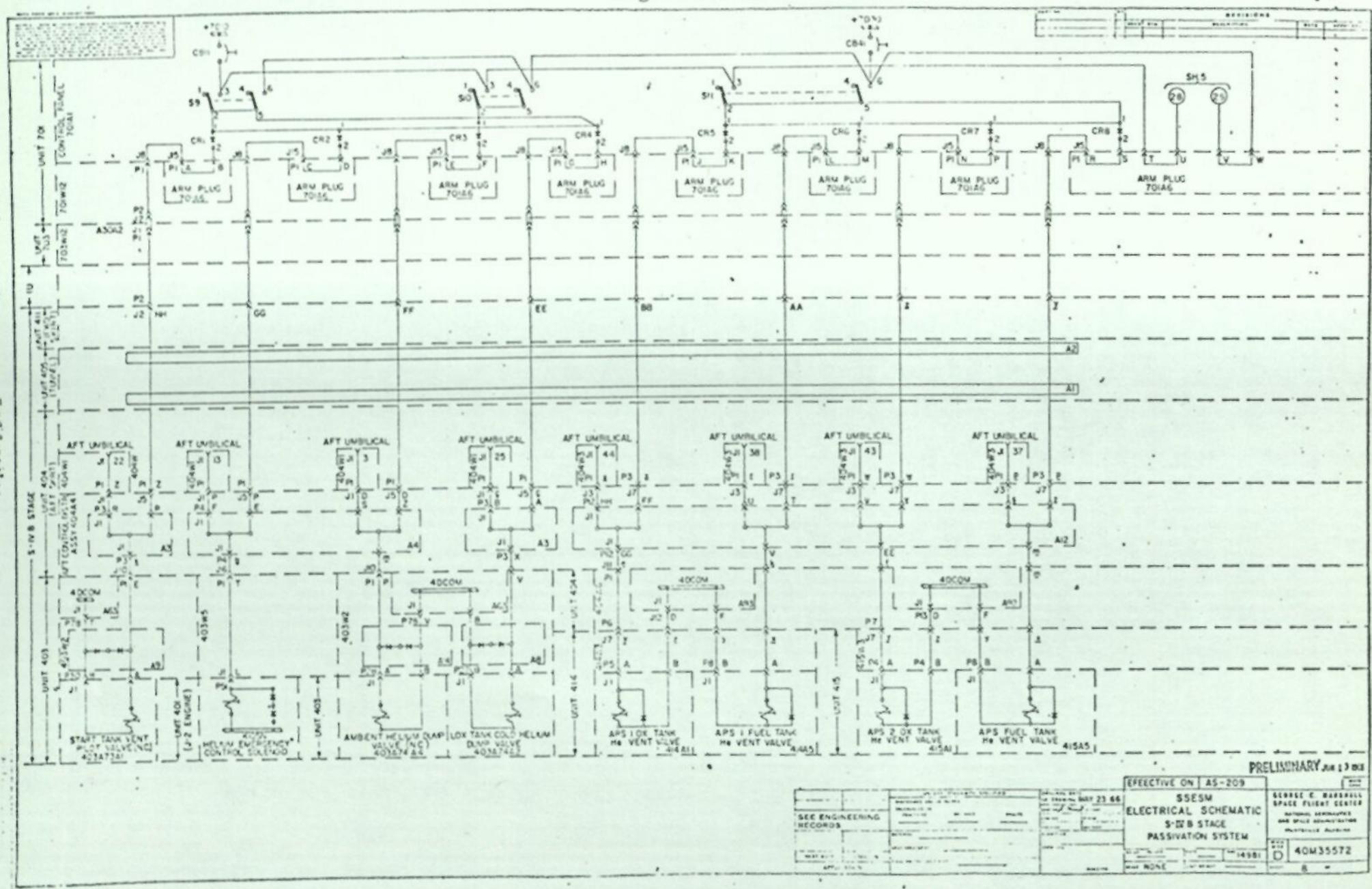


Figure 5.0-10



EFFECTIVE ON AS-209		PRELIMINARY JUN 13 1966	
SEE ENGINEERING RECORDS		GEORGE E. BARRELL SPACE FLIGHT CENTER NATIONAL AERONAUTICS AND SPACE ADMINISTRATION MOSCOW, RUSSIA	
40M35572		40M35572	

Figure 5.0-11

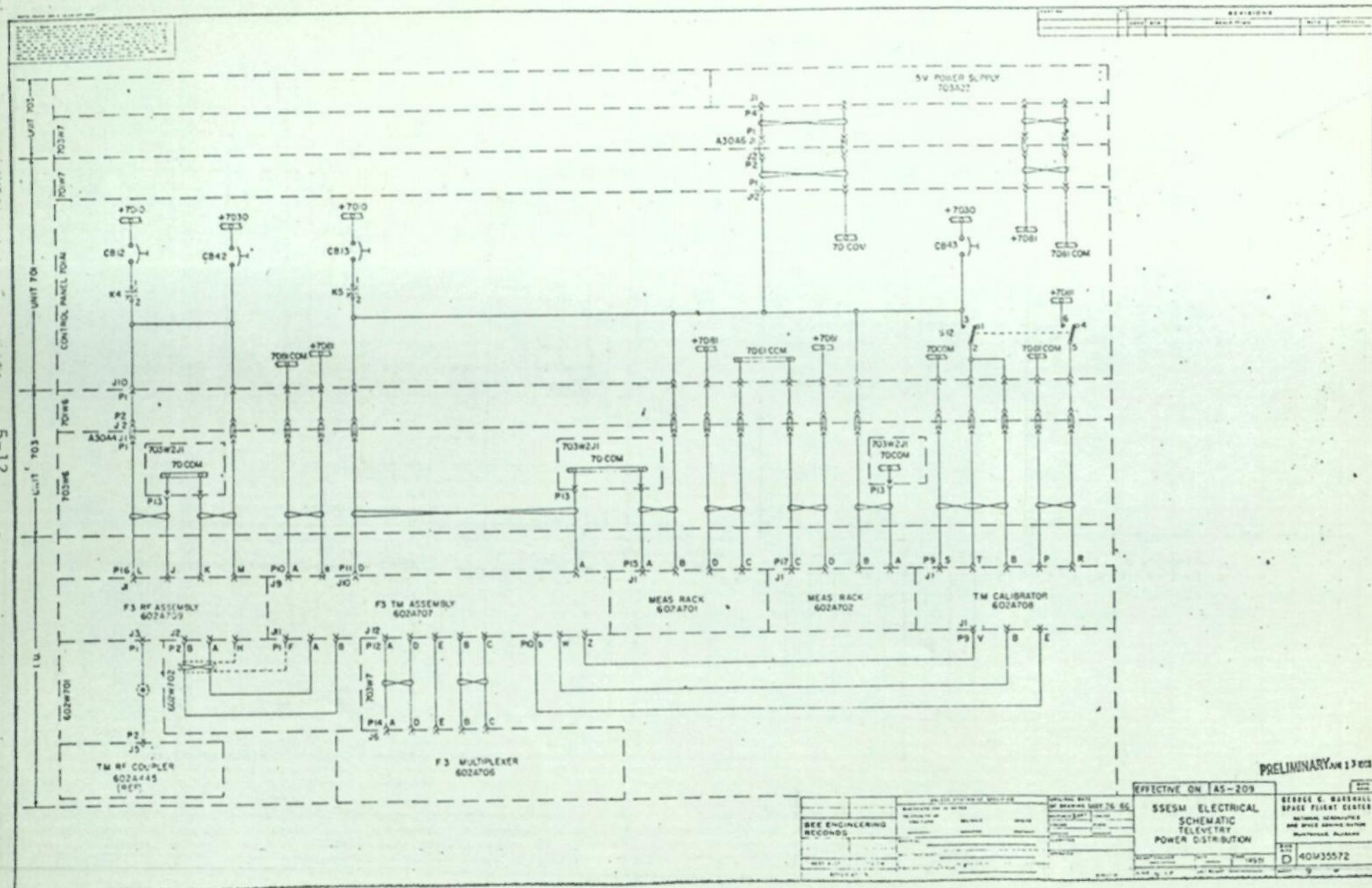


Figure 5.0-12

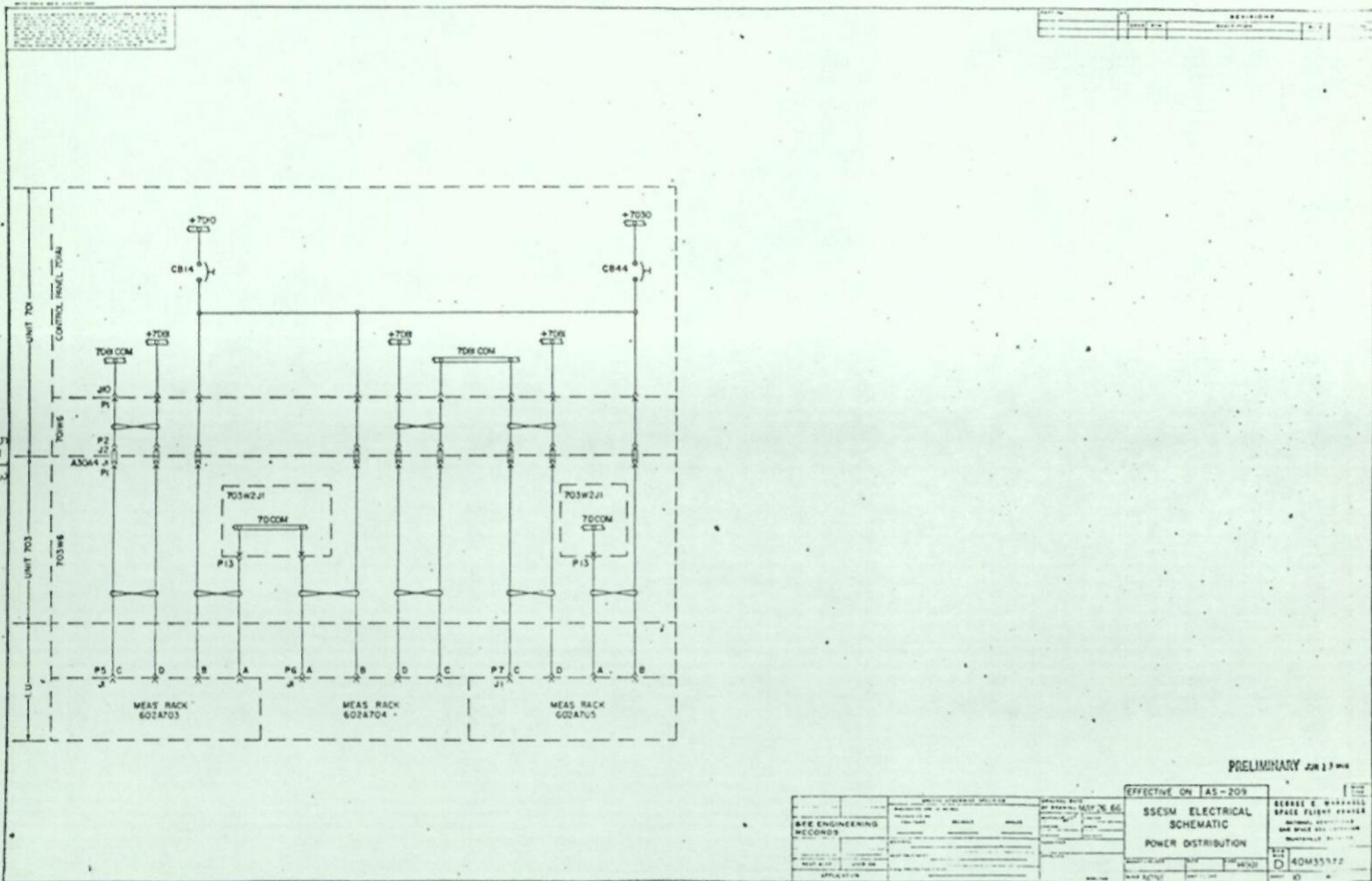


Figure 5.0-13

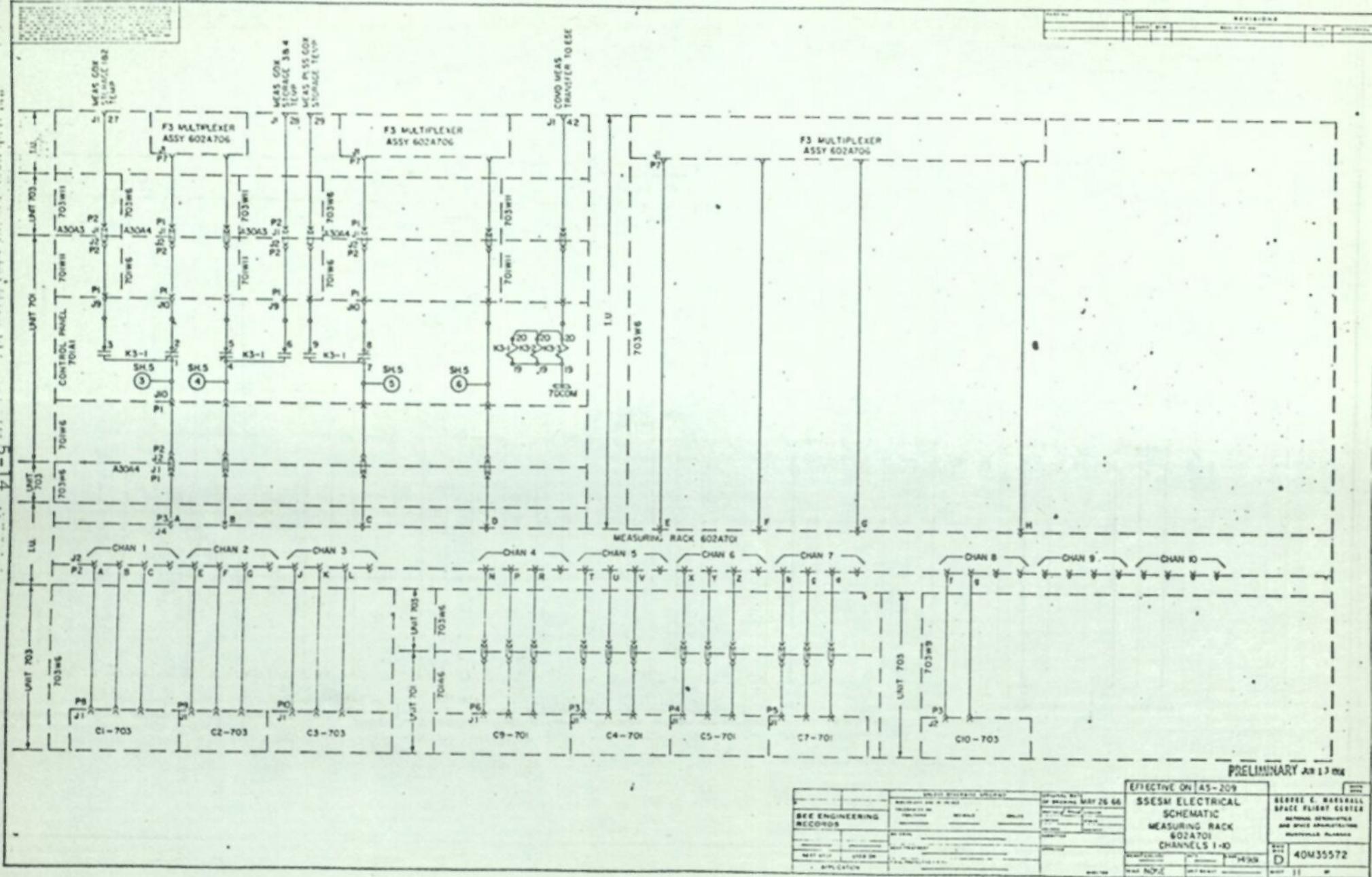


Figure 5.0-14

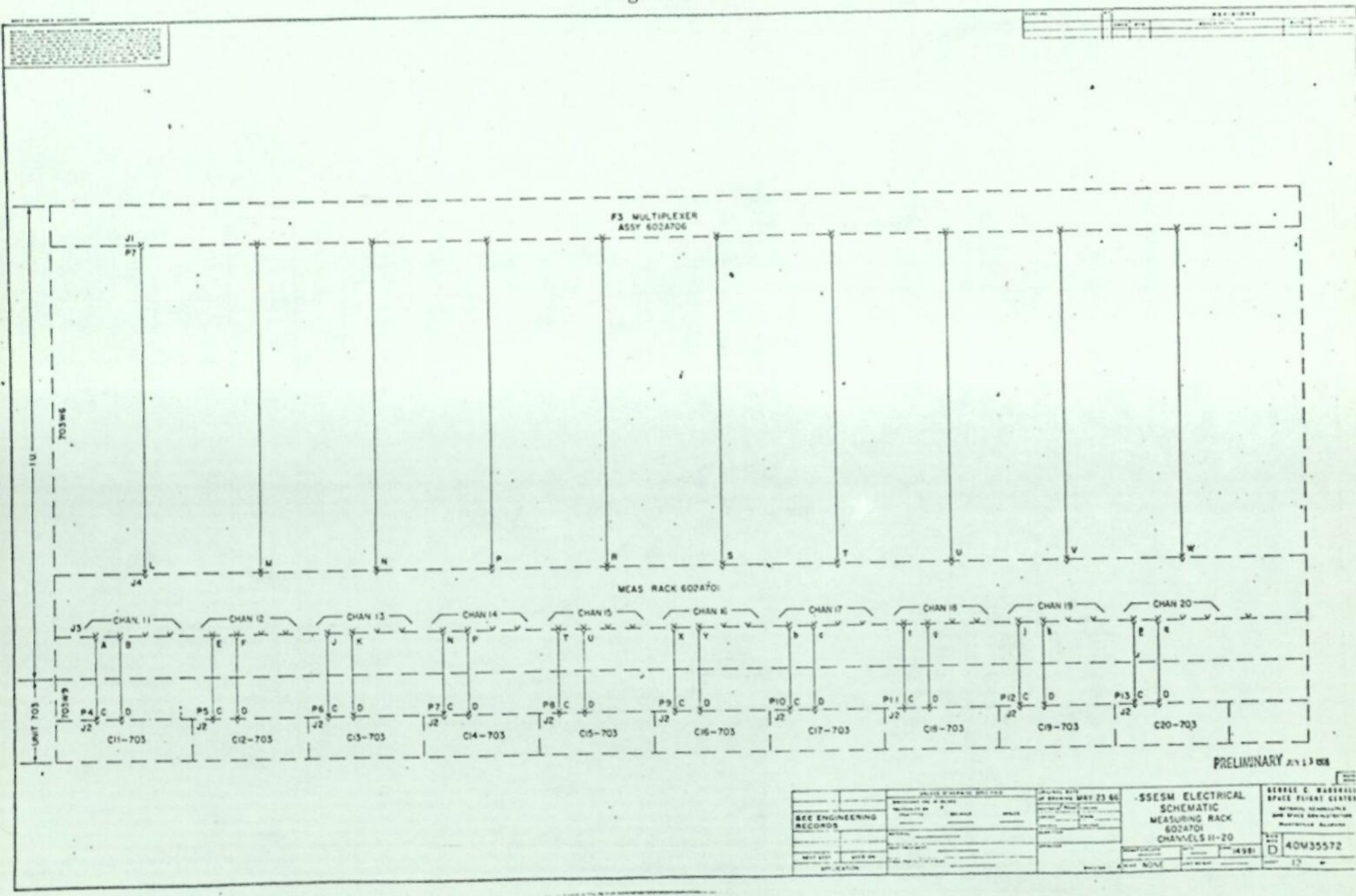


Figure 5.0-15

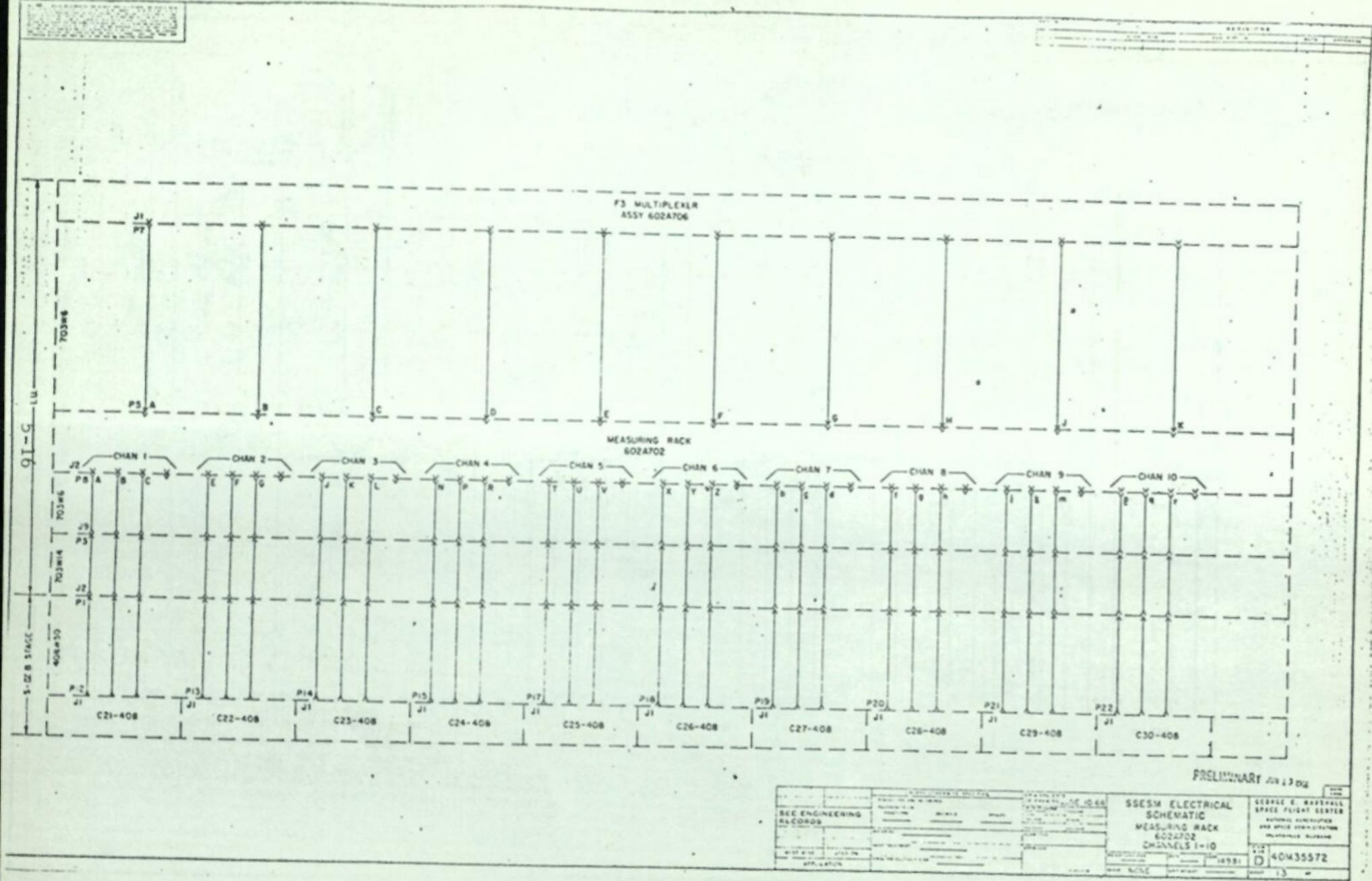


Figure 5.0-16

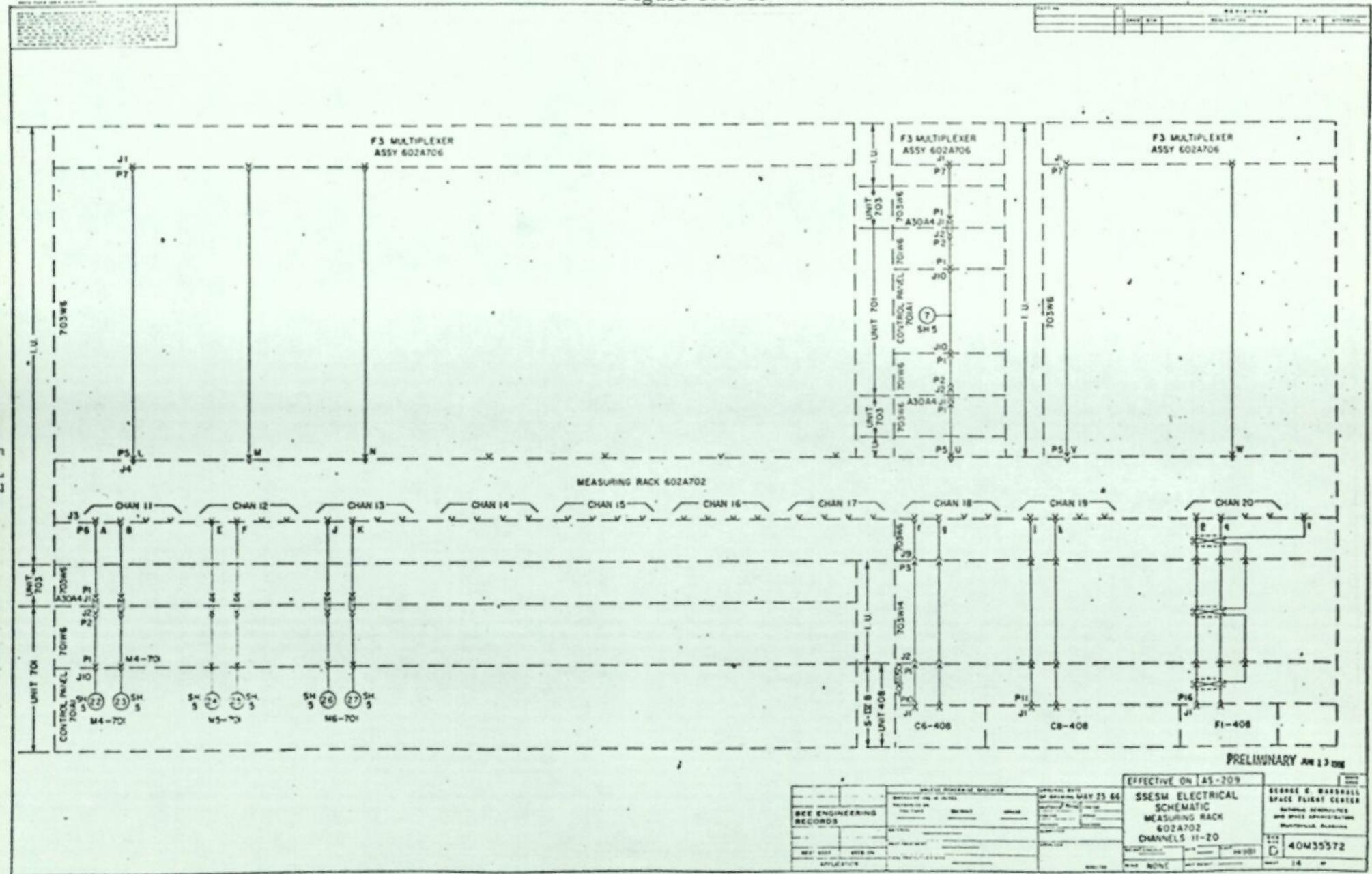
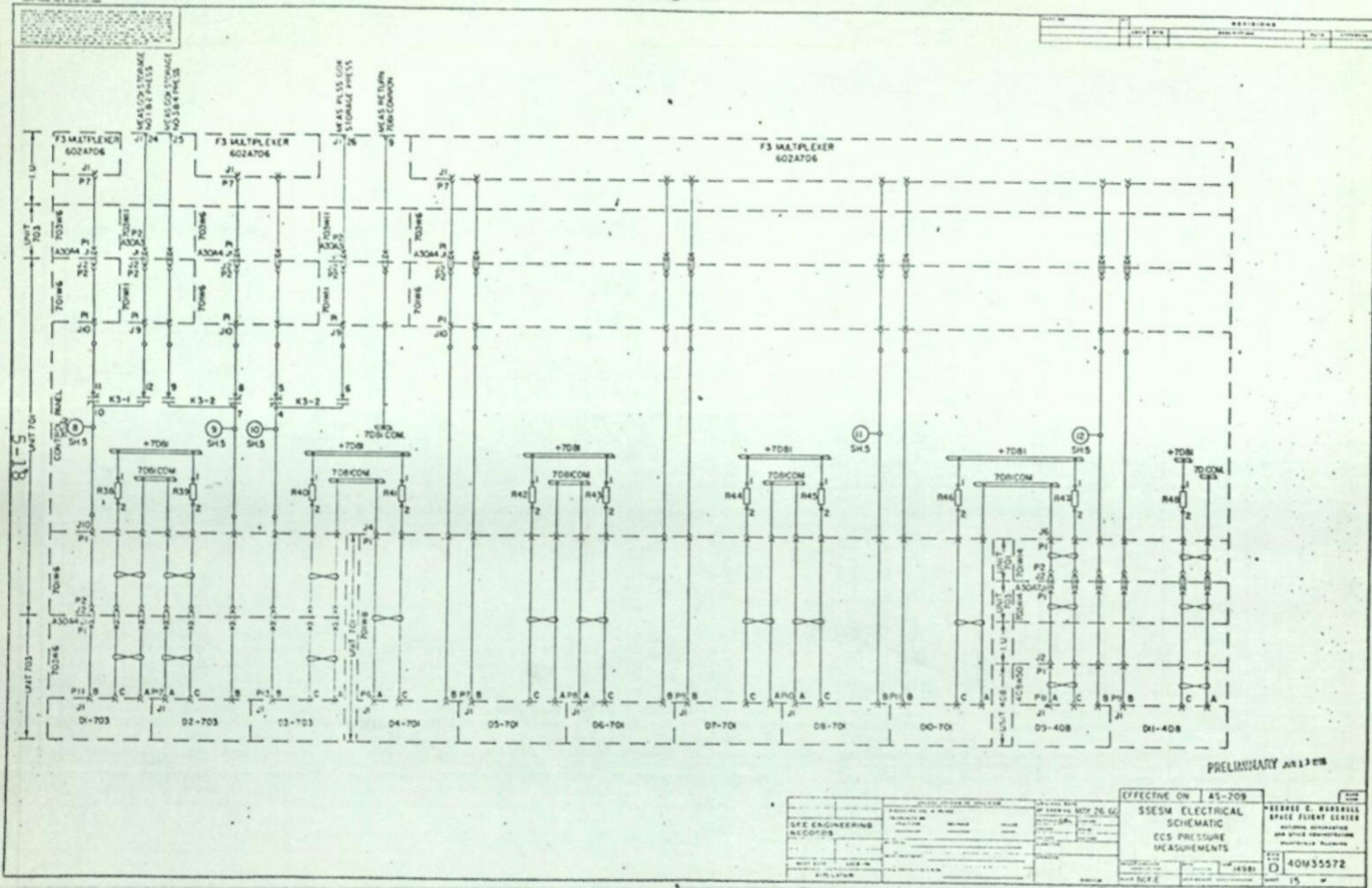


Figure 5.0-17



PRELIMINARY AS133E8

SFE ENGINEERING RECORDS	REVISIONS	EFFECTIVE ON AS-209
SSES/ELECTRICAL SCHEMATIC ECS PRESSURE MEASUREMENTS		
JOHNSON SPACE CENTER MAY 26, 1986		
40M35572		

JOHNSON
SPACE CENTER
MAY 26, 1986
40M35572

Figure 5.0-18

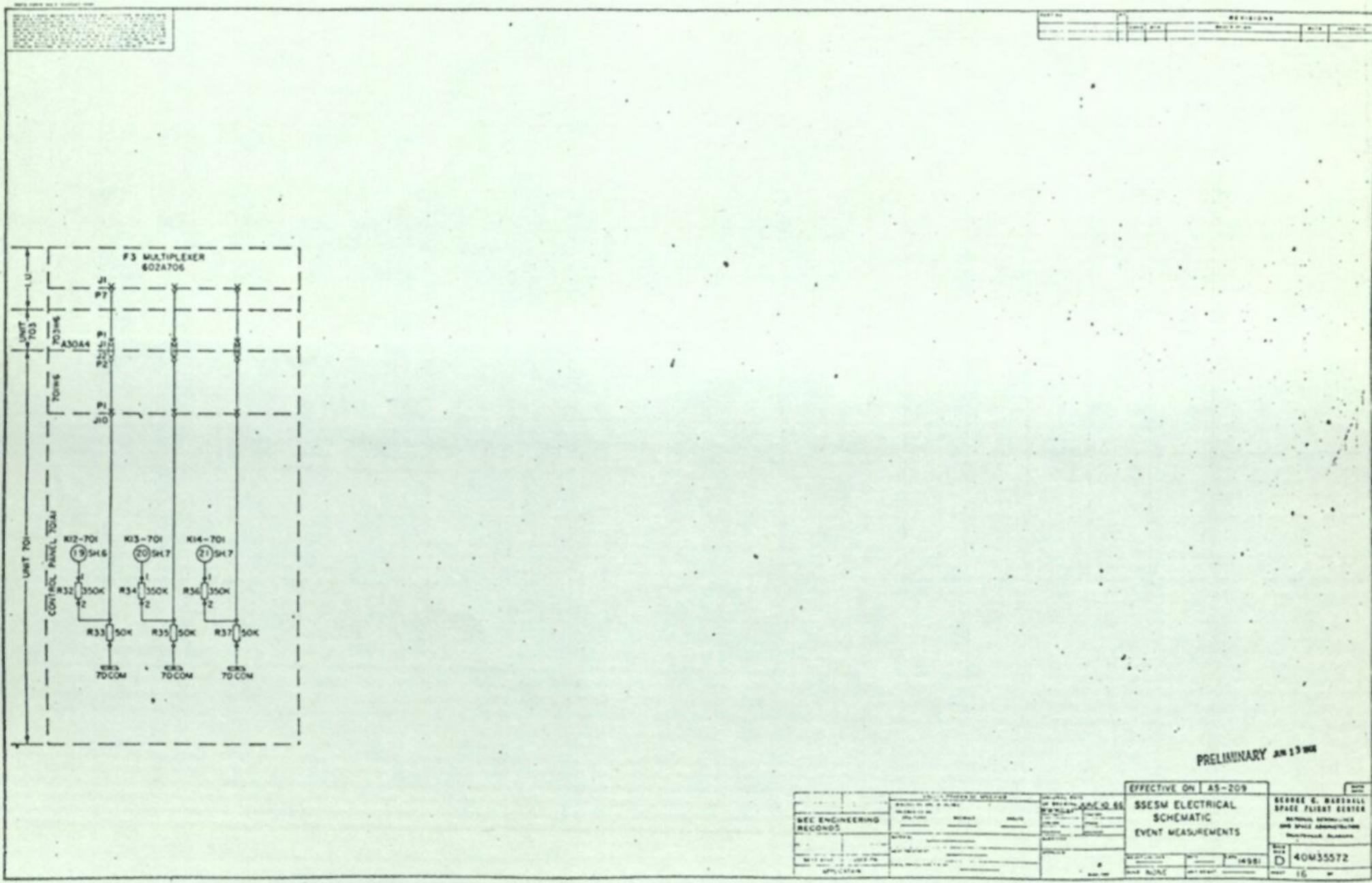
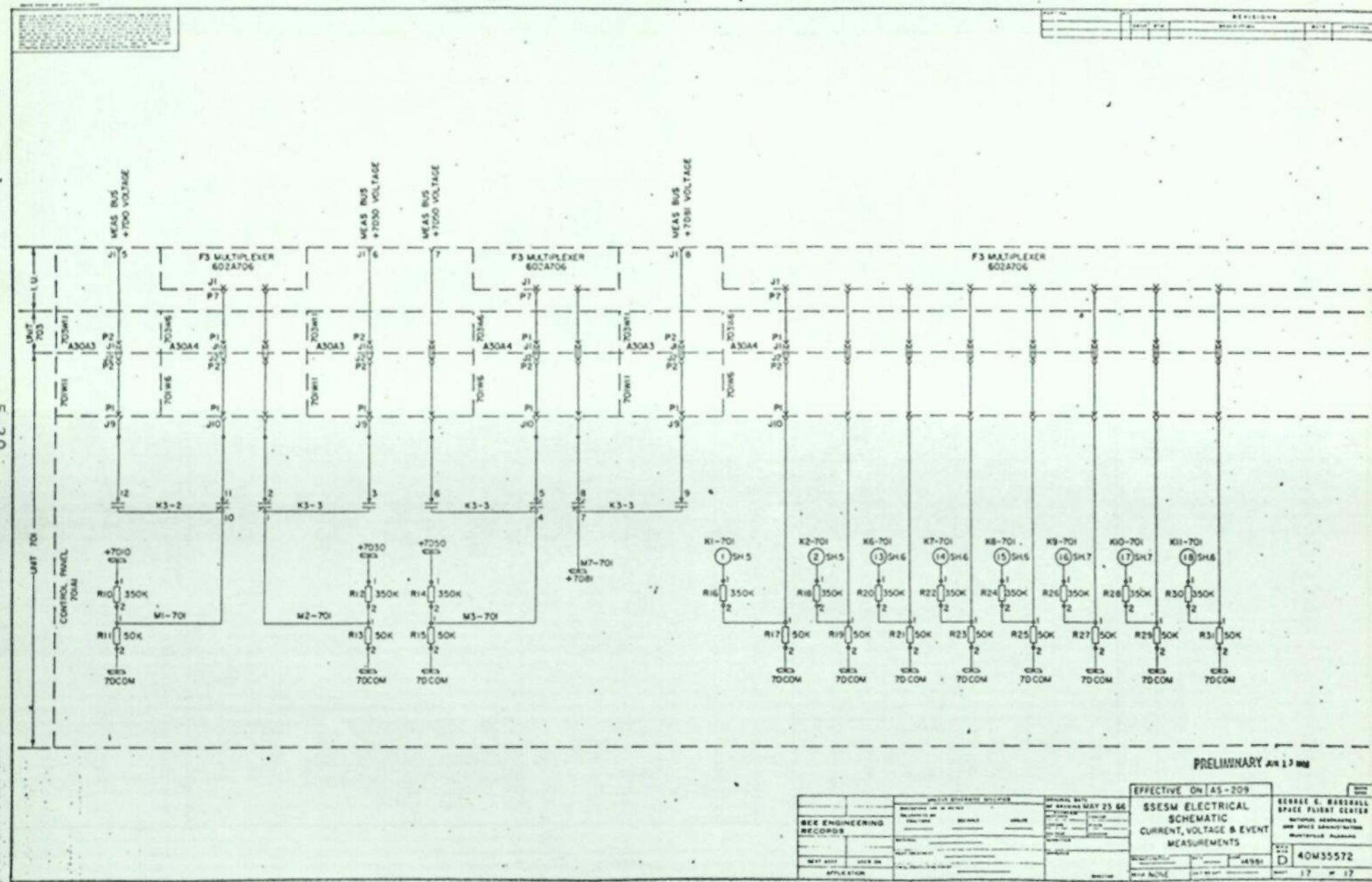


Figure 5.0-19



SECTION 6.0 INSTRUMENTATION PROGRAM AND COMPONENTS

A listing of the measuring system hardware, composed of telemetry, measuring, and RF components, which are not associated with particular measurements is presented in Table 6.0-1. Also presented, in Tables 6.0-2 through -13 is the complete instrumentation program, which consists of measurements, telemetry channels, applicable measuring components, range, and other pertinent information.

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER L I N E	Equipment		RANGE OR PART NO.	VEHICLE SSESM			TELEMETER CHANNEL	RES.	F L T. C A L	REQ	PAGE
	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT		FLT. PER.	% POS. ERR	INS. ENG.					
		Measuring Rack 703A404	50M12271								
		Measuring Rack 703A405	50M12271								
		Measuring Rack 703A406	50M12271								
		Measuring Rack 703A407	50M12271								
		Measuring Rack 703A408	50M12271								
		F1 RF Assy 703A401	50M12205								245.3 MC
		F1 Tm Assy 703A402	50M12206								
		F1 Multiplexer 703A403	50M12212								
		Tm Calibrator Assy	50M12416								

TABLE 6.0-1

INSTRUMENTATION PROGRAM & COMPONENTS

LINE	PARAMETER	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR	INS. ENG.	VEHICLE	SSESMM	DWG. NO.	PAGE		
											RES.	F L T. C A L	R E Q
	C1-703		Temp. Oxygen Storage Tank No. 1 Temp. Gauge DC Amplifier	-125 to +100°C 50M12400					EF3-X-01-01	12S	Y	01	4)
	C2-703		Temp. Oxygen Storage Tank No. 2 Temp. Gauge DC Amplifier	-125 to +100°C 50M12400					EF-X-01-02	12S	Y	01	4)
	C3-703		Temp. Oxygen Storage Tank No. 3 Temp. Gauge DC Amplifier	-125 to +100°C 50M12400					EF3-X-01-03	12S	Y	01	4)
	C4-701		Temp. Reg. (8A) Inlet Temp. Gauge DC Amplifier	-125 to +100°C 50M12400					EF3-X-01-04	12S	Y	01	4)

TABLE 6.0-2

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER		Temperature		VEHICLE	SSESMM	DWG. NO.	PAGE				
L I N E	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR.	INS. ENG.	TELEMETER CHANNEL	RES.	F L T C A L	R E Q	REMARKS
4-9	C5-701	Temp. Reg. (8A) Outlet Temp. Gauge DC Amplifier	-125 to 70°C 50M12400				EF3-X-01-05	12S	Y	01	4)
	C6-408	Temp. Valve (5c) Outlet Temp. Gauge DC Amplifier	-75 to +40°C 50M12400				EF3-X-01-06	12S	Y	01	4)
	C7-701	Temp. Suit Loop Supply Temp. Gauge DC Amplifier	5 to 15°C 50M12400				EF3-X-01-07	12S	Y	01	4)
	C8-408	Temp. Reg. (9B) Inlet Temp. Gauge DC Amplifier	-125 to +100°C 50M12400				EF3-X-01-08	12S	Y	01	5)
	C9-701	Temp. Airlock Temp. Gauge DC Amplifier	-100 to +125°F 50M12400				EF3-X-01-09	12S	Y	01	4)

TABLE 6.0-3

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER LINE	Temperature		VEHICLE	SSESMM		DWG. NO.		PAGE			
	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT		RANGE OR PART NO.	FLT. PER.	% POS. ERR.	INS. ENG.	TELEMETER CHANNEL	RES.	FLT. CAL	REQ
C10-703	Temp. Battery No. 1 Temp. Gauge DC Amplifier	0 to 70°C 50M12400						EF3-X-01-10	12S	Y	02
C11-703	Temp. Battery No. 3 Temp. Gauge DC Amplifier	0 to 70°C 50M12400						EF3-X-02-01	12S	Y	02
C12-703	Temp. Battery No. 5 Temp. Gauge DC Amplifier	0 to 70°C 50M12400						EF3-X-02-02	12S	Y	02
C13-703	Temp. Battery No. 7 Temp. Gauge DC Amplifier	0 to 70°C 50M12400						EF3-X-02-03	12S	Y	02
C14-703	Temp. Battery No. 9 Temp. Gauge DC Amplifier	0 to 70°C 50M12400						EF3-X-02-04	12S	Y	02

TABLE 6.0-4

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER		Temperature		VEHICLE	SSESMM	DWG. NO.	PAGE				
LINE	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR.	INS. ENG.	TELEMETER CHANNEL	RES.	FLT. CAL	REQ	REMARKS
9-9	C15-703	Temp. Battery No. 11 Temp. Gauge DC Amplifier	0 to 70°C 50M12400				EF3-X-02-05	12S	Y	02	
	C16-703	Temp. Battery No. 13 Temp. Gauge DC Amplifier	0 to 70°C 50M12400				EF3-X-02-06	12S	Y	02	
	C17-703	Temp. Battery No. 15 Temp. Gauge DC Amplifier	0 to 70°C 50M12400				EF3-X-02-07	12S	Y	02	
	C18-703	Temp. Battery No. 17 Temp. Gauge DC Amplifier	0 to 70°C 50M12400				EF3-X-02-08	12S	Y	02	
	C19-703	Temp. Battery No. 19 Temp. Gauge DC Amplifier	0 to 70°C 50M12400				EF3-X-02-09	12S	Y	02	
	C20-703	Temp. Battery No. 21 Temp. Gauge DC Amplifier	0 to 70°C 50M12400				EF3-X-02-10	12S	Y	02	

TABLE 6.0-5

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER LINE	Temperature		VEHICLE	SSESIM		TELEMETER CHANNEL	RES.	F.L.T. CAL	REQ	PAGE
	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT		RANGE OR PART NO.	FLT. PER.	% POS. ERR	INS. ENG.			
L-9	C21-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier	30 to 65°C 50M12400					EF3-X-05-02	12S	Y 01 5)
	C22-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier						EF3-X-05-03		
	C23-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier	30 to 65°C 50M12400					EF3-X-05-04	12S	Y 01 5)
	C24-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier						EF3-X-05-05		
	C25-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier	30 to 65°C 50M12400					EF3-X-05-06	12S	Y 01 6)
	C26-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier						EF3-X-05-07		
	C27-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier	30 to 65°C 50M12400					EF3-X-05-08	12S	Y 01 6)
	C28-408	Temp LH2 Tank, Int Temp Gauge DC Amplifier						EF3-X-05-09		

TABLE 6.0-6

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER	Temperature			VEHICLE	SSESMM			DWG. NO.	PAGE			
	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.		FLT. PER.	% POS. ERR	INS. ENG.		RES.	F L T. C A L	R E Q	REMARKS
	C29-409	Temp LH2 Tank, Ext Temp Gauge DC Amplifier	-60 to 100°C 50M12400					EF3-X-05-10	12S	Y	01	6)
	C30-409	Temp LH2 Tank Ext Temp Gauge DC Amplifier	-60 to 100°C 50M12400					EF3-X-06-01	12S	Y	01	6)

TABLE 6.0-7

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER	Pressure		VEHICLE	SSESMM		DWG. NO.	PAGE						
	LINE	MEAS. NR.		MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR	INS. ENG.	TELEMETER CHANNEL	RES.	F.L.T. CAL	REQ	REMARKS
D1-703		Pressure Oxygen Storage Tank No. 1 Press. Gauge		0 to 3500 psi 50M12344					EF3-Y-03-01	12S	Y	01	Hardwire Display for preflight 4) 6)
D2-703		Pressure, Oxygen Storage Tank No. 2 Press. Gauge		0 to 3500 psi 50M12344					EF3-X-03-02	12S	Y	01	Hardwire Display for preflight 4)6)
D3-703		Pressure, Oxygen Storage Tank No. 3 Press. Gauge		0 to 3500 psi 50M12344					EF3-X-03-03	12S	Y	01	Hardwire Display for preflight 4)6)
D4-701		Inlet Pressure, Oxygen Supply System Press. Gauge		0 to 3500 psi 50M12344					EF3-X-03-04	12S	Y	01	4)

TABLE 6.0-8

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER	Pressure			VEHICLE	SSESMM			DWG. NO.	PAGE				
	L I N E	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT		RANGE OR PART NO.	FLT. PER.	% POS. ERR		TELEMETER CHANNEL	RES.	F L T. C A L	R E Q	REMARKS
01-9	D5-701	Regulator (8A) Outlet Pressure Press Gauge	0 to 400 PSI						EF3-X-03-05	12S	Y	01	4)
	D6-701	Pressure, Suit Loop Supply Press Gauge	0 to 15 PSI 50M10262						EF3-X-03-06	12S	Y	01	4)
	D7-701	Regulator (7A) Outlet Pressure Press Gauge	05 to 1500 PSI						EF3-X-03-07	12S	Y	01	4)
	D8-701	Airlock Pressure Press Gauge	0 to 20 PSI 50M10259						EF3-X-03-08	12S	Y	01	Hardwire Display for preflight 4) 5) 6)
	D9-408	Pressure, LH2 Tank Press Gauge	0 to 10 PSI						EF3-X-03-09	12S	Y	01	4) 5) 6)

TABLE 6.0-9

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER	Pressure		VEHICLE	SSESMM			DWG. NO.	PAGE					
	L I N E	MEAS. NR.		MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR	INS. ENG.	TELEMETER CHANNEL	RES.	F L T. C A L	R E Q	REMARKS
D10-201		CO2 Partial Pressure Airlock Gauge Assy		0 to .15 psi					EF3-X-03-10	12S	Y	01	4) 6)
		CO2 Partial Pressure LH2 Tank		0 to .15 psi					EF3-X-04-01	12S	Y	01	4) 5)

TABLE 6.0-10

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER	FLOW		VEHICLE	SSESMM			DWG. NO.	PAGE					
	L I N E	MEAS. NR.		MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR	INS. ENG.	TELEMETER CHANNEL	RES.	F L T. C A L	R E Q	REMARKS
		F1-408		Flow- ECS Flowmeter DC Amplifier	0.2 to 3 lb/hr 50M12400				EF3-X-05-01	45	Y	01	5)

TABLE 6.0-11

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER		Signal		VEHICLE	SSESMM	DWG. NO.	PAGE				
L I N E	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR	INS. ENG.	TELEMETER CHANNEL	RES.	F L T. C A L	R E Q	REMARKS
	K1-701	Voltage Sensor No. 1	0 or 5 VDC				EF3-X-04-02	12S	Y	02	
	K2-701	Voltage Sensor No. 2	0 or 5 VDC				EF3-X-04-03	12S	Y	02	
	K6-701	Lights LH2 Tank	0 or 5 VDC				EF3-X-05-05	12S	Y	02	
	K7-701	Lights LH2 Tank	0 or 5 VDC				EF3-X-05-06	12S	Y	02	
	K8-701	Blowers On	0 or 5 VDC				EF3-X-05-07	12S	Y	02	
	K9-701	Oxygen Heater 701A6 On	0 or 5 VDC				EF3-X-05-08	12S	Y	02	
	K10-701	Oxygen Heater 701A7 On	0 or 5 VDC				EF3-X-05-08	12S	Y	02	
	K11-701	Exterior Lights On	0 or 5 VDC				EF3-X-05-09	12S	Y	02	
	K12-701	Airlock Light On	0 or 5 VDC				EF3-X-05-10	12S	Y	02	

TABLE 6.0-12

INSTRUMENTATION PROGRAM & COMPONENTS

PARAMETER L I N E	Voltage, Current & Frequency			VEHICLE	SSESMM	DWG. NO.	PAGE				
	MEAS. NR.	MEASUREMENT NAME AND OR COMPONENT	RANGE OR PART NO.	FLT. PER.	% POS. ERR	INS. ENG.	TELEMETER CHANNEL	RES.	F L. T. C A L	R E Q	REMARKS
41-9	M1-701	Voltage Bus 7D10	0 to 28 VDC				EF3-X-04-04	12S	Y	02	4)
	M2-701	Voltage Bus 7D30	0 to 28 VDC				EF3-X-04-05	12S	Y	02	4)
	M3-701	Voltage Bus 7D50	0 to 28 VDC				EF3-X-04-06	12S	Y	02	4)
	M4-701	Current Bus 7D10 DC Amplifier	0 to 120 Amps				EF3-X-04-07	12S	Y	02	4)
	M5-701	Current Bus 7D30 DC Amplifier	0 to 24 Amps				EF3-X-04-08	12S	Y	02	4)
	M6-701	Current Bus 7D50 DC Amplifier	0 to 120 Amps				EF3-X-04-09	12S	Y	02	4)
	M7-701	Voltage 5 VDC Measuring Supply	0 to 5 VDC				EF3-X-04-10	12S	Y	02	

TABLE 6.0-13

SECTION 7.0 HANDLING SEQUENCE

7.1 GENERAL

This Section describes receiving the SSESM at KSC, checkout of SLA, SSESM installation in SLA, SLA and IU mating, and spacecraft mating and forward buildup.

7.2 RECEIVING OF SSESM AT KSC (Figures 7.2-1 through -3)

7.2.1 The SSESM is shipped from MSFC, Huntsville, to KSC.

7.2.2 The SSESM is transferred to Manned Spacecraft Operations Building (MSOB), MILA.

7.2.3 The SSESM is removed from the shipping container by:

a. Removal of upper section of the container.

b. Installation of handling ring on SSESM.

c. Removal of all clamping devices on the SSESM, freeing it from the lower section of the shipping container.

d. Using a hoisting sling and the crane facilities at MSOB.

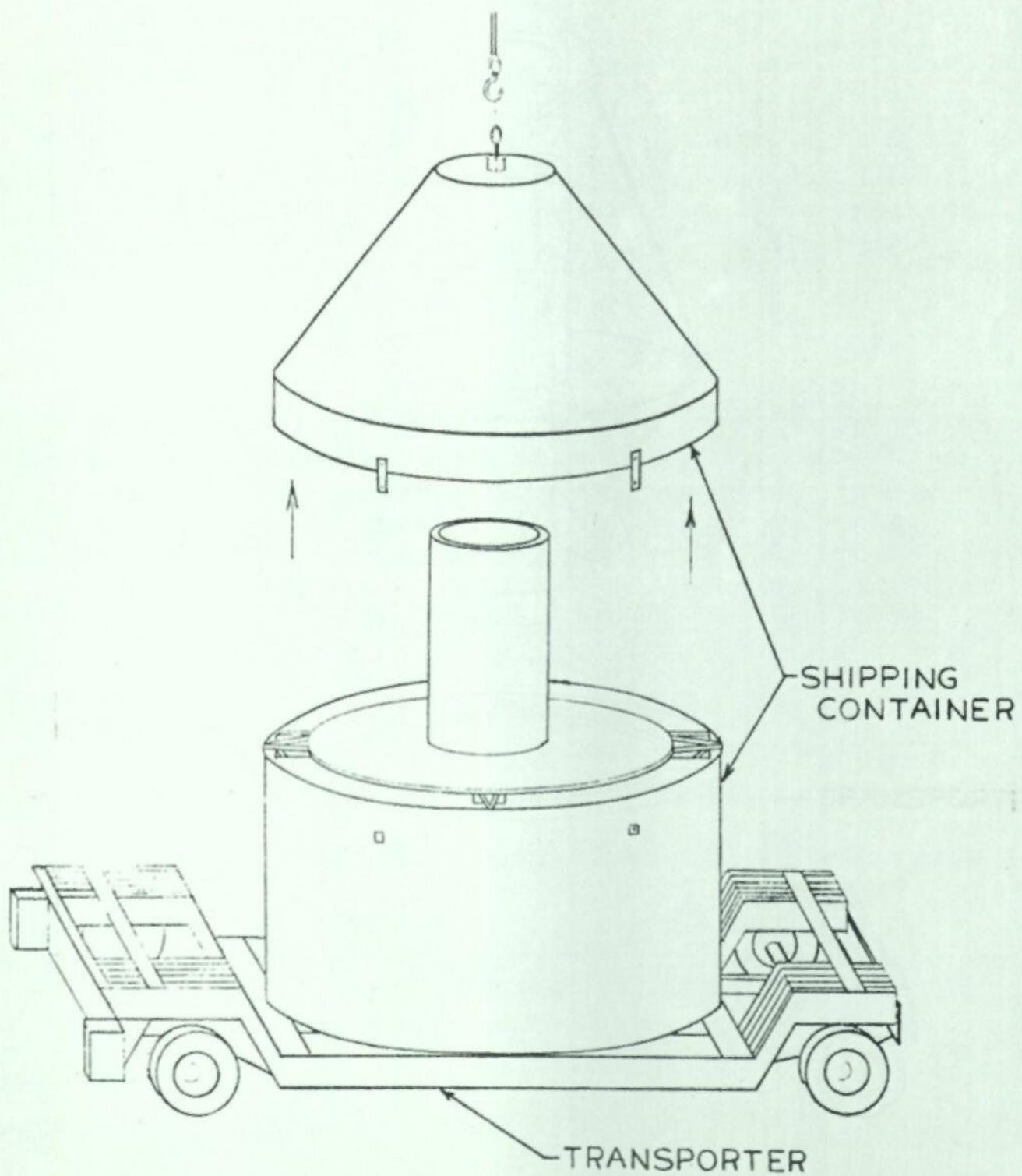


FIGURE 7.2-1 - ARRIVAL OF SSESM AT THE TEST AND CHECKOUT FACILITIES

THE METEROID SHIELD IS
HITCHED IN 4 PLACES FOR
CLAMP INSTALLATION

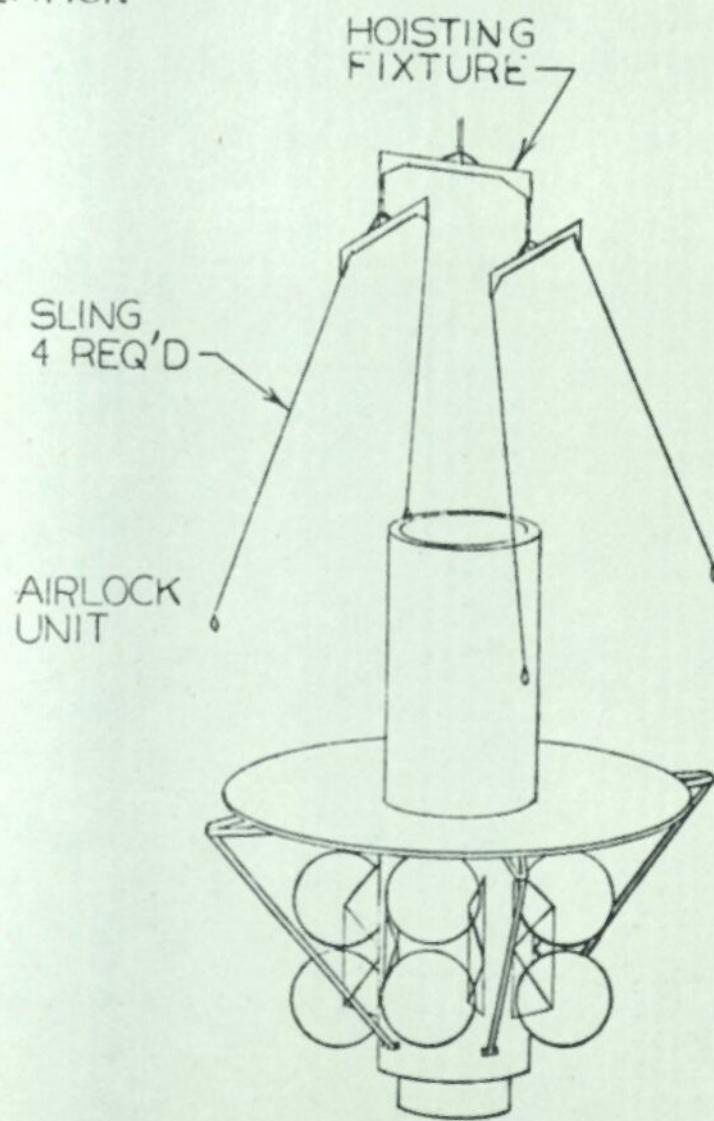


FIGURE 7.2-2 - METHOD OF HOISTING SSESMS

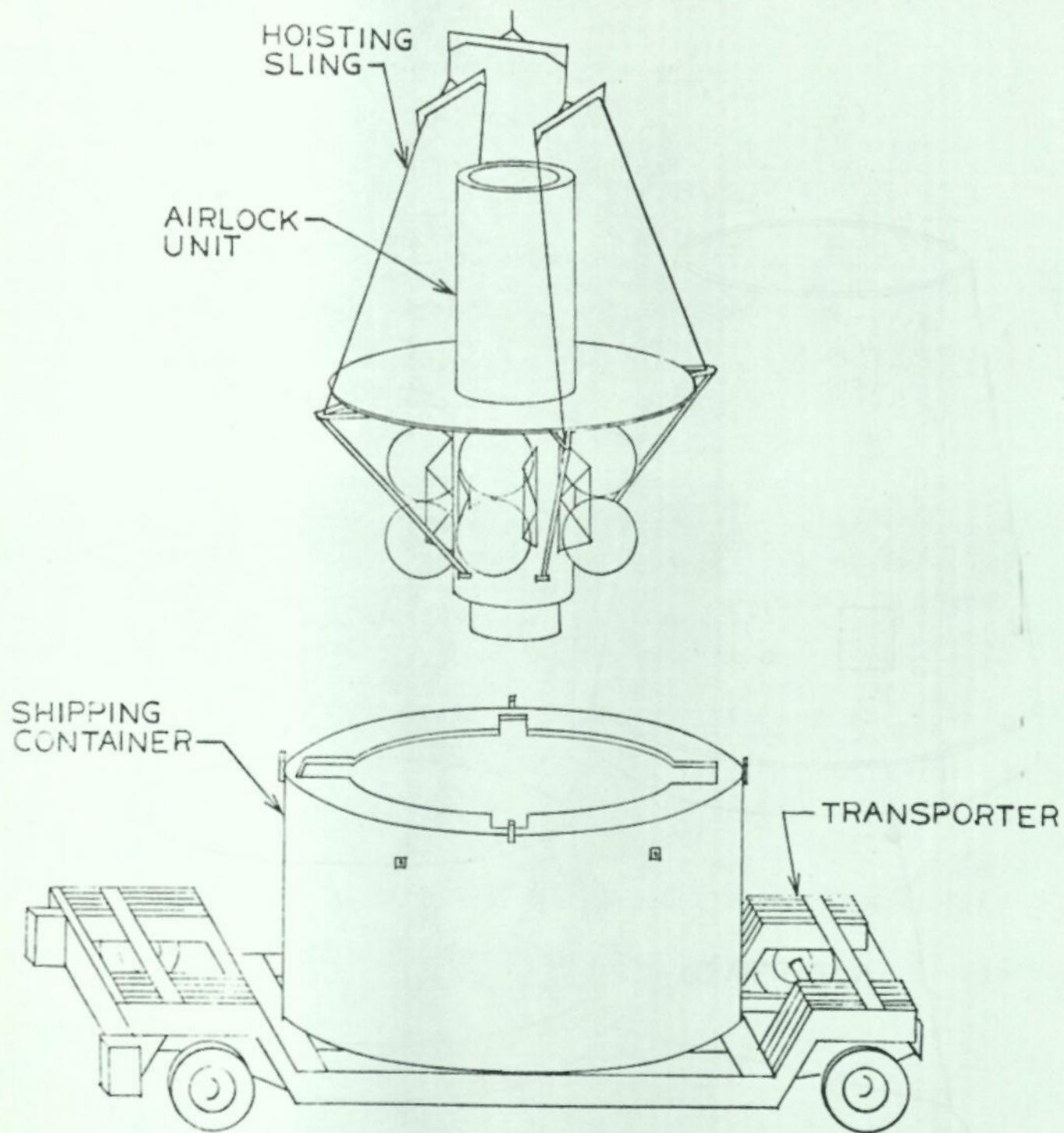


FIGURE 7.2-3 - REMOVAL OF SSESM FROM STORAGE CONTAINER

7.3 CHECKOUT OF SLA PRIOR TO SSESMM INSTALLATION
(Figure 7.3-1)

7.3.1 Receive SLA and install in the work stand at MSOB.

7.3.2 Perform inspection.

7.3.3 Install open items:

- a. Separation system
- b. Umbilical
- c. Associated wiring
- d. Instrumentation

7.3.4 Perform continuity check.

7.3.5 Demate SLA.

7.3.6 Transfer SLA upper section to the next station.

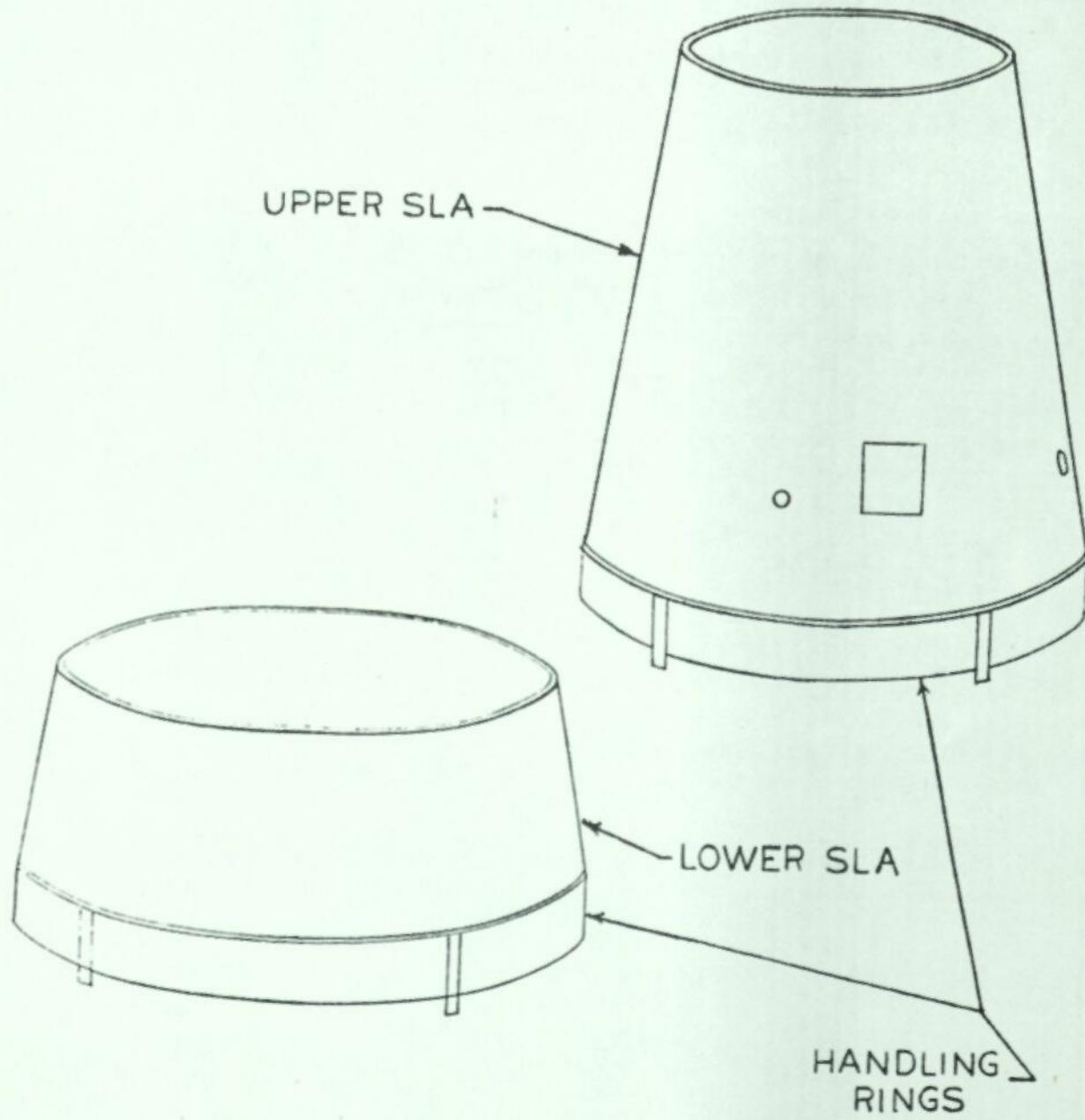


FIGURE 7.3-1 - SLA SEPARATED

7.4 SSESMM INSTALLATION IN SLA LOWER SECTION
(Figures 7.4-1 through -3)

7.4.1 Install SSESMM in the SLA lower section.

7.4.2 Adjust the attachment fittings.

7.4.3 Verify the alignment.

7.4.4 Mate the electrical connectors and verify their compatibility.

7.4.5 Demate.

7.4.6 Transfer the SSESMM to the next station.

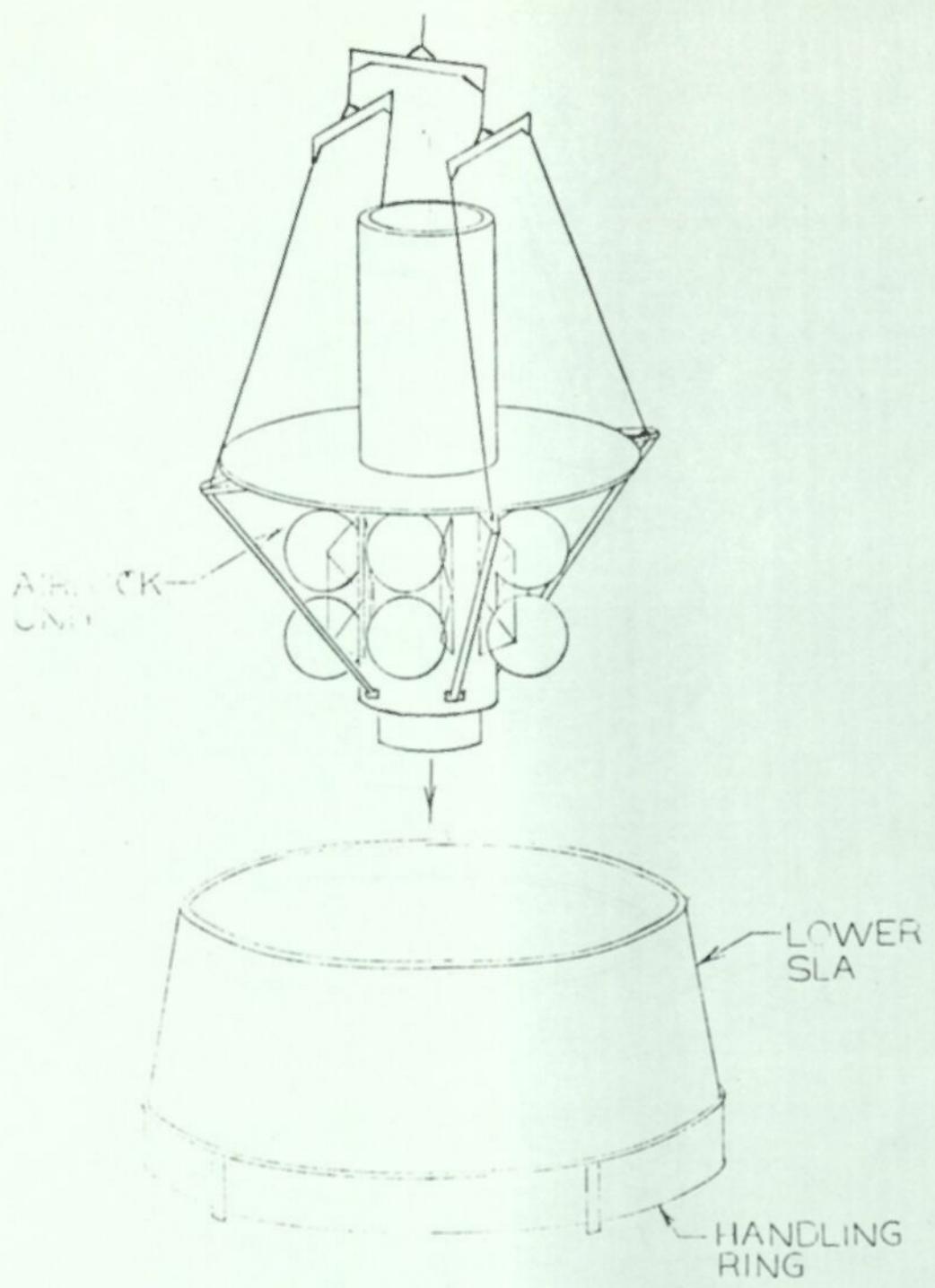


FIGURE 7.4-1 - INSTALLATION OF SSES M IN LOWER SLA FOR TEST AND CHECKOUT

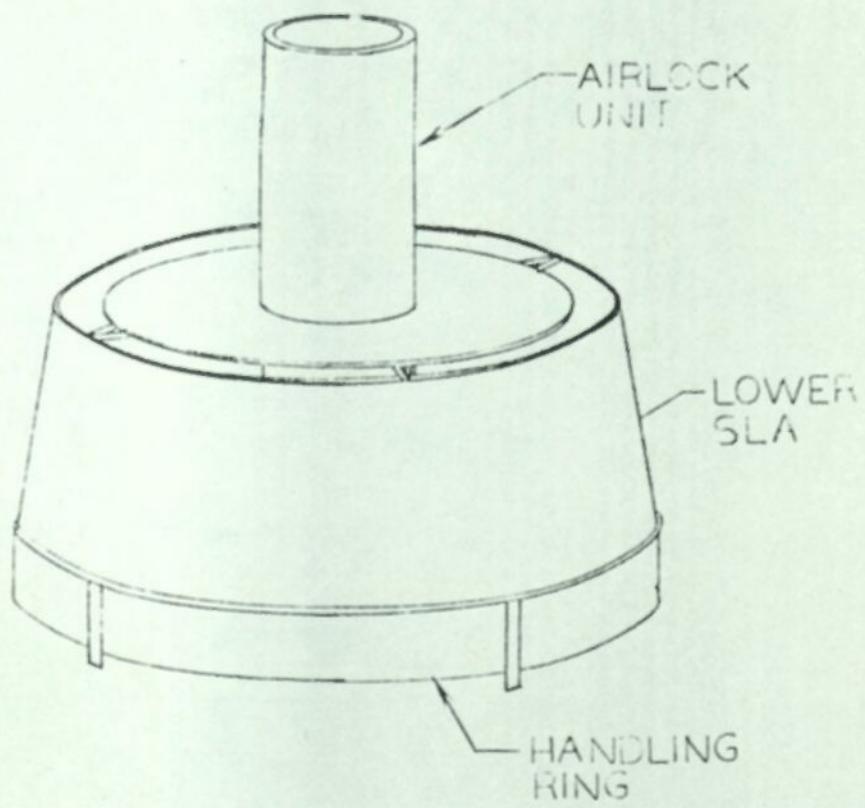


FIGURE 7.4-2 - SSESMA AND LOWER SLA ASSEMBLY

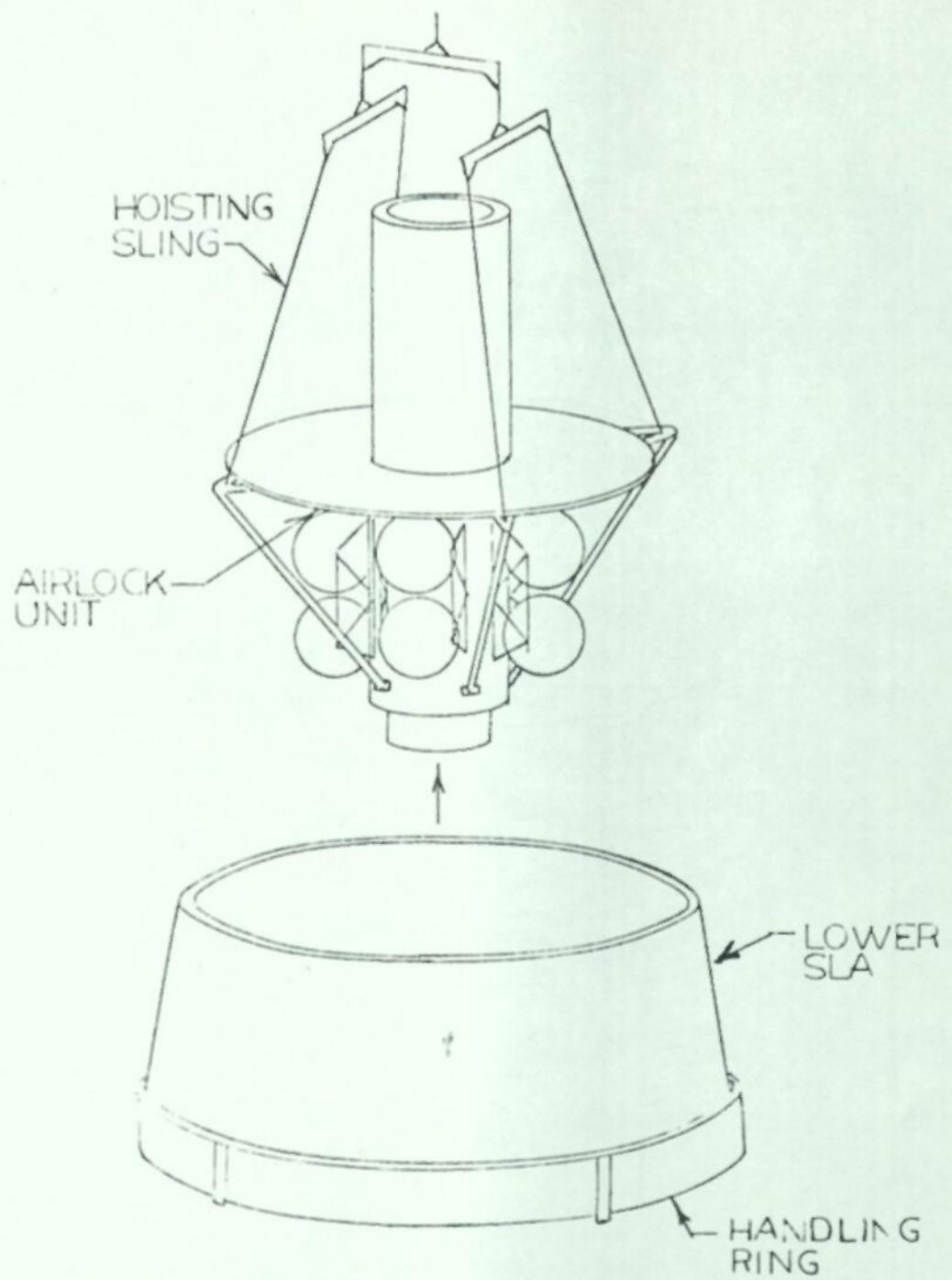


FIGURE 7.4-3 - SSESM REMOVAL FOR FURTHER TESTING OF LOWER SLA

7.5 SLA LOWER SECTION AND IU MATING FOR TEST AND CHECKOUT
(Figure 7.5-1)

- 7.5.1 Receive IU.
- 7.5.2 Mate SLA lower section to IU.
- 7.5.3 Perform mechanical fit check and verify mechanical alignment.
- 7.5.4 Perform electrical fit check.
- 7.5.5 Demate SLA from IU.
- 7.5.6 Transfer IU and SLA lower section to the next station.
- 7.5.7 Not shown: Verification of CM/SLA mechanical compatibility and storage of SLA.

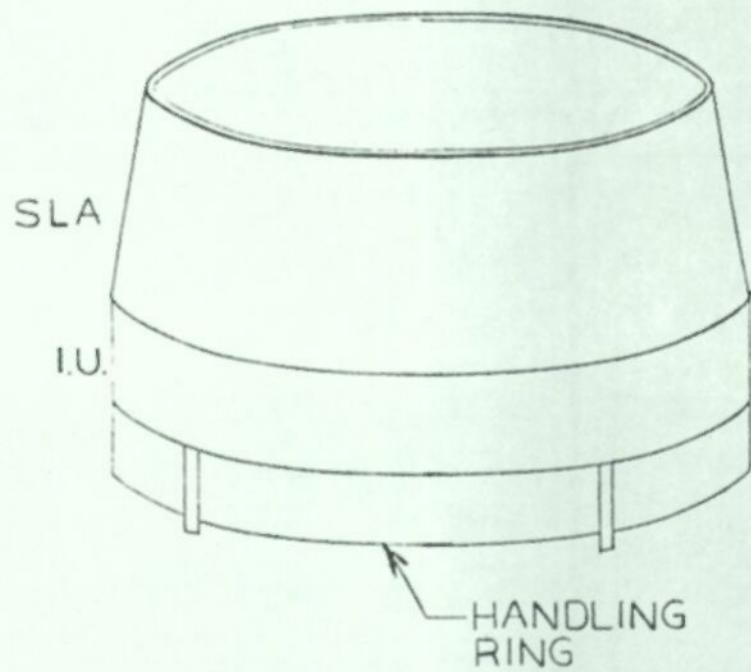


FIGURE 7.5-1 - LOWER SLA MATED TO IU FOR TEST AND CHECKOUT

7.6 SPACECRAFT MATE AND FORWARD BUILDUP
(Figure 7.6-1 through -3)

- 7.6.1 Install complete SSESM in SLA lower section.
- 7.6.2 Verify interface and alignment.
- 7.6.3 Mate SLA upper section to SLA lower section.
- 7.6.4 Install internal access platform set.
- 7.6.5 Mechanically mate CSM to SLA.
- 7.6.6 Verify CSM/SLA mechanical alignment.
- 7.6.7 Electrically mate CSM to SLA.
- 7.6.8 Verify CSM/SLA electrical interfaces.
- 7.6.9 Buildup forward deck.
- 7.6.10 Install forward heat shield.
- 7.6.11 Install ordnance devices.
- 7.6.12 Spacecraft transferred to Launch Complex (LC).

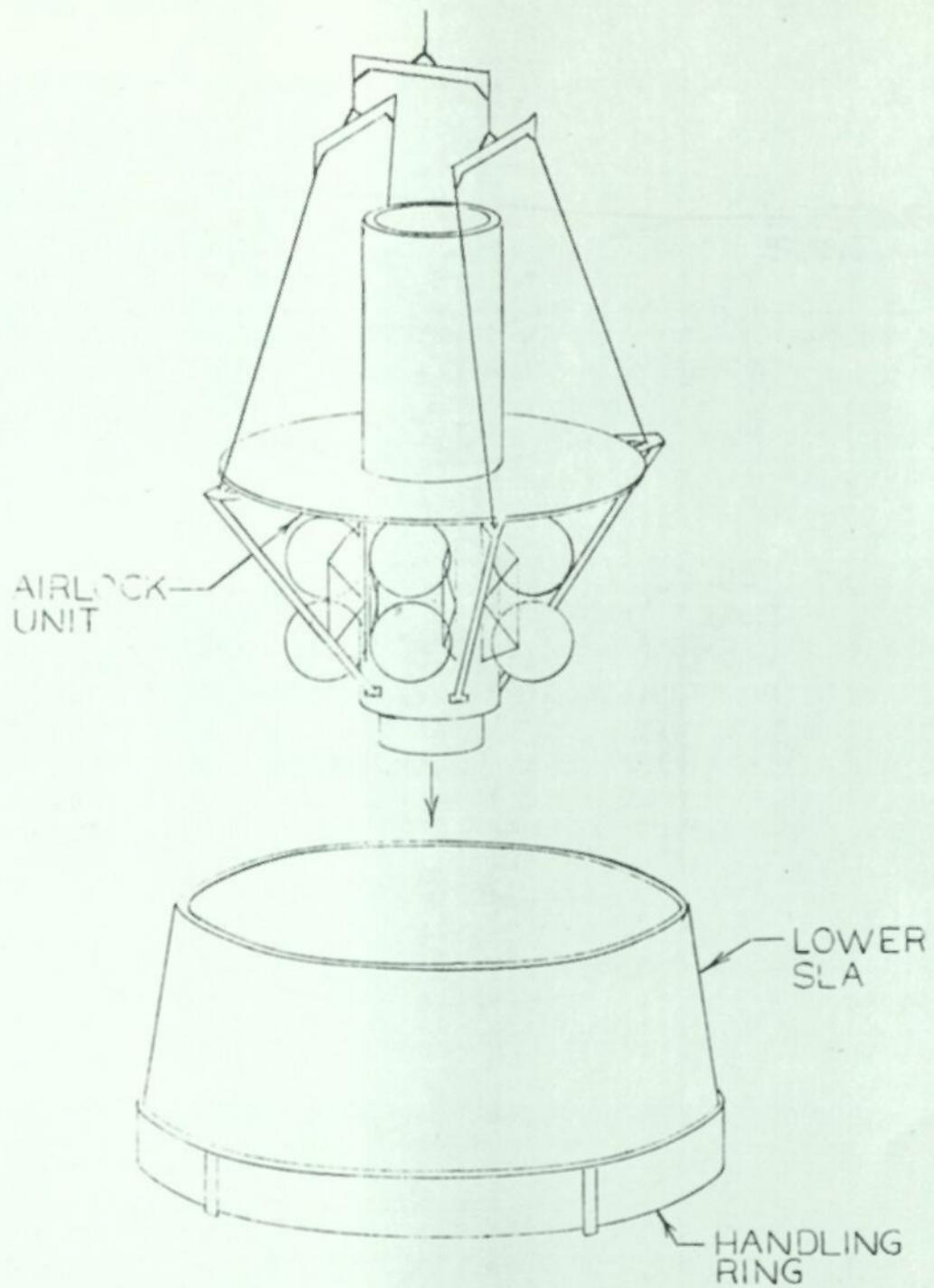


FIGURE 7.6-1 - SSES M INSTALLATION IN LOWER SLA PRIOR TO MATING
WITH THE FLIGHT VEHICLE

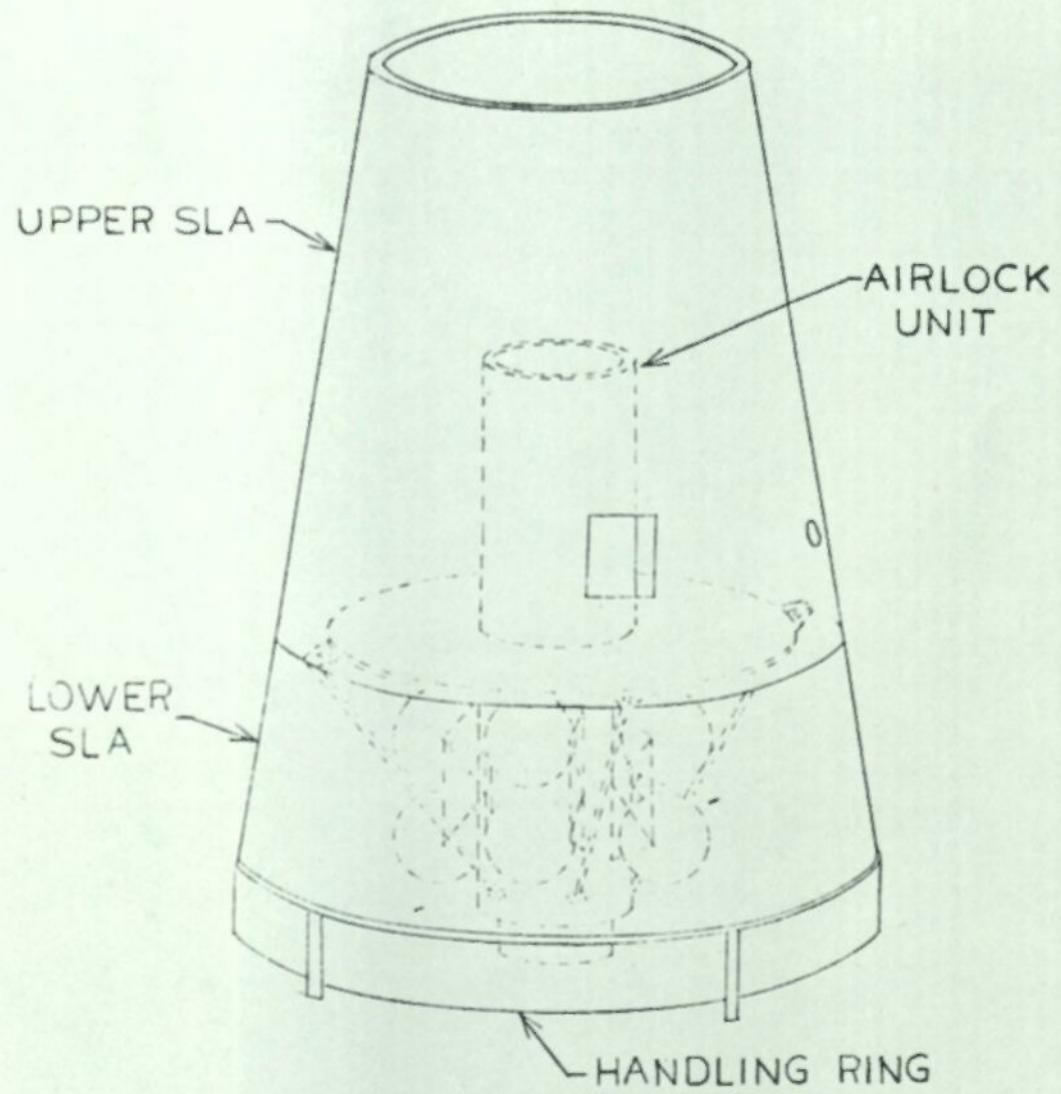


FIGURE 7.0-2 - SSESM INSTALLED IN SLA ASSEMBLY

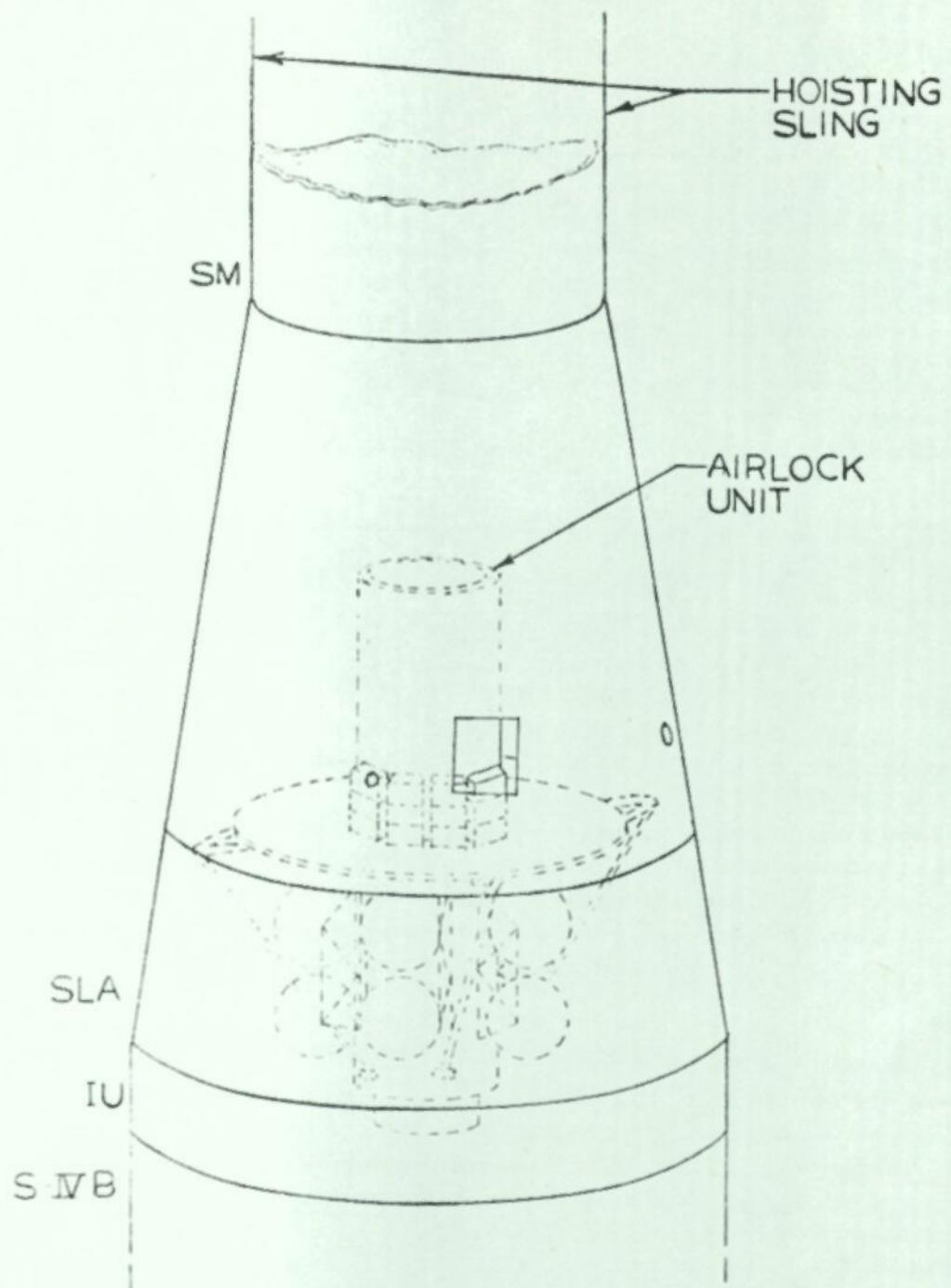


FIGURE 7.0-3 - CM/SM/SLA/ SSESMA MATING TO VEHICLE

SECTION 8.0 MAINTENANCE CONCEPT

8.1 INTRODUCTION

8.1.1 Purpose

The maintenance concept for the SSESMM is presented in this Section. It shall be used by MSFC and contractors when developing maintenance program plans to insure adequate maintenance for the SSESMM.

8.1.2 Scope

This concept applies to all orbital maintenance activities occurring on the SSESMM system after docking takes place.

8.1.3 Objectives

The principal objective of this maintenance concept is to provide a baseline for systematic maintenance planning for the SSESMM logistics support. Systematic maintenance planning is required in order to accomplish the following:

- a. Increased equipment availability.
- b. Increased repair reliability.
- c. Increased safety for equipment and personnel.
- d. Reduced probability of human error.

The above objectives are attained by achieving the following:

- a. Verified maintenance procedures and maintenance technical support data.
- b. Compatible man-machine relationships for successful completion of maintenance activities.
- c. Adequate training for personnel to perform maintenance of the SSESMM.

8.1.4 Concept Revisions

This concept provides the preliminary maintenance program for all organizations performing logistics planning functions. As analysis and program definition proceed, this concept will be subject to additions, deletions, and modifications. These changes should be justified by appropriate technical or management studies.

8.1.5 Applicable Documents

The following documents shall be used for reference to aid in the maintenance planning for the SSESM. In case of conflict between this document and the referenced documents, the referenced documents shall apply:

Astronaut Training Plan (not released)

Apollo Logistics Support Plan (NHB 7500.1)

SSESM Maintenance Plan (not released)

8.2 BASIC CONCEPTS

8.2.1 Mission Concept

The present mission concept requires that, in the event of a malfunction in any critical system, the mission will be aborted. It is the intent of this maintenance concept to extend the mission concept to permit an attempt to repair the system prior to issuing an order to abort.

8.2.2 Spares Concept

A limited number of spare parts will be provided for in-space maintenance. Candidates for spares will be identified as the result of performance of a maintenance requirements analysis. The actual spares to be transported with the SSESM will be determined from a detailed spare parts analysis. This spare parts analysis will consider, as a minimum, the following: (a) Reliability; (b) Criticality; (c) Feasibility; (d) Weight Constraints. Spare parts will only be considered for support of the Environmental Control System (ECS).

8.2.3 Maintenance Concept

Maintenance on the SSESM will be performed by removing and replacing malfunctioned components. Disposal of defective components will be accomplished by stowing them in appropriate locations in the Spent Stage. No attempt will be made to return defective components to Earth. Structural repair will be considered, depending on development of adequate repair techniques. The maintenance requirements, tool requirements, astronaut training requirements, etc., will be identified by a maintenance analysis (to be performed in accordance with NHB 7500.1). Repair, in lieu of component replacement, will be considered if justification is provided by means of maintenance analysis or other trade studies. Components which are capable of being removed and replaced or repaired will be identified in the SSESM maintenance plan (to be developed at a later date). Maintenance will be considered only on the SSESM Environmental Control System (ECS) due to the high mission criticality of this system.

8.3 TYPES OF MAINTENANCE

8.3.1 Preventive Maintenance (Scheduled Maintenance)

Preventive maintenance is defined as any planned maintenance action which is performed to maintain the system in a satisfactory operational condition. This consists, normally, of systematic inspections, servicing, and the detection and correction of incipient malfunctions before they occur or develop into major malfunctions.

8.3.2 Corrective Maintenance (Unscheduled Maintenance)

Corrective maintenance is any maintenance action which is performed as the result of a failure and is performed in order to restore the equipment to satisfactory operational condition.

8.4 MAINTENANCE LEVELS

Levels of maintenance have been identified in order to categorize maintenance activities on a functional and location basis. Levels of maintenance for the S-IVB Workshop are described as follows:

8.4.1 First Level

First-level maintenance includes all maintenance activities accomplished directly on system-installed hardware. This includes fault

isolation, removal and replacement of components, servicing, replenishing, inspection, and repair-in-place activities performed on the Workshop whether it be in space or on the ground prior to launch.

8.4.2 Second Level

Second-level maintenance includes all activities performed in direct support of first-level maintenance and involves disposition or repair of hardware removed during first-level maintenance activities. In view of the philosophy discussed in paragraph 10.2.3, no second-level or lower-level maintenance will be required.

8.5 MAINTENANCE STANDARDS

Space maintenance activities demand the application of high quality standard maintenance practices. Specifications must be developed which delineate in-space maintenance requirements to be met in regard to torque, cleanliness, bonding soldering, and lockwiring. Maintenance directives and procedures shall implement these specifications as applicable.

SECTION 9.0 TEST AND SIMULATION FACILITIES

9.1 GENERAL

Substantial test facility capability exists at the MSFC with present and planned facilities. The applicability of the existing facilities to the development and test of a SSESM is discussed in this Section.

9.2 EXISTING FACILITIES

To supplement the mechanically-induced vibration spectrum, use could be made of the recently-completed acoustical Test Position 116. This unique facility provides a clean acoustical environment which can subject the SSESM to a simulated acoustical spectrum equivalent to that encountered during CM detaching and docking maneuvers.

The structural integrity of the air lock and the docking structure could be verified by tethering both the assembled air lock and CM from the top of the 425-foot-high Saturn V Dynamic Test Stand. The extreme length of the suspension cables would induce negligible horizontal components and permit simulated in-space docking maneuvers.

The Saturn V Dynamic Test Stand also houses the largest U.S. Low Gravity Test Facility. This facility could be utilized to verify the design and to establish in-flight fluid flow characteristics such as would be encountered by the environmental control and other gaseous or fluid systems.

The CTL Area can accommodate component system development and verification tests involving hazardous propellants and high-pressure gases as employed by the slug environmental control system. In addition, newly and especially developed components, such as valves, regulators, switches, gauges, and heat exchangers, could be evaluated for system compatibility and response characteristics.

The recently-completed Test Position 500 could be employed in the development of hazardous cryogenic handling, transfer, storage, and dumping techniques as would be encountered during orbital hydrogen tank blowdown, as well as facilitate the solution to inevitable unforeseen problems which frequently occur in system design and development efforts.

The currently-functional GSE Area could be utilized in development of SLA panel explosive removal techniques. The random motion devices could be employed to simulate the action of the S-IVB Workshop in a perturbed orbit while activating SLA panel deployment.

In general, the aforementioned test facilities are but a few of those existing which could considerably benefit an austere in-house development of the SSESM. All of the test positions and areas are fully instrumented to sense and record the required design and test phenomena. As the program guidelines and operational requirements solidify, it is anticipated that other existing Test Laboratory facilities and component test positions can be used to greater advantage than presently envisioned.

SECTION 10.0 CREW FAMILIARIZATION PLAN

10.1 GENERAL

A description of a proposed Crew Familiarization Program for the S-IVB Workshop and spent stage experiments is presented in this Section. This plan will assure timely identification and integration of all familiarization resources and services necessary to insure adequate, timely, and economical familiarization support for the crew members. This plan shall be conducted within the guidelines and ground rules established for the overall astronaut familiarization program and shall be controlled and monitored by MSC.

This plan conforms to NHB-7500.1, Apollo Logistics Requirements Plan, November 1965; MSFC Logistics Support Requirements Plan, January 1966; and NPC 500.1, Apollo Configuration Management Manual, May 1964..

10.2 FAMILIARIZATION CONCEPT

10.2.1 Description

This familiarization concept is a proposed method of accomplishing crew familiarization for the S-IVB spent stage, the SSESM, and the experiments. This concept will assure the effective control and management required to identify, develop, provide, and maintain a familiarization program for the orbital workshop.

All crew members will be trained in the deployment and use of air lock and workshop equipment, including equipment required in MSFC-developed experiments. Contingency time will be included throughout the familiarization program to allow for unexpected events or task difficulties.

It is estimated that three or four months will be required for actual crew familiarization. This will cover five primary familiarization areas and will be divided into four phases.

10.2.2 Familiarization Areas

The primary familiarization areas are as follows:

- a. Crew system equipment handling and operation.
- b. S-IVB Workshop activation and passivation procedures.
- c. Experiment equipment transfer, operation, and data collection.
- d. S-IVB Workshop shutdown.
- e. Safety procedures and contingencies.

10.2.3 Familiarization Phase

The program will be divided into the following phases:

- a. Orientation of mission requirements and subsystems capabilities. Astronaut/equipment interface will be defined and component functions will be introduced.
- b. Simulation of man-machine mission requirements to validate equipment locations and layout.
- c. Simulation of man-machine mission requirements incorporating recommended modifications.
- d. Total mission simulation; reduced gravity, high fidelity simulation of equipment and man-equipment functional requirements.

After the orientation period, integrated mission simulation will be conducted in a Spent Stage functional mockup. Reduced gravity, vacuum, and atmospheric conditions to be encountered during the actual mission will be simulated where necessary. A continuous evaluation of the familiarization program will be conducted to determine that familiarization course objectives are met.

10.2.4 Elements Required

The elements required to identify, provide control of, and manage the familiarization program are the following:

a. Familiarization Requirements Analysis. - A systematic familiarization requirements analysis will be made of the post docking to CSM-SSESMS separation sequence of events, systems analysis, maintenance analysis, and experiment outputs to identify those crew member tasks that require familiarization and associated familiarization equipment. The familiarization requirements analysis will be made along the guidelines detailed in paragraph 10.3. The analysis will form the basis of the familiarization plans and familiarization equipment specification.

b. Familiarization Plans. - Familiarization plans will be developed to cover equipment and familiarization requirements identified in the familiarization requirements analysis. Each will be developed along the guidelines detailed in paragraph 10.4. A program plan will be developed that will give visibility to the total familiarization requirements and will indicate areas for cross-training and unscheduled redundancies.

c. Implementation. - Some of the prime considerations during the implementation period are inter-Center schedule milestones, interface familiarization requirements, and mission requirements. MSFC will provide a technical coordinator to NASA Headquarters and MSC.

d. Management. - MSC will provide the necessary program coordination and control to assure that the familiarization program covered herein meets MSC program milestones and standards. Necessary management control through directives, instructions, and procedures will be provided. Techniques such as PERT, EDS, configuration management, etc., will be utilized for effective and economical management of the familiarization program.

10.3 FAMILIARIZATION REQUIREMENTS ANALYSIS

10.3.1 Purpose

The purpose of the familiarization requirements analysis is to identify specific familiarization requirements and

familiarization equipment for the S-IVB Workshop mission. This analysis will be a systematic review of the SSESM experiments and their related operations and maintenance tasks. A part of this operations and maintenance analysis has already been accomplished.

10.3.2 Flight Equipment Analysis

Flight equipment that requires crew familiarization for satisfactory operation will be identified and categorized in accordance with its mission criticality, complexity of operation, physical constraints imposed upon crew members, interface with other equipment, safety considerations, and contingencies. Expendable and recoverable equipment will be identified and their stowage procedures defined.

10.3.3 Task Analysis

Tasks required to perform each normal/emergency operational function will be defined. A comprehensive and systematic review of the flight equipment and task analyses will be conducted to determine total task familiarization and individual task familiarization requirements. Specific task procedures will be defined. Estimates of time, in minutes, required to perform each task will be made. These estimates will be revised at the end of the crew familiarization program to indicate a more realistic task time factor based upon simulated operation time. Each task will be identified to indicate its criticality to mission success, degradation of equipment, perceptual requirements, motor skill demands, judgmental requirements, and number of crew members required.

10.3.4 Familiarization Equipment and Facilities Analysis

Familiarization equipment and facilities analyses will be made to determine requirements and availability dates. Selection and provisioning of familiarization equipment will be made based on this analysis. Before fabrication, familiarization equipment specification will be prepared and approved for each familiarization equipment end item. Appropriate configuration control procedures will be implemented to maintain familiarization equipment end item compatibility with the operational program equipment.

10.3.5 Nature of Familiarization

The most economical and effective methods of teaching will be used. Familiarization aids, components, operational equipment, and simulators will be used for orientation and task-based familiarization. Orientation of mission requirements, subsystem capabilities and component functions is required to familiarize the crew members with tasks to be performed. Equipment built to actual operational system specifications and simulators will be used to develop exact unique skills and to meet specific familiarization objectives. Existing operational equipment and simulators will be fully utilized. Familiarization facilities, as determined by the facilities analysis, will be provided. Extensive renovation will not be accomplished unless it is considered critical to the familiarization program mission.

10.3.6 Familiarization Outline

A familiarization outline will be prepared from the familiarization requirements analysis data. The outline will define the courses, equipment, integrated resources, and services necessary for crew familiarization in each program phase as stated in paragraph 10.2. This outline will provide a basis for the familiarization plans, and the estimated time required to complete each course.

10.4 FAMILIARIZATION PLANS

10.4.1 Purpose

The familiarization plan will provide documented sources for identifying lesson plans, resources and controls to assure that familiarization requirements are met.

10.4.2 Course Description and Outline

A course description and outline will be prepared from the familiarization outline data for each program phase (see paragraph 10.2). It will contain the basic organization material and an itemized listing of each familiarization requirement, including the time element required for familiarization. The data will contain information such as security classification, course objective and

scope, course length in manhours, location of familiarization, familiarization methods to be used, required familiarization equipment, and contingencies. The course description and outline data will be used to develop lesson plans.

10.4.3 Lesson Plans

Lesson plans will be prepared for each program operation to define the familiarization accomplishments required for daily performance. In addition to operational and equipment procedures, the lesson plans will include contingencies, equipment relationships and interfaces, mission criticality, safety procedures, evaluation data, and conditions that would necessitate abort. Simultaneous crew participation at different work stations will be covered.

10.4.4 Schedules

Schedules will be developed from the course description and outline, the latest Apollo Program schedules, and MSC astronaut familiarization schedule. They will contain provisioning data relative to familiarization equipment, facilities, lesson plans, instructors, and crew members. This part of the familiarization plan will give visibility to the total crew familiarization program and will clearly portray major familiarization milestones, critical familiarization events, schedule slippage or compromise provisioning inadequacies and current status.

10.4.5 Familiarization Evaluation

A performance measurement system will be developed to assure an effective familiarization program and crew-system integration. MSC will evaluate the crew proficiency in relation to the familiarization course objectives. Approval of crew efficiency to successfully conduct mission operations will be the responsibility of MSC.

10.5 IMPLEMENTATION

The preparation for crew familiarization will consist of the following:

- a. A detailed preparation and presentation of data identified in the familiarization requirements analysis and familiarization plans.
- b. Design and fabrication of additional familiarization equipment defined in the familiarization requirements analysis.
- c. Utilization of equipment and facilities identified in the familiarization requirements analysis.
- d. An evaluation of knowledge and skills required to conduct crew familiarization.

To assure crew proficiency, crew familiarization will be conducted using the course description and outline, lesson plans, familiarization equipment and facilities identified/developed in the technical requirements analysis and familiarization plan developed phases.

NASA configuration management techniques will be used for familiarization equipment provisioning and control to assure that the equipment is current with flight hardware configuration and program schedules.

A monthly status report will be submitted. In addition to the information required by the reporting procedures, the report will contain any problem encountered and the solution, schedule slippages with justification and recommended corrective action, and current status.

Familiarization evaluation reports will be submitted by the instructor at the completion of each lesson. This report will contain lesson number and title, name of instructor, names of crew members participating, actual time required for course completion, evaluation of crew proficiency, degree of familiarization equipment efficiency, recommendations to improve lesson plan, and recommendations concerning crew-system interfaces.

10.6 FAMILIARIZATION MANAGEMENT

The methods and procedures specified herein will provide assurance that the crew familiarization requirements for the S-IVB Spent Stage Experiment will be satisfied. It will assure that requirements are identified and satisfied in a manner and time frame permitting effective integration and control of this program with the MSC astronaut training program.

Major milestones, program elements, and functional flow paths are shown in Figure 10.6-1. Each function is shown within its program element and is defined within the program element text shown for that function. Each function will be further defined and maintained during the life of the program.

The documentation developed for each of the functions is shown in Figure 10.6-2. The documentation used will be structured to permit common use in establishing the familiarization baselines and in performing program requirements. Documentation will be revised throughout the program to maintain familiarization and equipment current with program configuration and schedules.

FIGURE 10.6-1 FAMILIARIZATION PLAN FLOW PATH

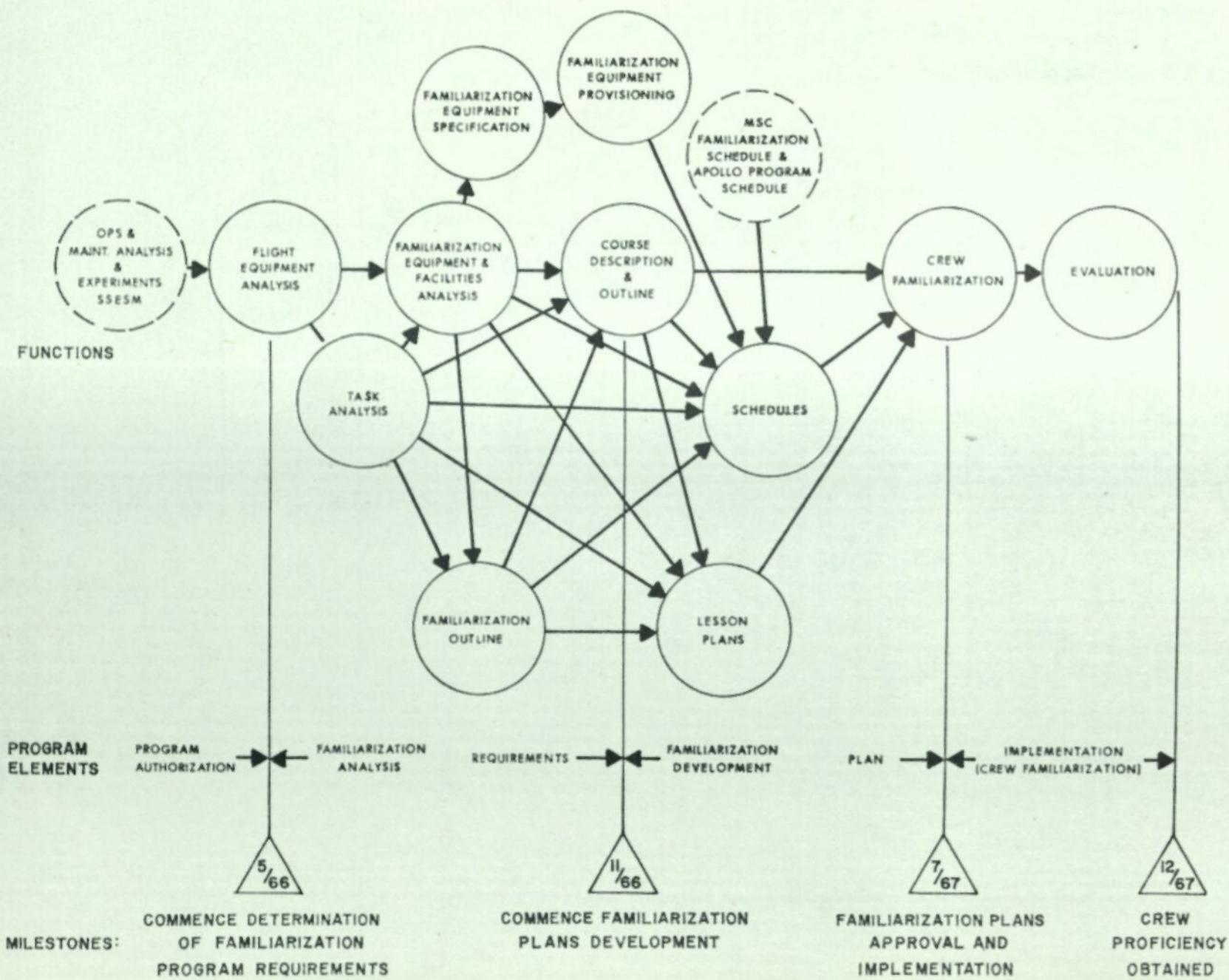


FIGURE 10.6-2 - FAMILIARIZATION FUNCTIONS AND RELATED DOCUMENTATION

10-10

